

Quantitative Visualization of Static and Dynamic Biological Complexes

Chandrajit Bajaj

<http://www.ices.utexas.edu/CCV>

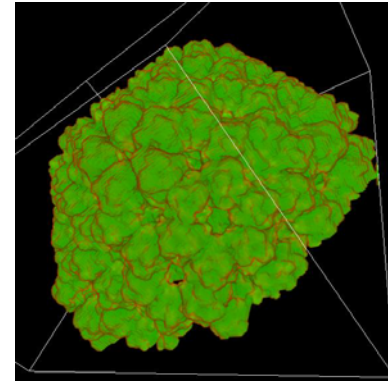
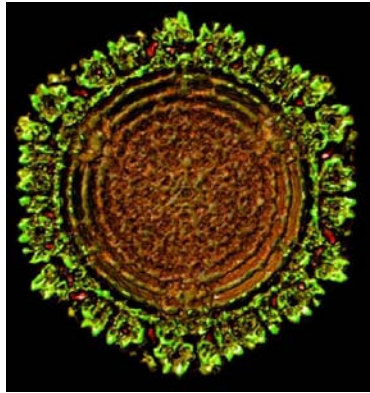
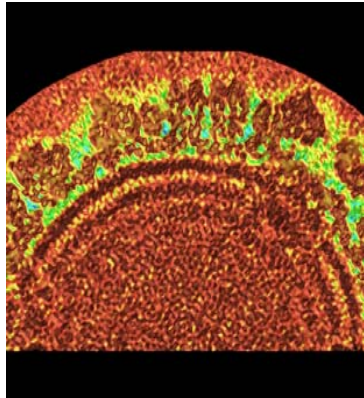
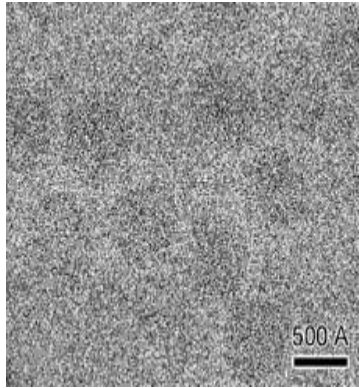


Outline

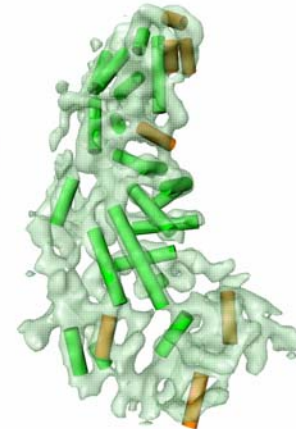
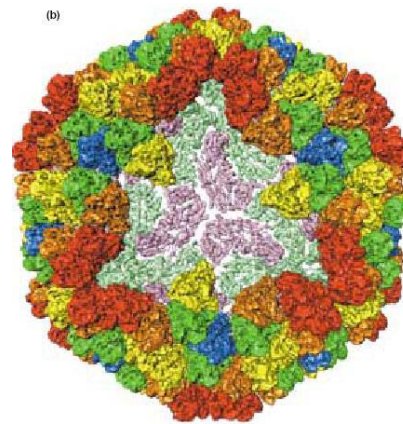
- Domains
 - Cryo-EM Maps
 - Tomographic
 - PDB structures (shape), Properties (electrostatics, hydrophobicity)
- Techniques
 - Image Processing (Scalar/Vector Filtering, Contrast Enhancement, Skeletonization, InPainting)
 - Finite Element Meshing (Linear, Higher-Order)
 - Analysis (Area, Volumes, Combinatorics, Topological)
 - Compression (Hierarchical, Progressive)
 - Visualization (Surface+Volume Rendering, Texture Rendering)



Imaging to Structure to Modeling to visualization



Cryo-EM → Anisotropic and
Vector Diffusion
Filtering → Structure
Segmentation → Sub-
Atomic Modeling →
Functional Analysis
→ Visualization



(Collaborators: Wah Chiu, NCMI, Baylor
College of Medicine, A. Sali, UCSF)



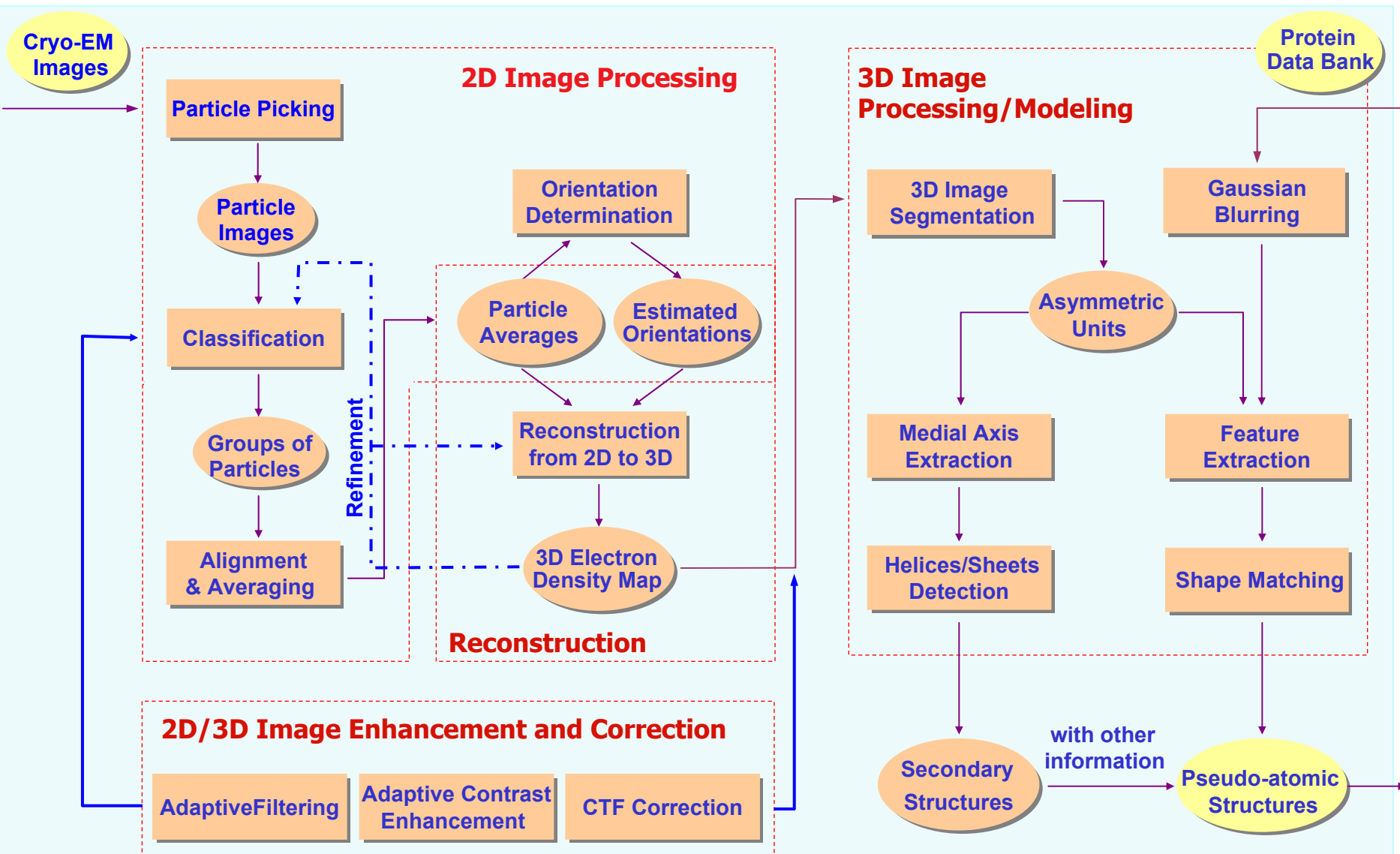
Center for Computational Visualization
Institute of Computational and Engineering Sciences
Department of Computer Sciences

****Sponsored by NSF-ITR**

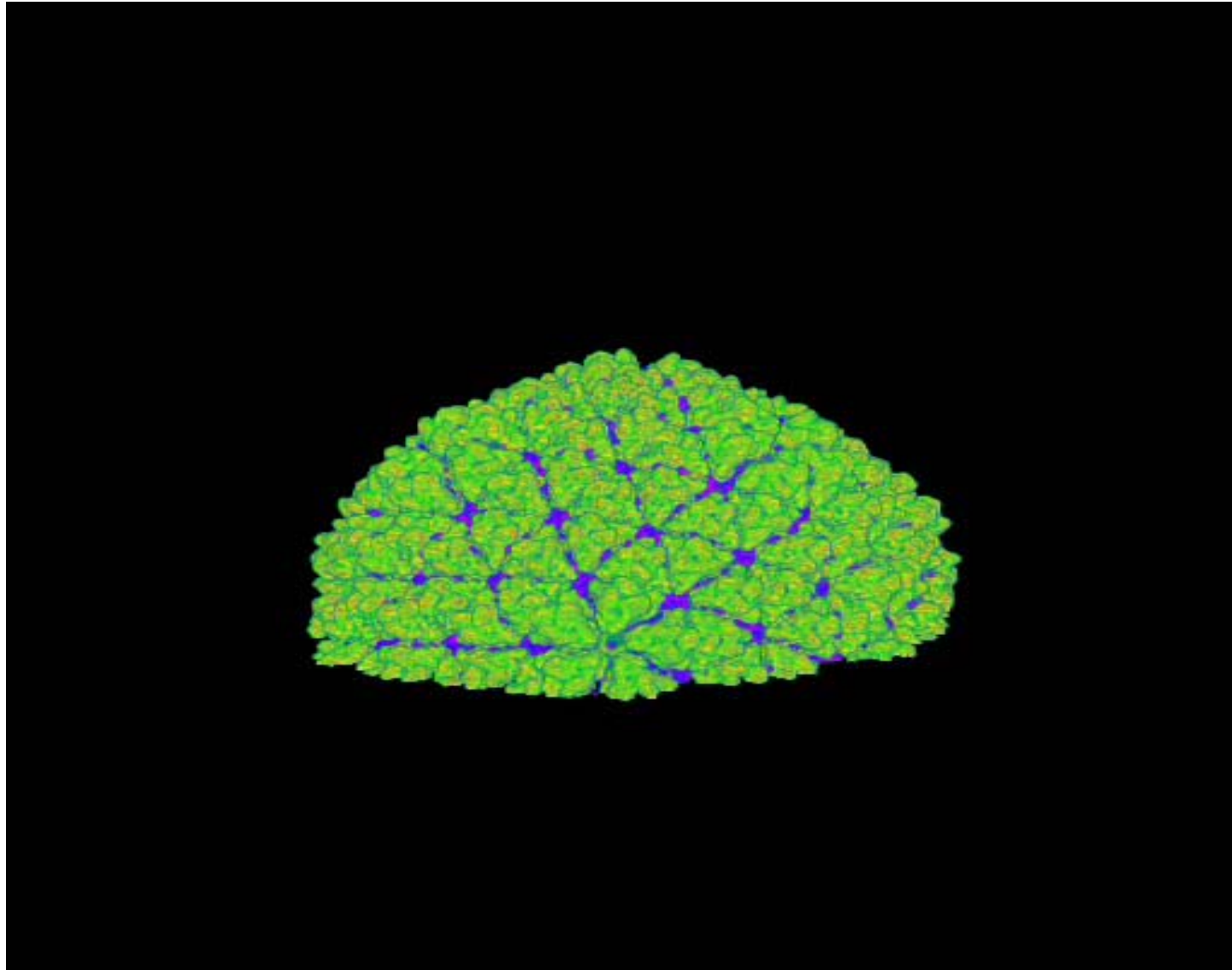
University of Texas at Austin

Oct 2003

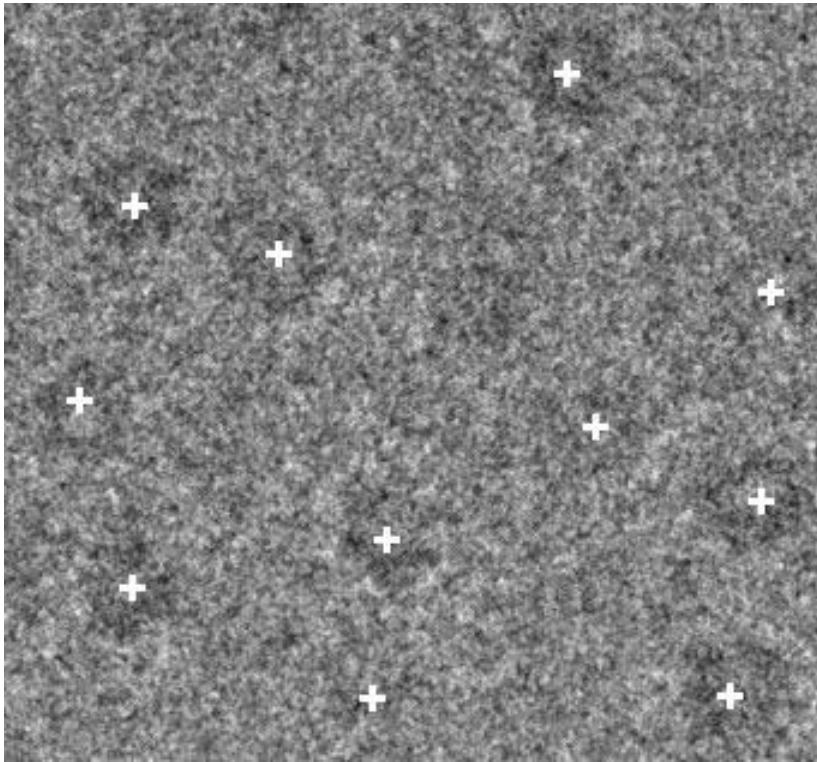
Computational Pipeline



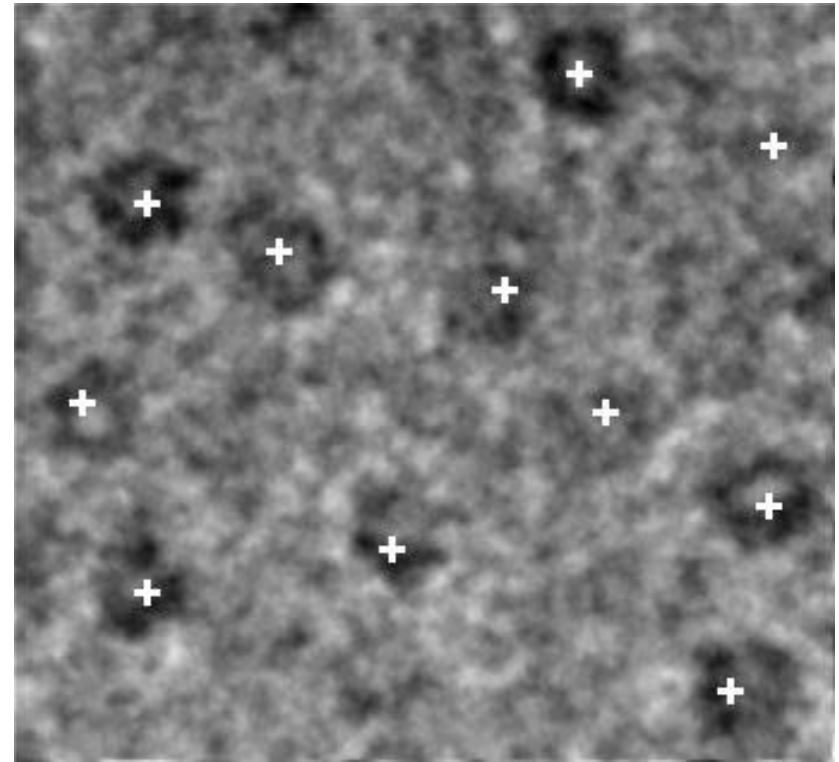
Rice Dwarf Virus



Would Image Filtering Help Structure Determination ?



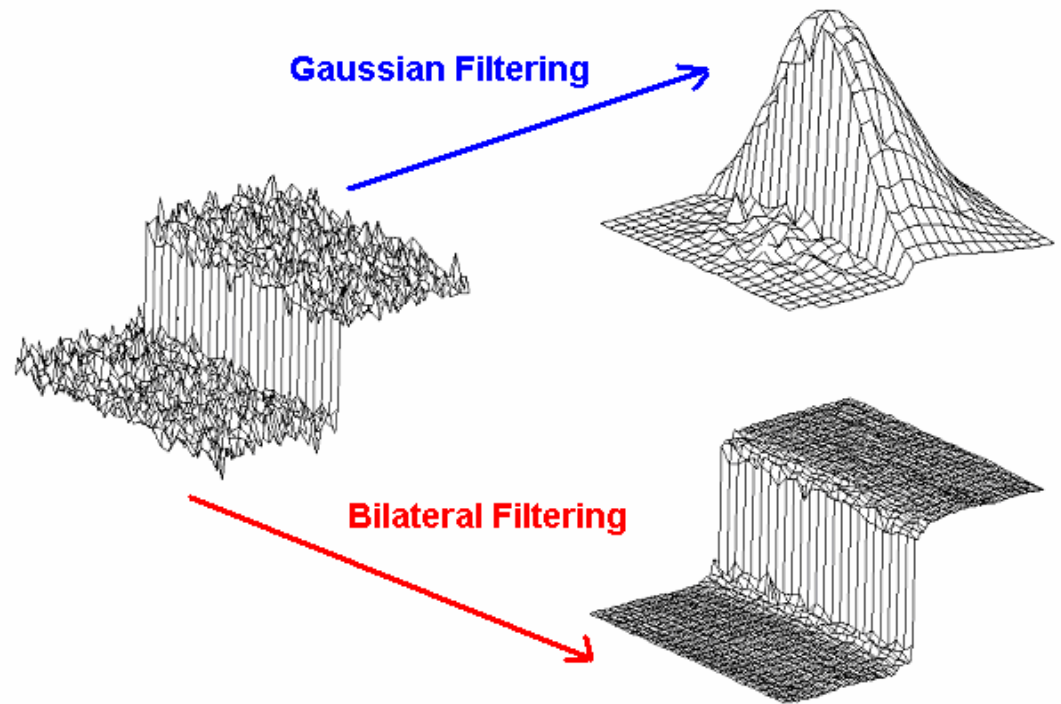
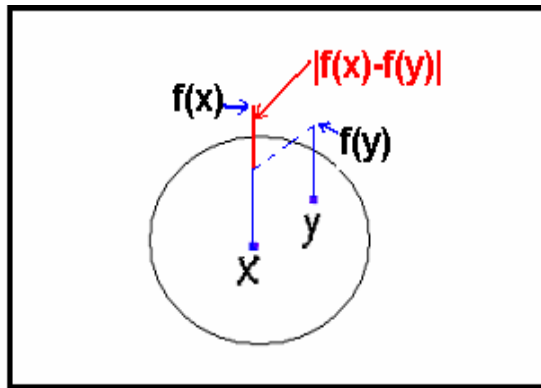
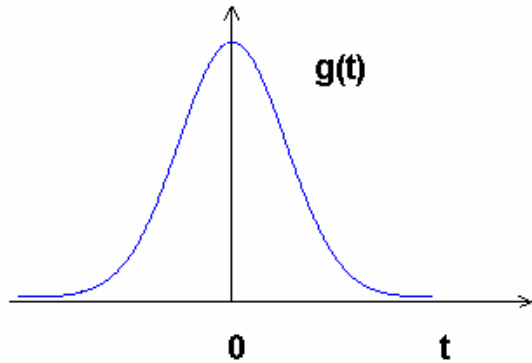
Original image



After anisotropic diffusion



Image Filtering: Gaussian vs Bilateral

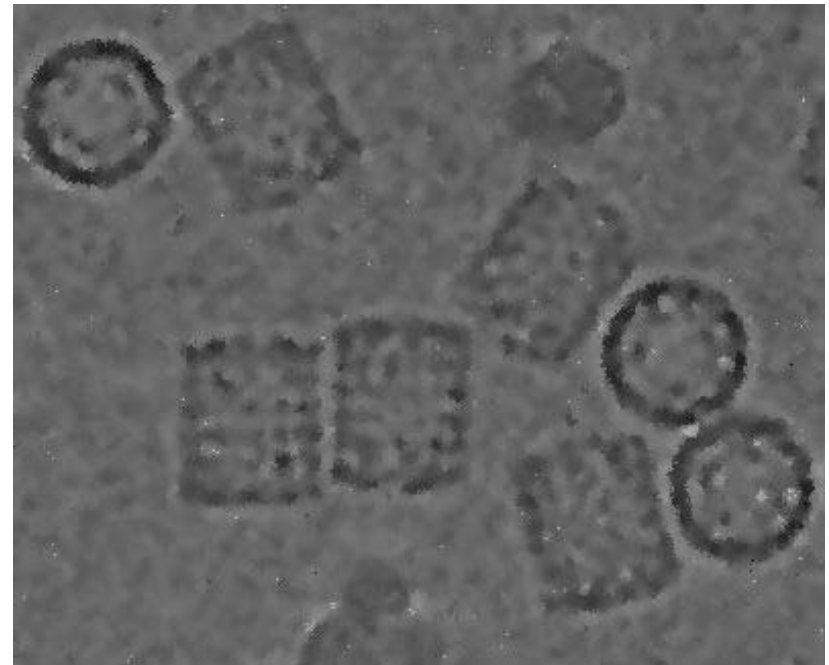
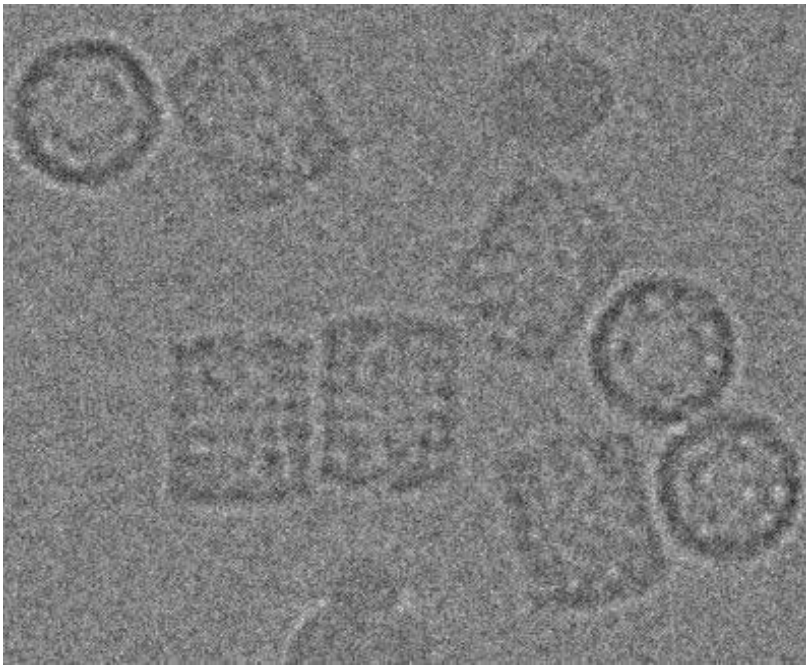


Bilateral Filtering

- Weighting Function

$$h(x, \xi) = e^{-\frac{(x-\xi)^2}{2\sigma_d^2}} \cdot e^{-\frac{(f(x)-f(\xi))^2}{2\sigma_r^2}}$$

where σ_d and σ_r are parameters and $f(\cdot)$ is the image intensity value.

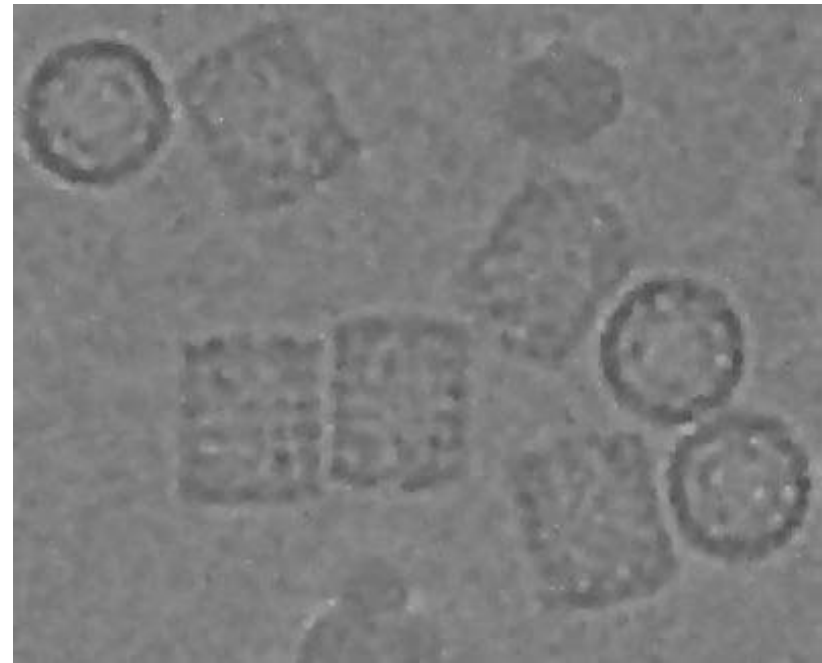
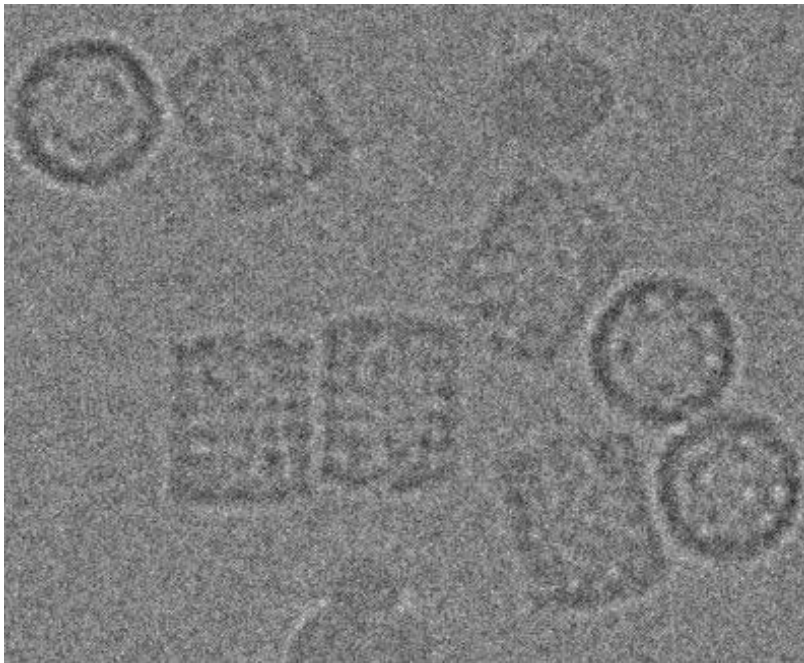


Non-Linear Filtering (using PDEs)

- Diffusion Equation == Weighted Gaussian

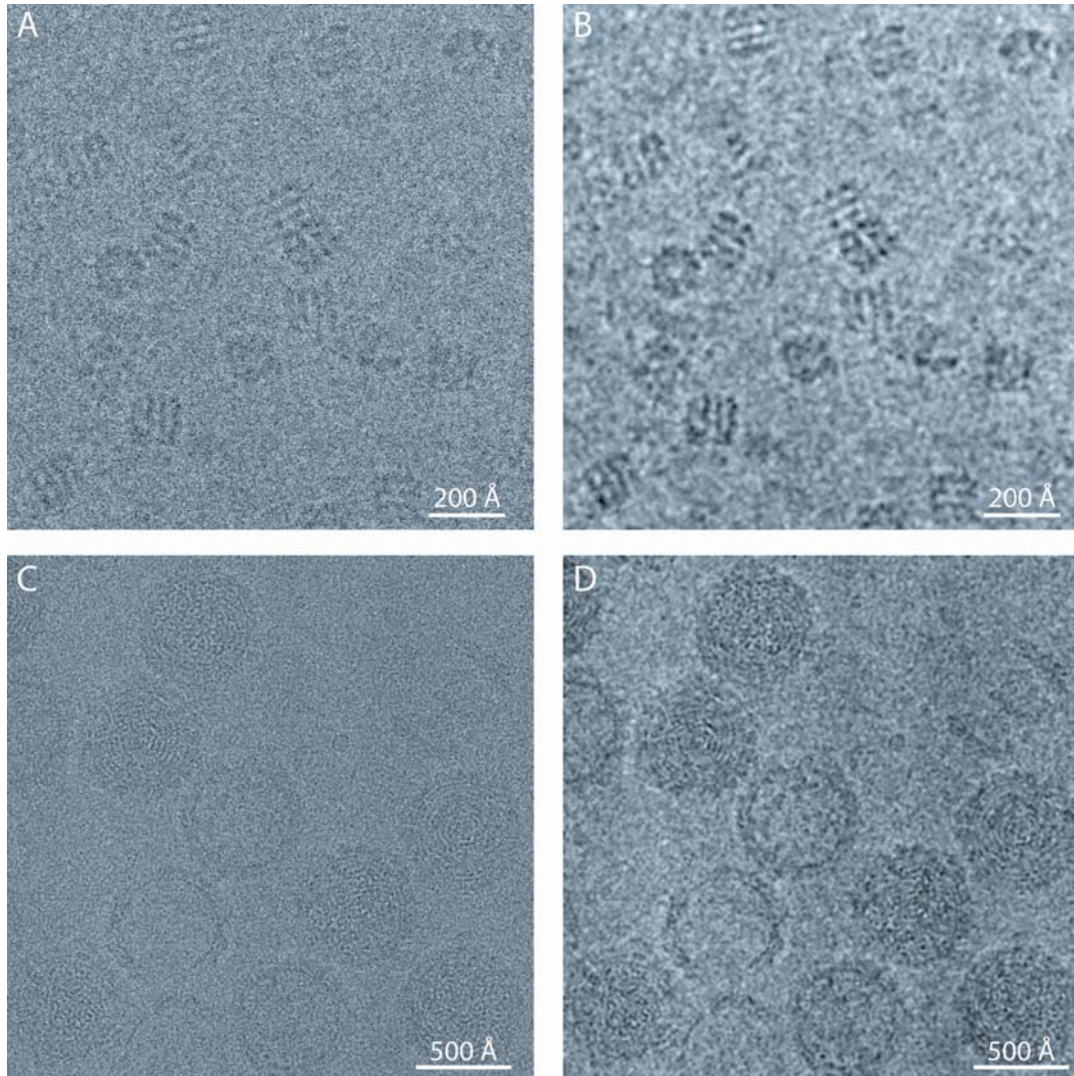
$$\partial_t \phi - \operatorname{div}(g(|\nabla \phi|) \nabla \phi) = 0$$

where $g(\cdot)$ is a decreasing scalar function, e.g., $g(|\nabla \phi|) = \frac{1}{1 + |\nabla \phi|^2 / \lambda^2}$

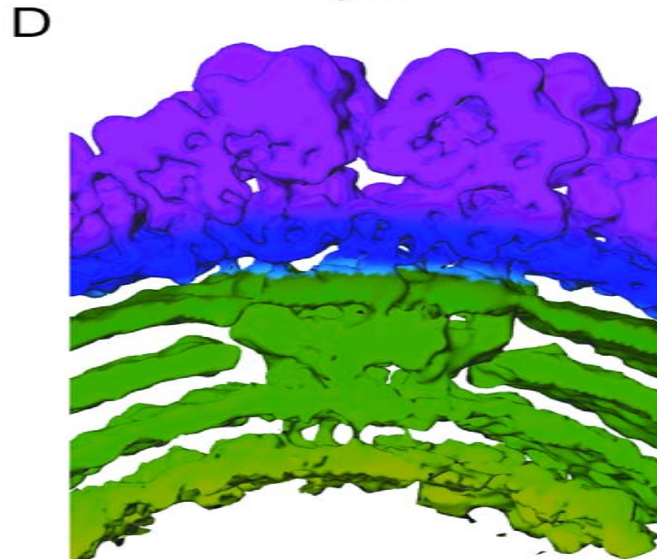
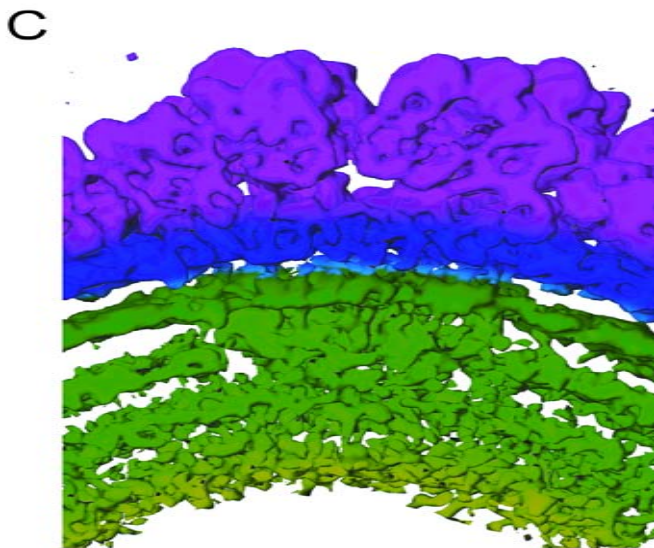
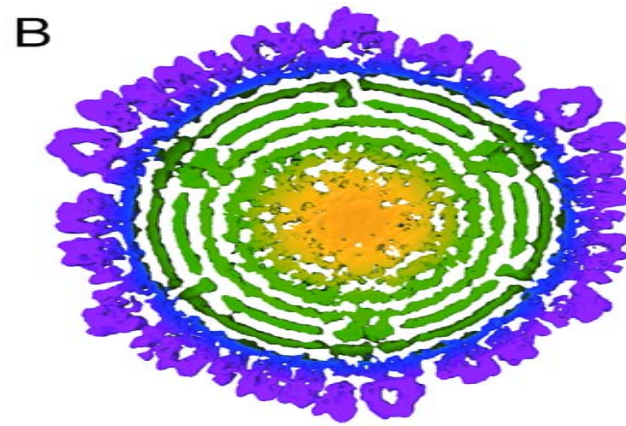
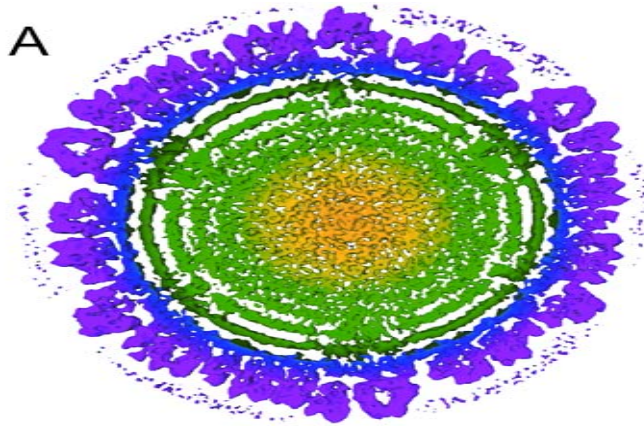


Bilateral Filtering

(Wen Jiang et al., JSB, 2003)



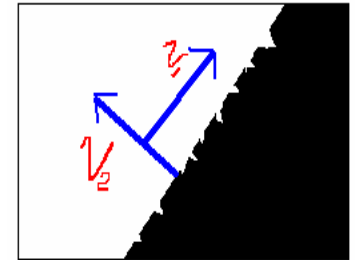
Bilateral Filtering on RDV Map



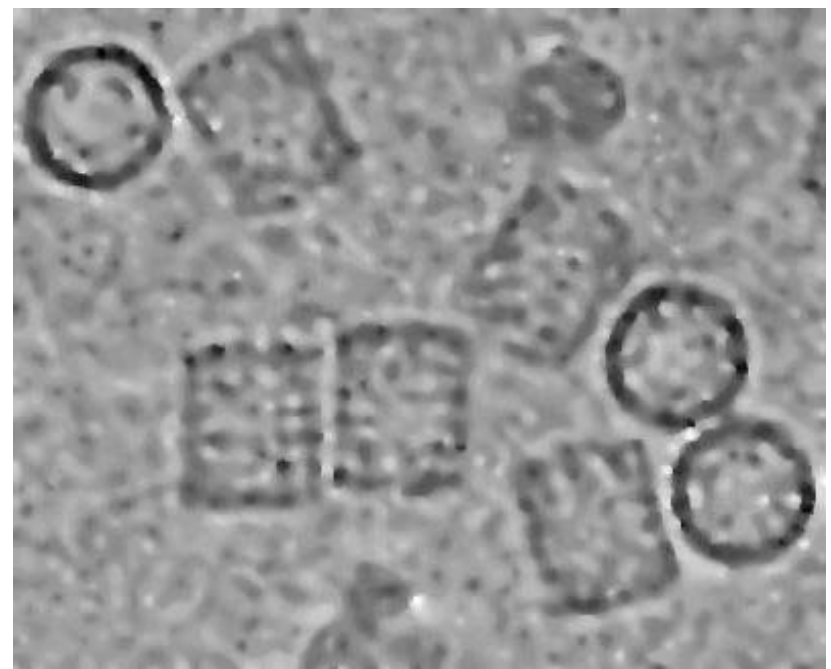
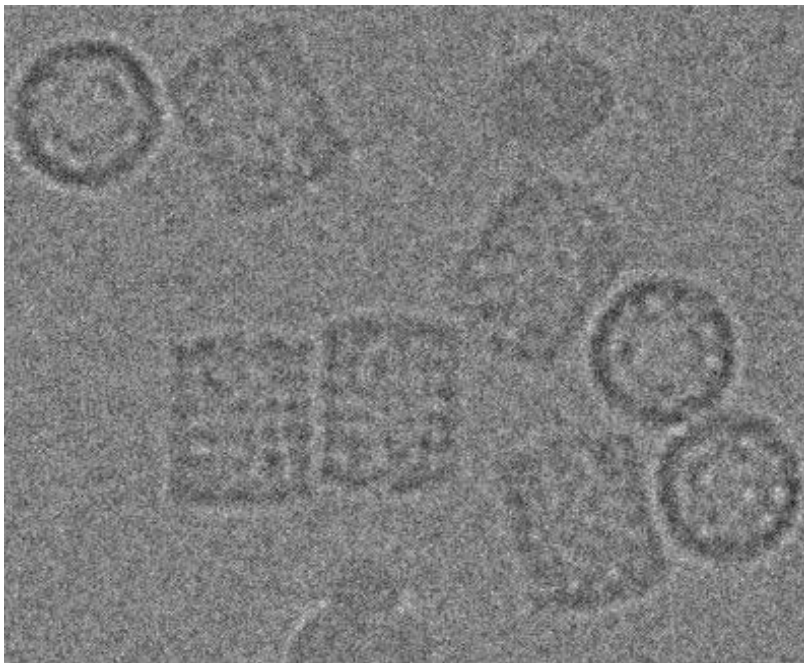
Anisotropic Diffusion (AD) Filtering

- Diffusion Equation

$$\partial_t \phi - \operatorname{div}(a(|\nabla \phi|) \nabla \phi) = 0$$



where **a** stands for the diffusion tensor determined by local curvatures.



Finite Element Method for Anisotropic Diffusion (Bajaj, Xu 2002, TOG)

Model

$$\partial_t x(t) - \operatorname{div}(a(x) \nabla_{M(t)} x(t)) = 0$$

$a(x)$ is symmetric, positive definite matrix

Variational form

$$(\partial_t x(t), \theta)_{M(t)} + (\nabla_{M(t)} x(t), \nabla_{M(t)} \theta)_{TM(t)} = 0,$$

$$\forall \theta \in C^\infty(M(t)) \quad \text{where}$$

$$(f, g)_M = \int_M fg dx, \quad (\phi, \psi)_{TM} = \int_M \phi^T \psi dx$$

- How to represent $M(t)$?
- How to choose θ ?



solution of the linear system

$$(M^n + \tau L^n)C((n + 1)\tau) = M^n C(n\tau)$$

$$M^n = \left((\phi_i, \phi_j)_{M(n\tau)} \right)_{i,j=1}^m \quad C(t) = [c_1(t), \dots, c_m(t)]$$

$$L^n = \left((\nabla_{M(n\tau)} \phi_i, \nabla_{M(n\tau)} \phi_j)_{TM(n\tau)} \right)_{i,j=1}^m$$

- M^n and L^n are sparse.
- M^n is symmetric and positive definite.
- L^n is symmetric and nonnegative definite.
- $M^n + \tau L^n$ is symmetric and positive definite.

The system is solved by a conjugate gradient method.



Choice of Anisotropic Diffusion Tensor

Let $v^{(1)}(x), v^{(2)}(x)$, be the principal curvature directions of $M(t)$
at point $x(t)$ Let $N(x)$ be the normal at that point.

Then any vector $z = \alpha v^{(1)}(x) + \beta v^{(2)}(x) + \delta N(x)$

And define a , such that

$$az = g(k_1)\alpha v^{(1)}(x) + g(k_2)\beta v^{(2)}(x) + \delta N(x)$$

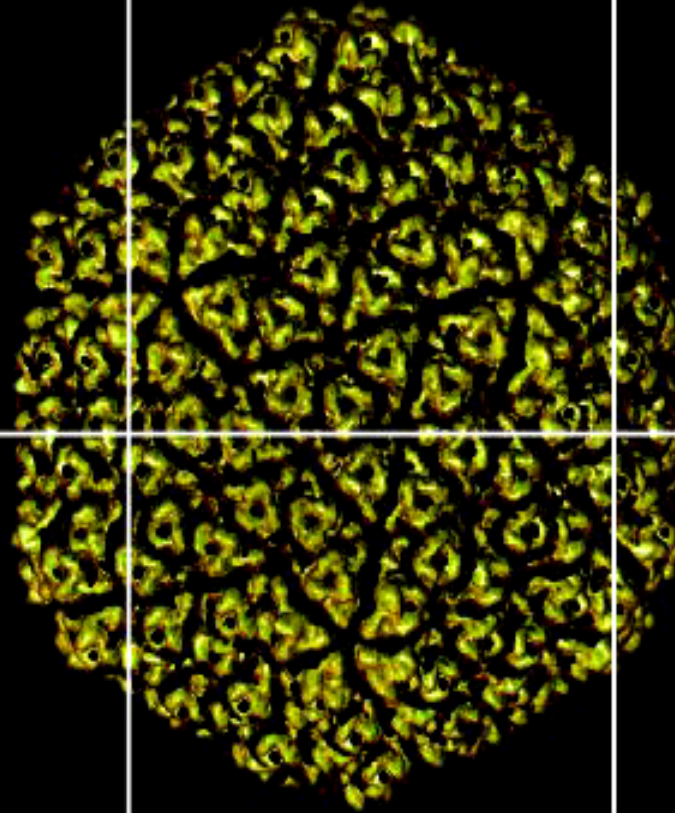
where

$$g(s) = \begin{cases} 1, & s \leq \lambda \\ 2(1 + \frac{s^2}{\lambda^2})^{-1}, & s > \lambda \end{cases}$$

$\lambda > 0$ is a given constant.



Rice Dwarf Virus



Anisotropic Gradient Vector Diffusion

Isotropic Diffusion (Xu *et al.*, 1998)

$$\begin{cases} \frac{\partial u}{\partial t} = \mu \nabla^2 u - (u - f_x)(f_x^2 + f_y^2) \\ \frac{\partial v}{\partial t} = \mu \nabla^2 v - (v - f_y)(f_x^2 + f_y^2) \end{cases}$$

Where:

$(u(t), v(t))$ stands for the evolving vector field;

μ is a constant;

f is the original image to be diffused;

$(f_x, f_y) = (u(0), v(0))$.

Anisotropic Diffusion (Yu & Bajaj ICPR'02)

$$\begin{cases} \frac{\partial u}{\partial t} = \mu \nabla (g(\alpha) \cdot \nabla u) - (u - f_x)(f_x^2 + f_y^2) \\ \frac{\partial v}{\partial t} = \mu \nabla (g(\alpha) \cdot \nabla v) - (v - f_y)(f_x^2 + f_y^2) \end{cases}$$

Where

$(u(t), v(t))$ stands for vector field;

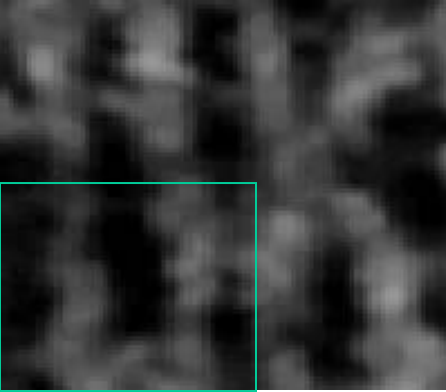
μ is a constant; $(f_x, f_y) = (u(0), v(0))$.

f is the original image to be diffused;

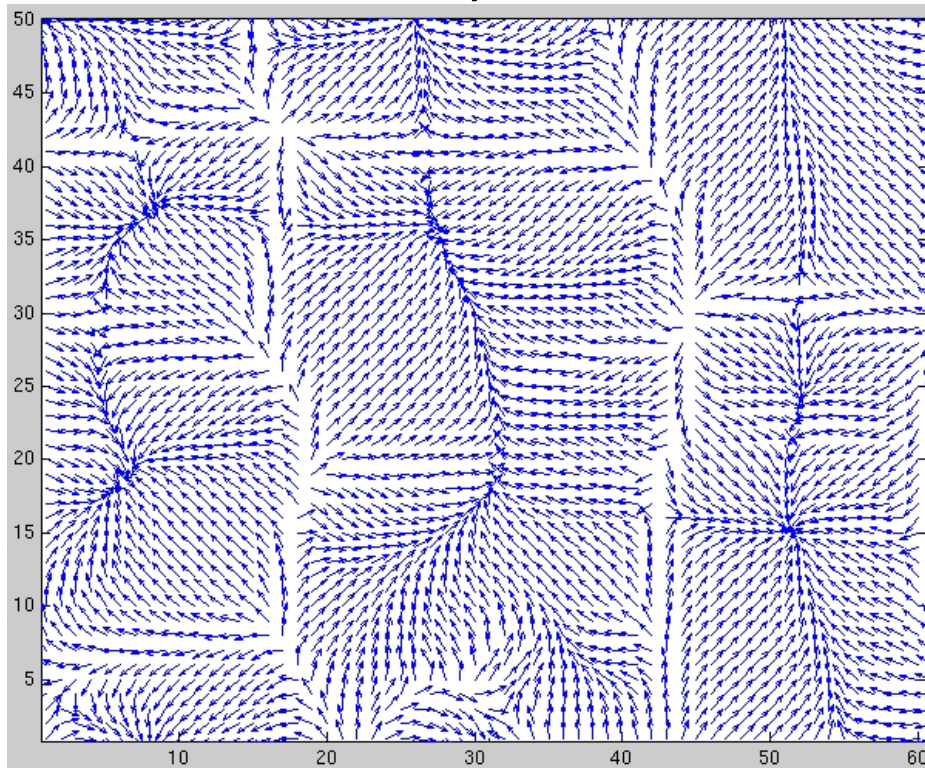
$g(\cdot)$ is the angle between two vectors



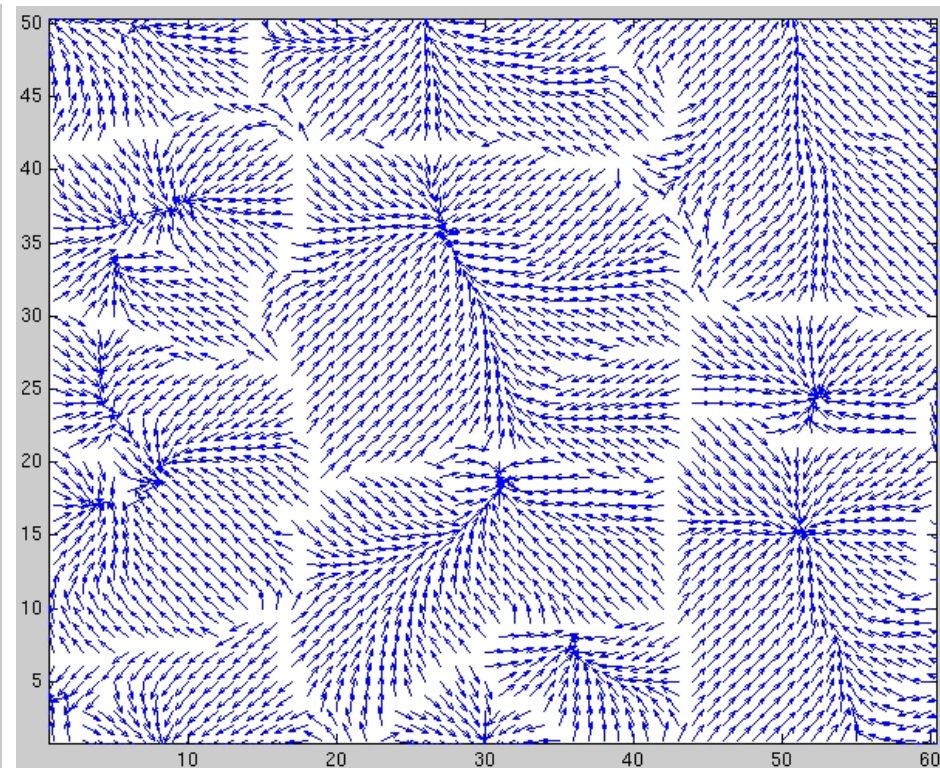
GVD v.s. AGVD



Isotropic diffusion



Anisotropic diffusion

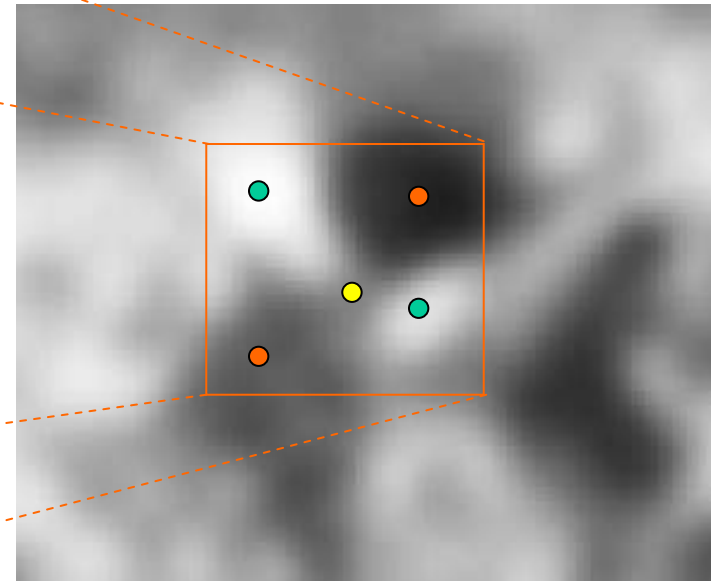
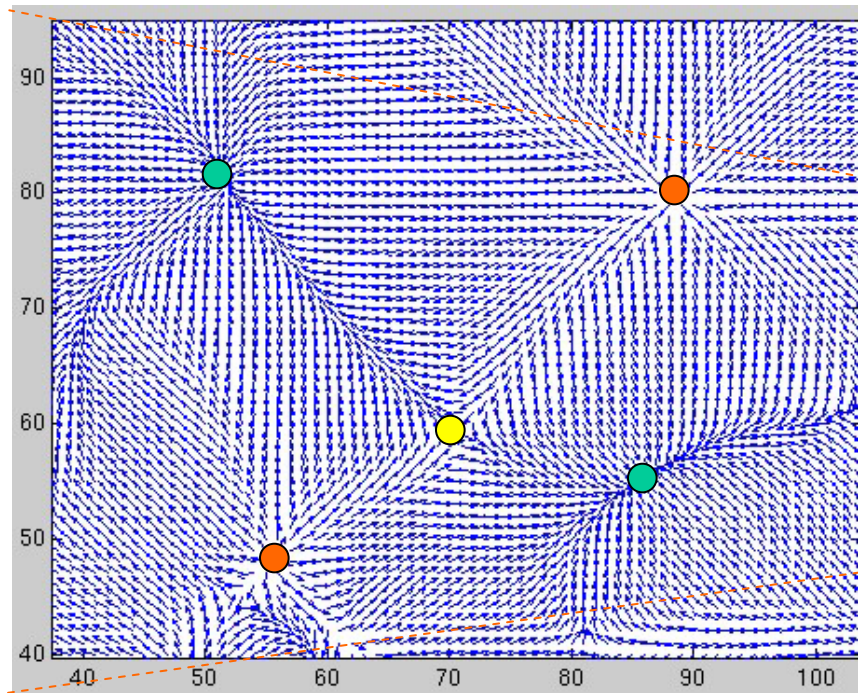


How AGVD Helps Image Segmentation ?

- Fast Marching Method
 - Initial seed points
 - Stopping criterion
- Use AGVD to locate seed points
 - Compute min/max critical points
(discard saddle critical points)
 - All such critical points are used as seeds
 - Advantages: automatic, close to centers of homogenous regions, robust to noise due to vector diffusion.



Compute Critical Points Using AGVD



● : minimum

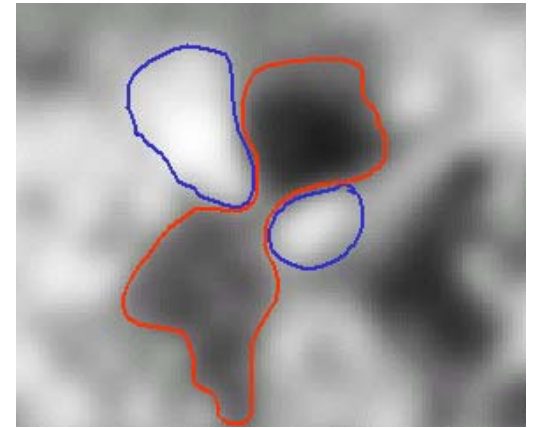
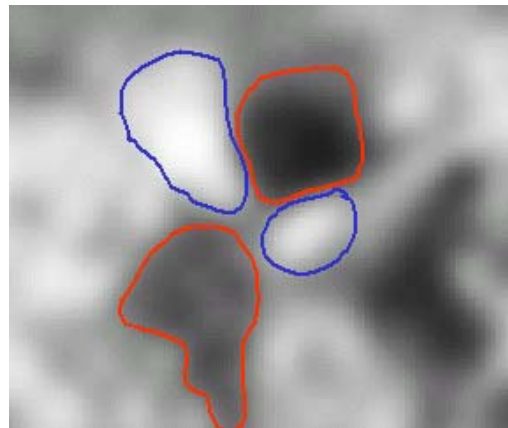
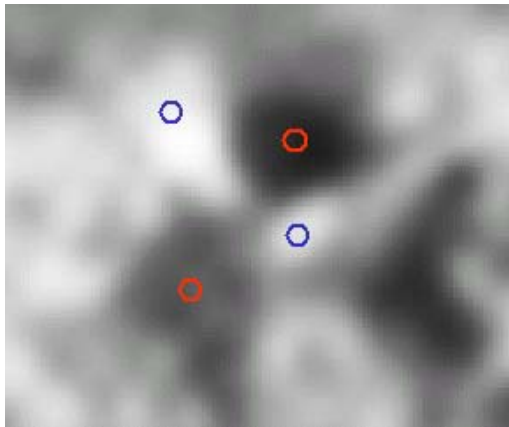
● : maximum

● : saddle

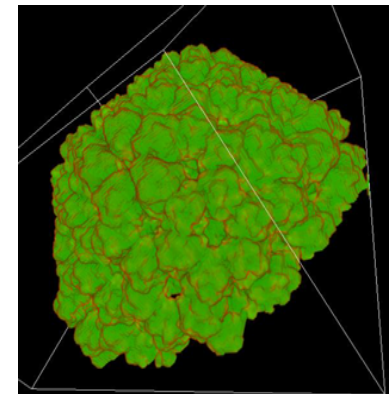
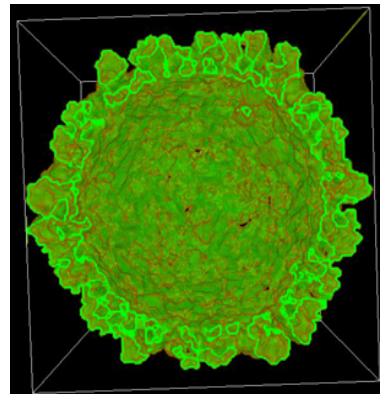
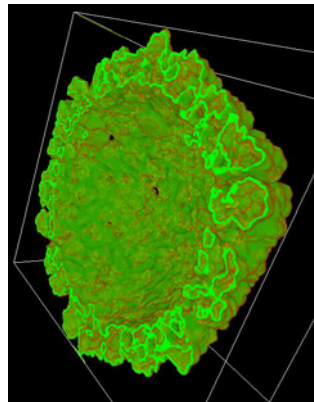
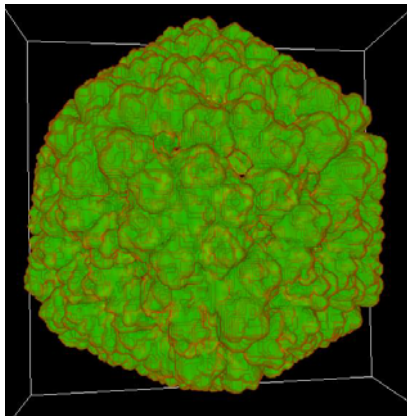
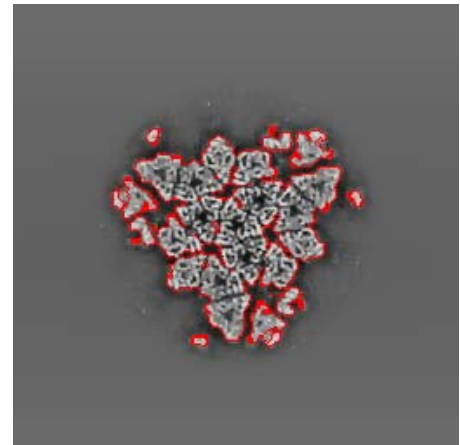
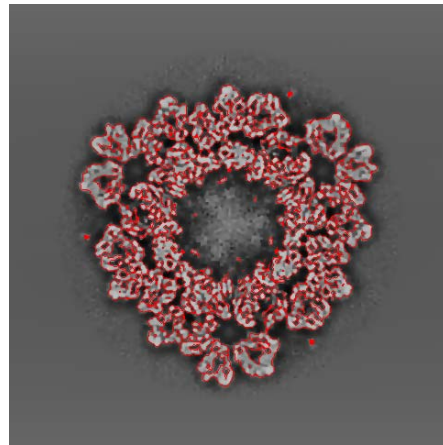
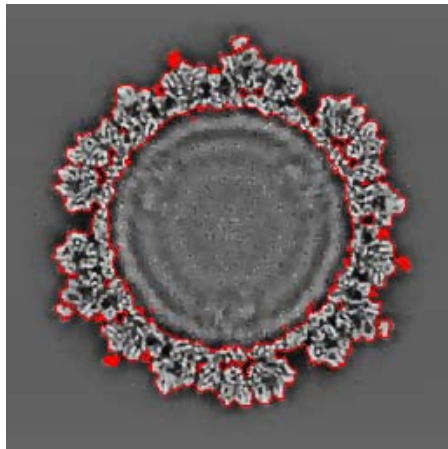


Stopping Criteria Using Multiple-Contour

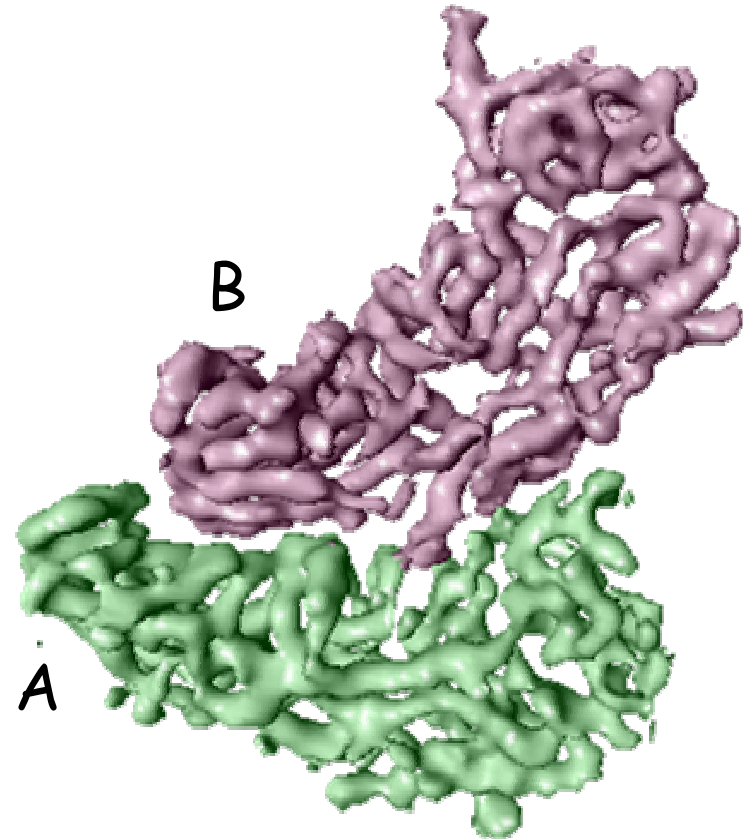
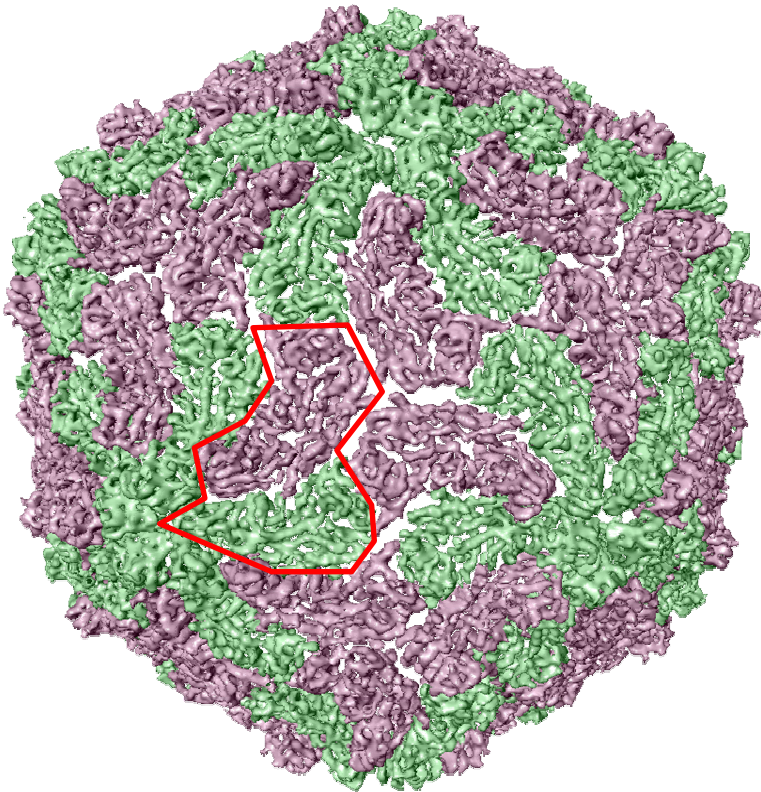
- Multiple-Contour
 - Group the critical points (for example, two groups as follows:
max. critical points \rightarrow feature & min. critical points \rightarrow background)
 - Each seed initializes one contour, coupled with its group's I.D.
 - Contours march simultaneously. Contours with same I.D. are merged while contours with different I.D. stop on their common boundaries



Boundary Segmentation after Filtering



Boundary Segmentation of Inner Shell



Inner shell (T=1)

540 Å in diameter

P3 (114kDa) 29% of total protein

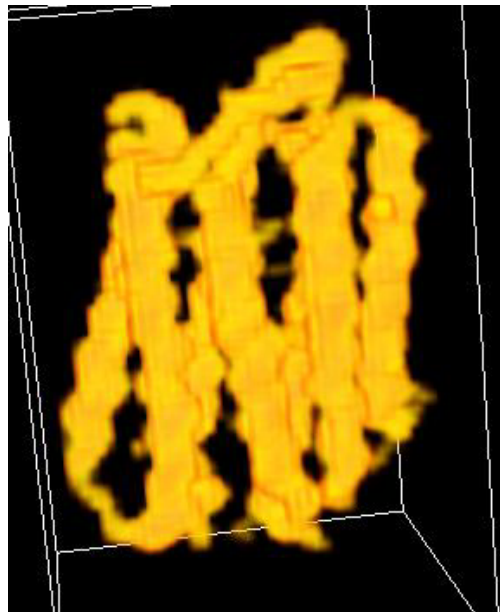
2 isoforms (A/B)

P3 dimer

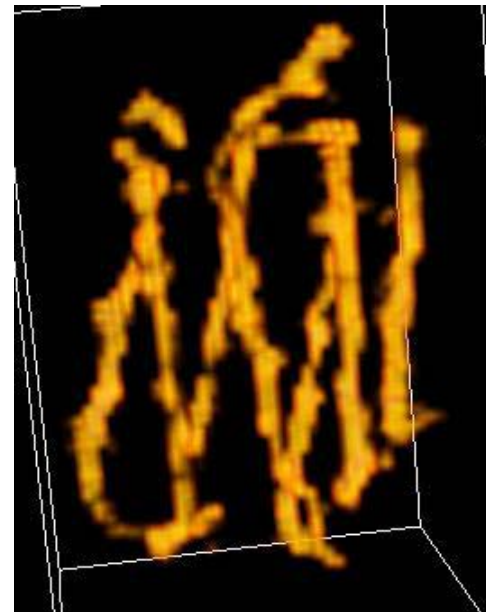


Volumetric Skeletonization/ InPainting

- Pre-Processing for Docking Structures (Match & Fit)




Original Filtered
Map



Skeleton Map

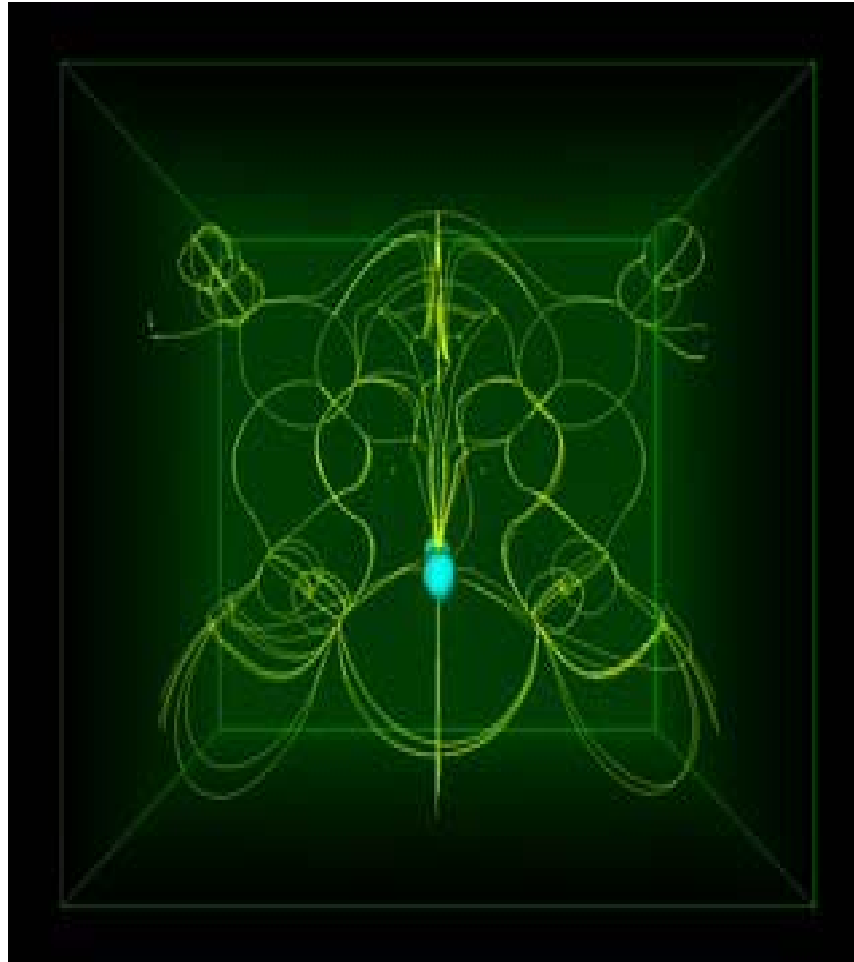


How GVD Helps Image Skeletonization ?

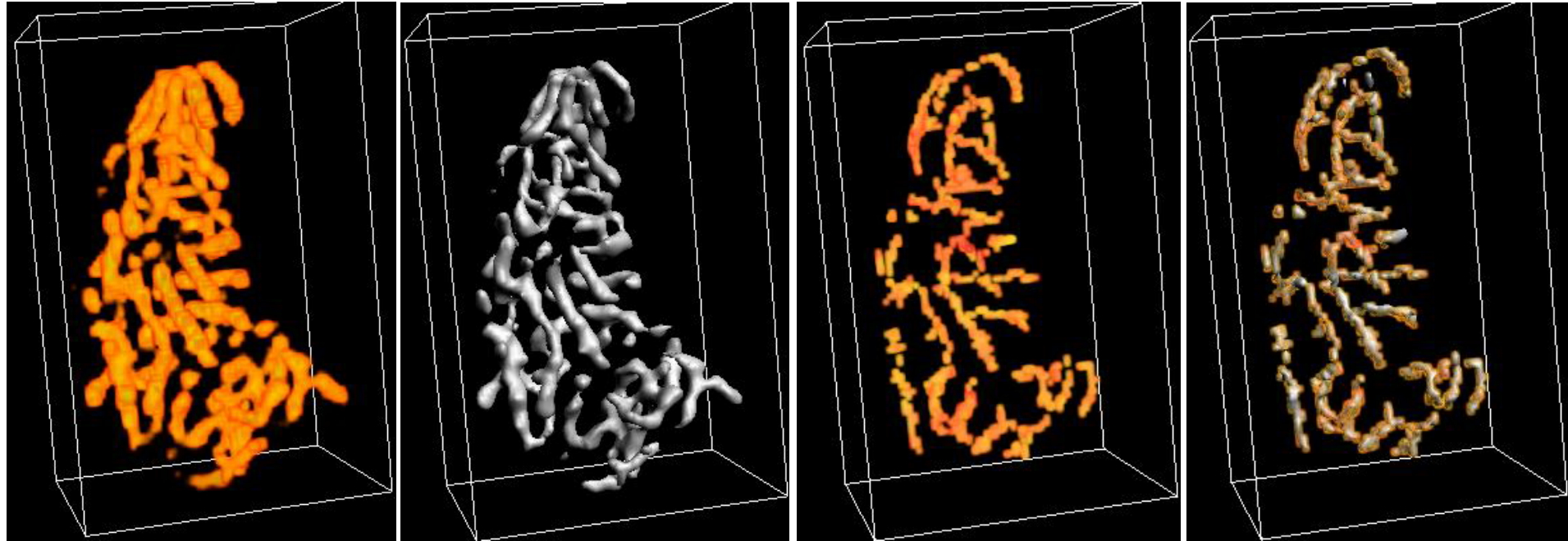
- Use GVD to locate critical points
 - Include minimum/maximum/saddle critical points
- Start from saddle points; trace integral lines along the diffused gradient vector field  Morse graph
- Prune the Morse graph for more meaningful skeletons
- Advantages:
 - Robust to noise due to vector diffusion.
 - Critical points are on the “skeletons” of features even for “flat” regions.



3D Morse Complex



RDV: P3 monomer



Volume-rendering

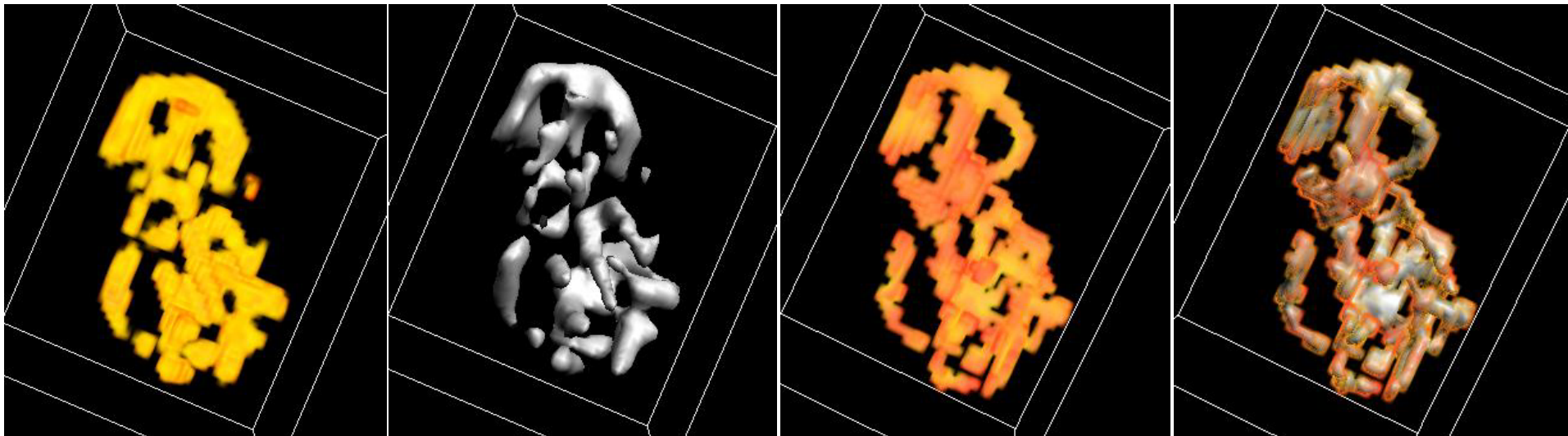
Isosurface

Skeleton

Skeleton with
InPainting



RDV: P8 monomer



Volume-rendering

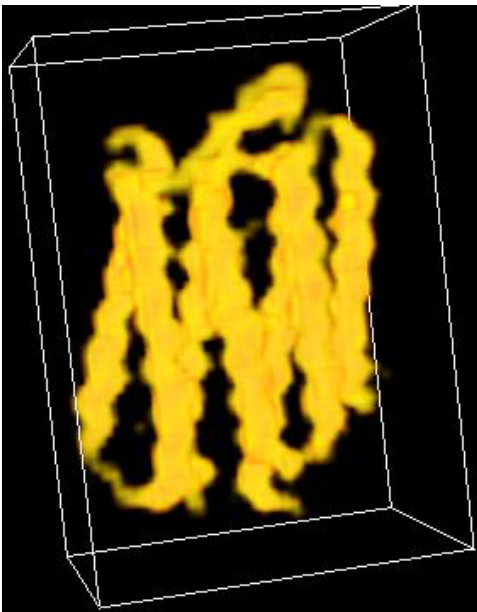
Isosurface

Skeleton

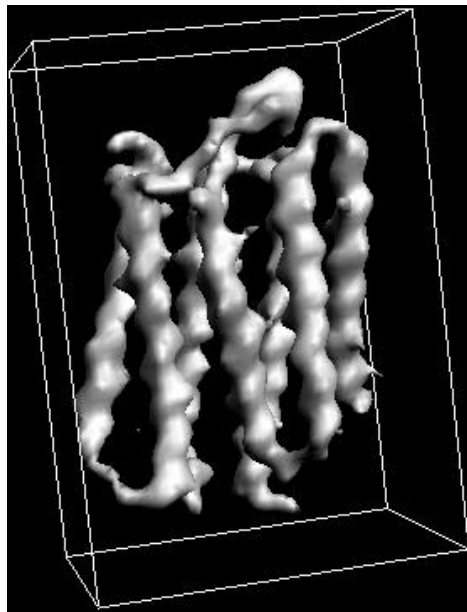
Skeleton with
another isosurface



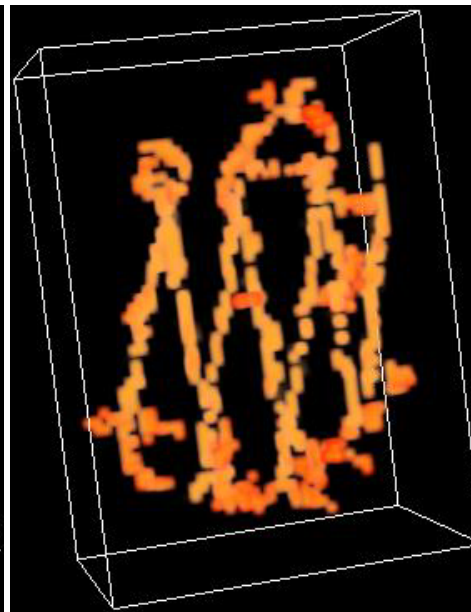
Bacteriorhodopsin/Lipid Complex (PDB: id=1c3w)



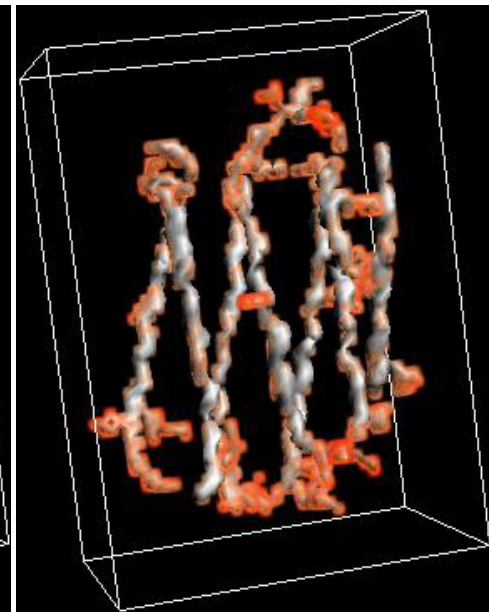
Volume-rendering



Isosurface



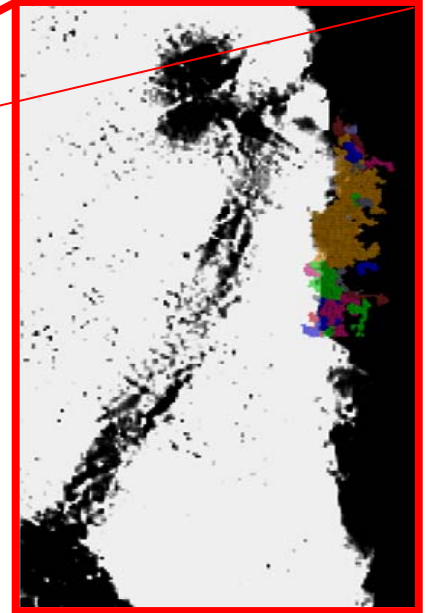
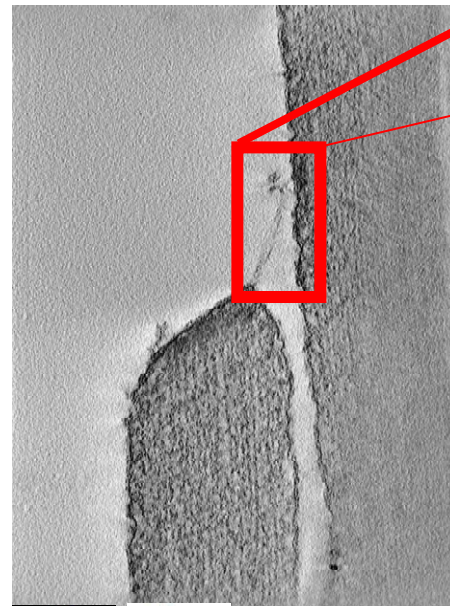
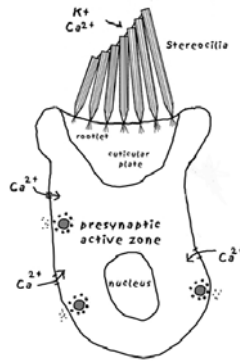
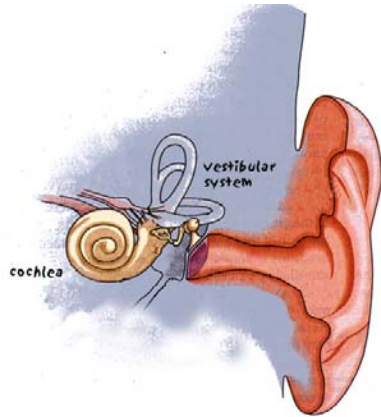
Skeleton



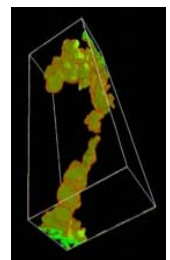
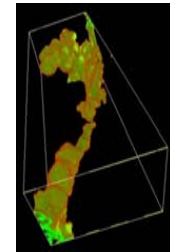
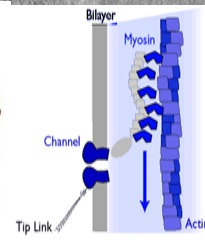
Skeleton with
InPainting



Tomographic Imaging to Structure to Analysis & visualization of Hearing Machinery



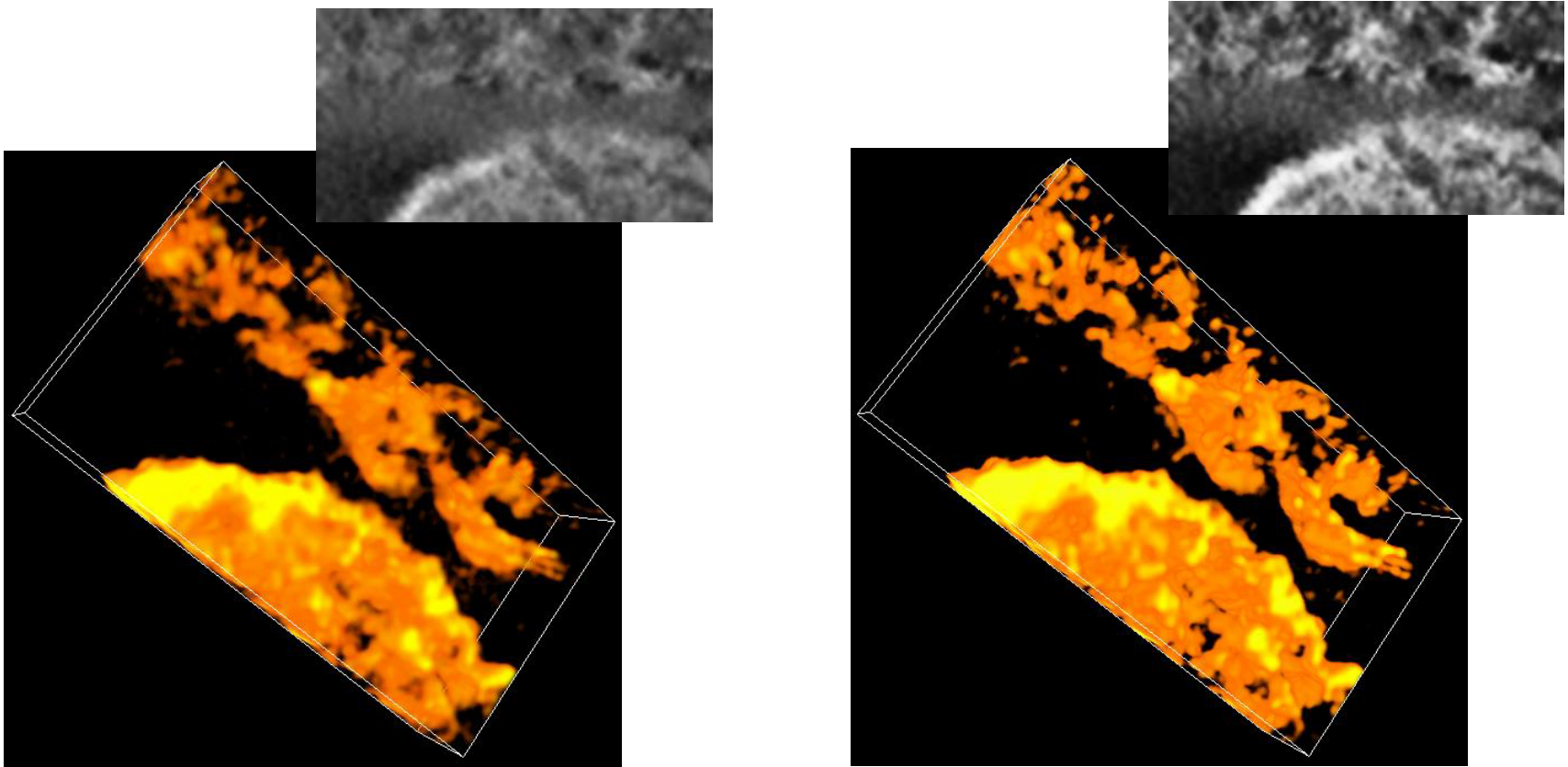
Tomographic Molecular Imaging → Anisotropic Diffusion Filtering → Classification, Segmentation, Skeletonization of 3D Density Maps → Quantitative Structure Analysis → Visualization



(Collaborator: Manfred Auer, Jim Hudspeth Rockefeller University and NYU Medical Sciences)



Image Contrast Enhancement (contd.)

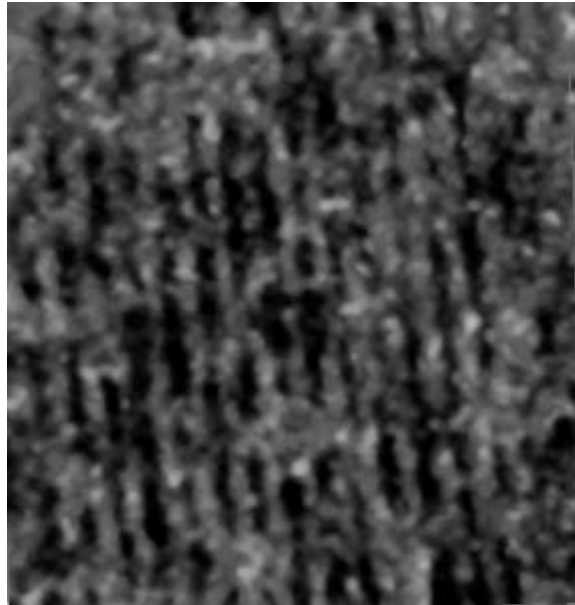


Tip structure of B280a (Left: original Right: enhanced)

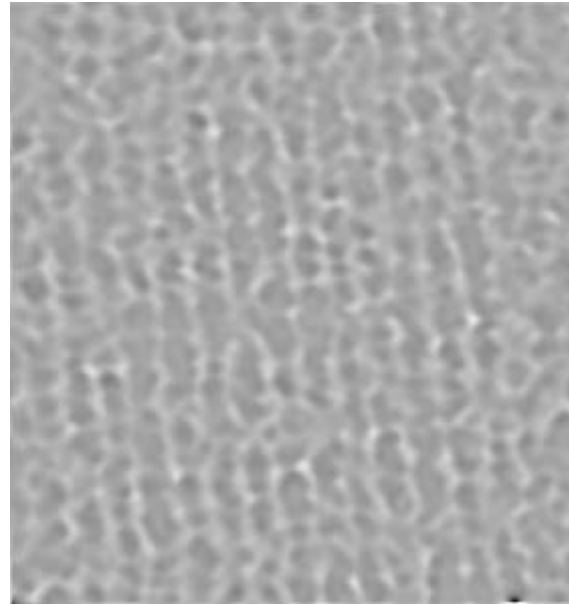


Skeletons of ActinBundle (B280a)

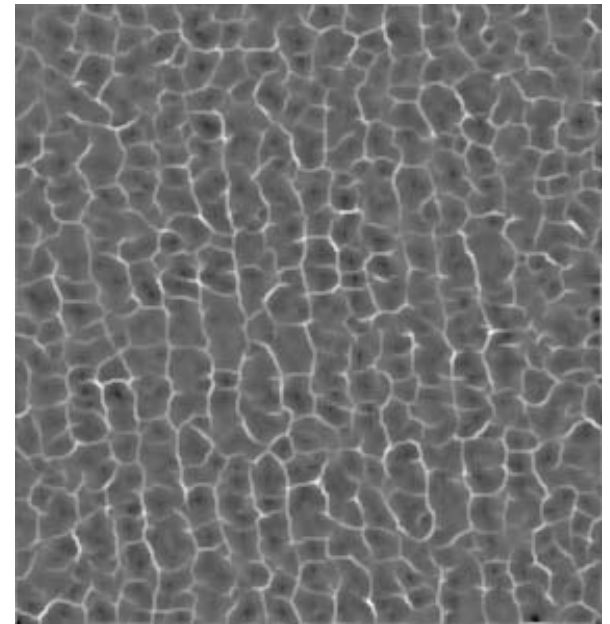
- 2D Electron tomogram



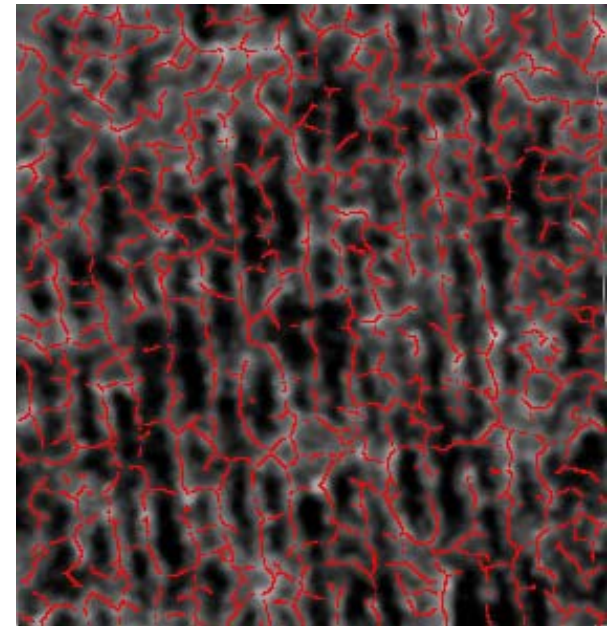
Original image



SMM (isotropic)



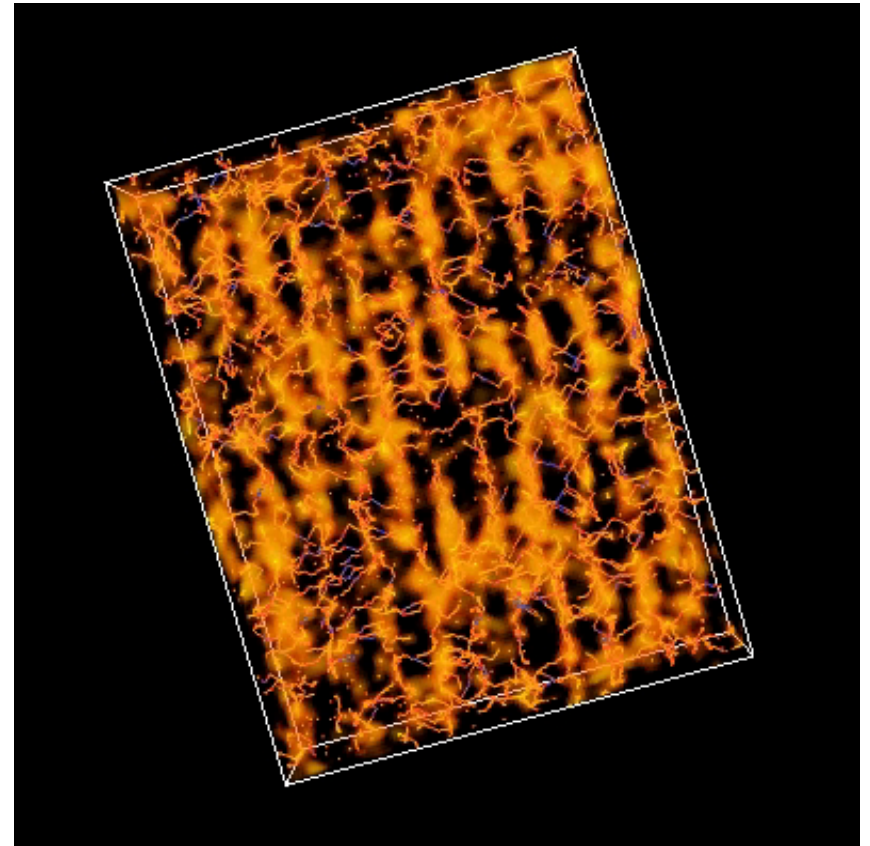
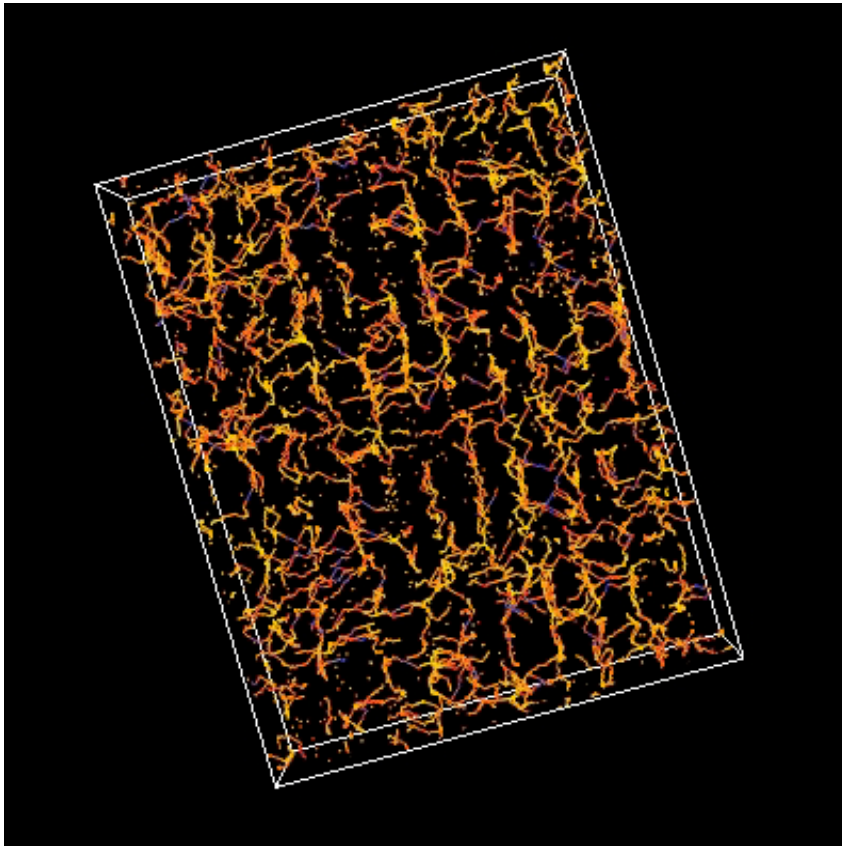
SMM (anisotropic)



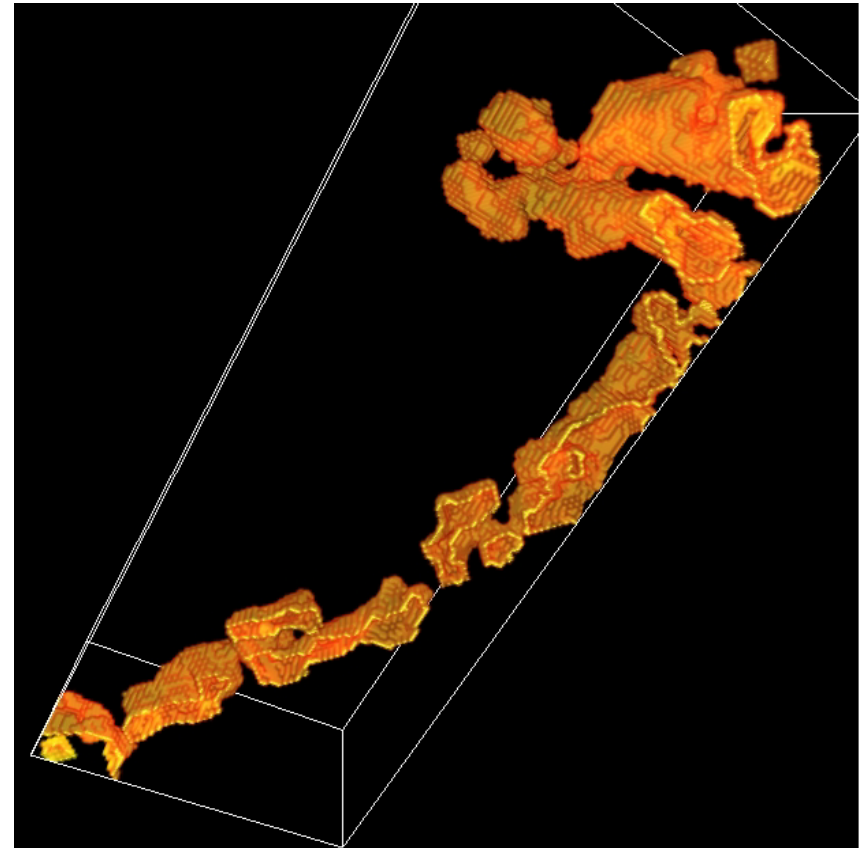
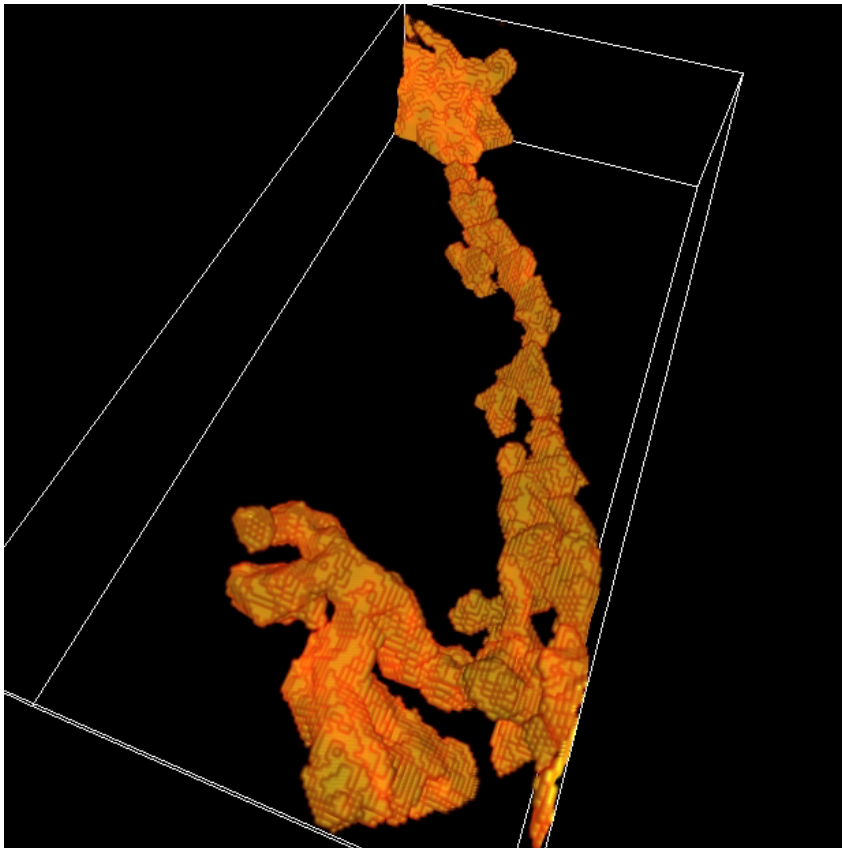
Skeletons >>



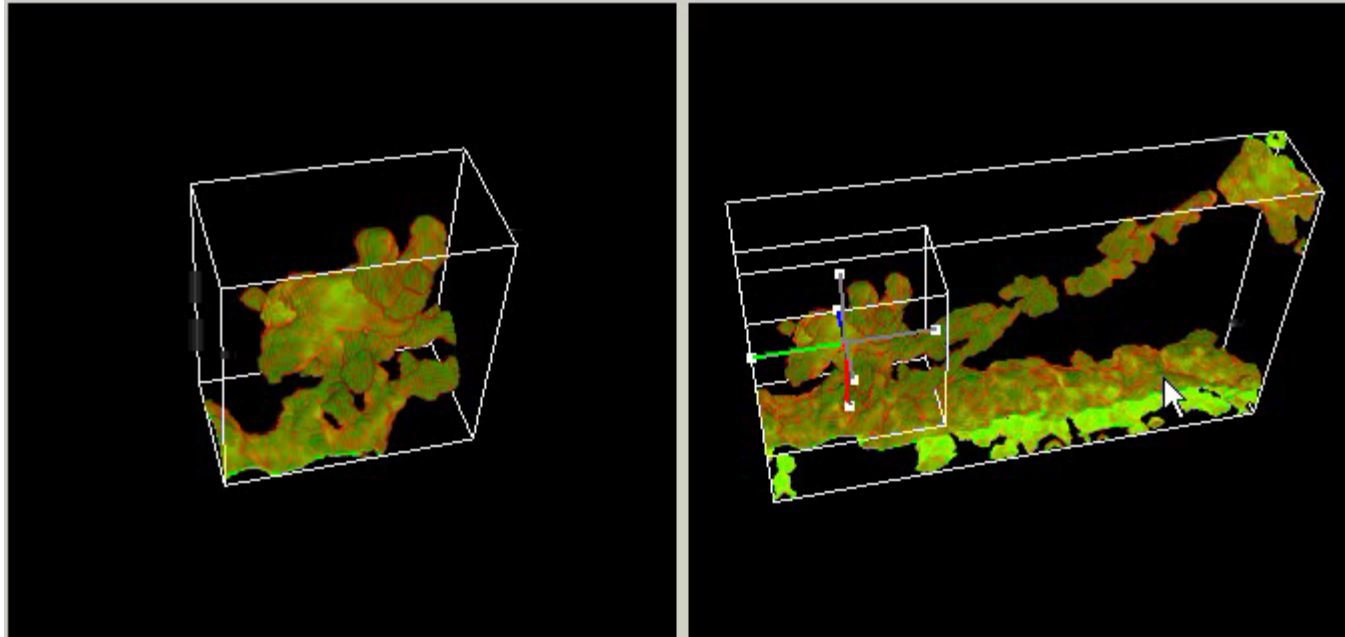
Skeletons of ActinBundle (B280a)



Segmentation of TipLink (B206a)



Segmented Tip Link (B206)

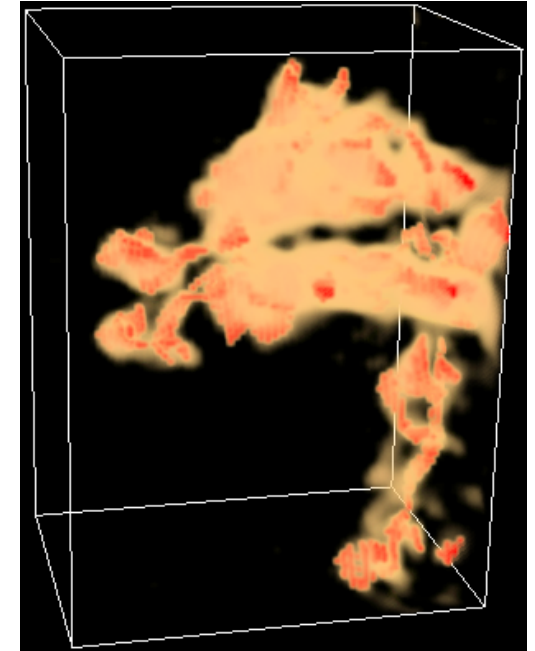
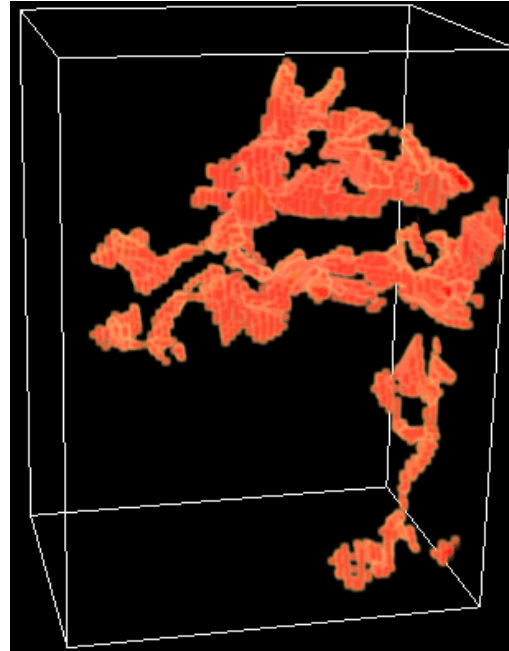
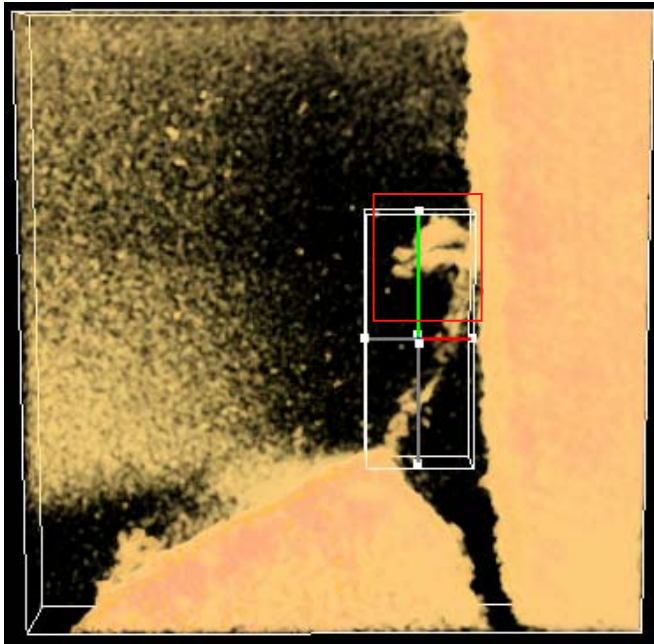


Bajaj, Zeyun, Auer, JSB,
2003 to appear.



skletonization/InPainting

- 3D Electron Tomogram



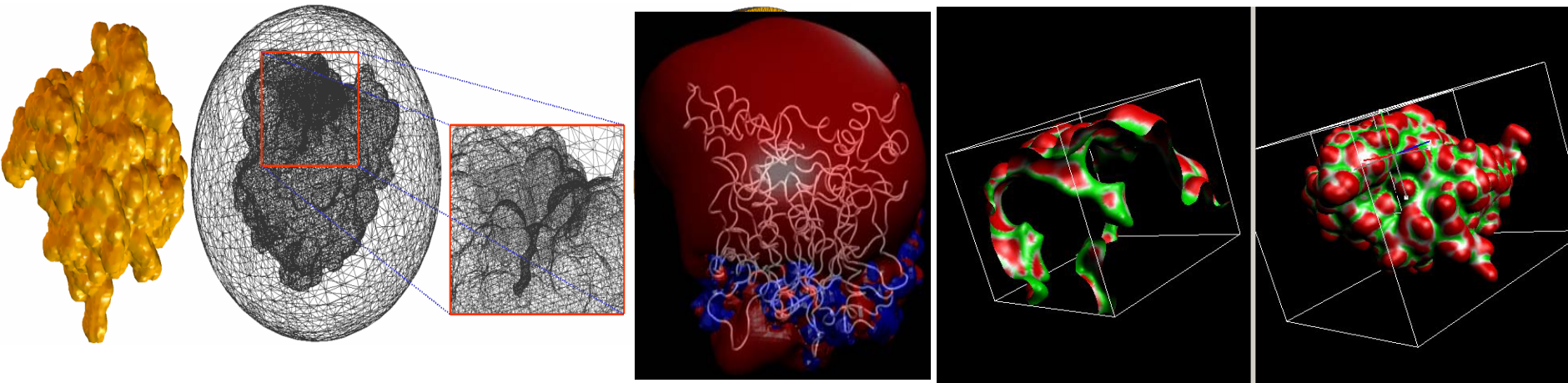
Overall volume

Skeletons

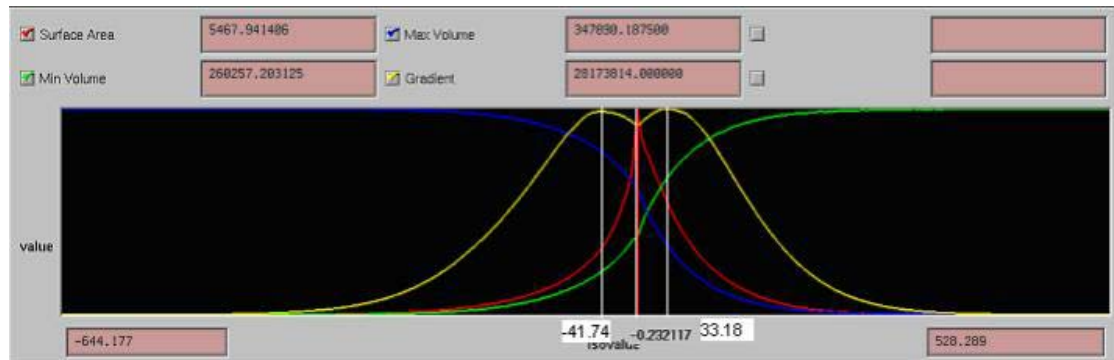
Skeletons with density map



Atomic Level Structure to Simulation to Analysis to Protein Function



PDB → Finite Element
Meshes with Properties
→ Poisson Boltzmann
Calculations →
Flexible Docking
→ Function Fingerprints



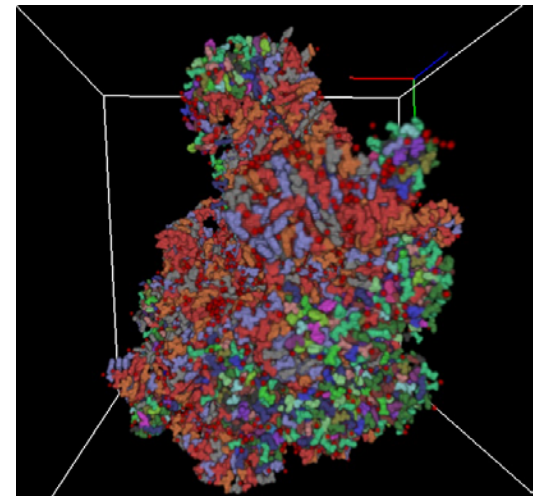
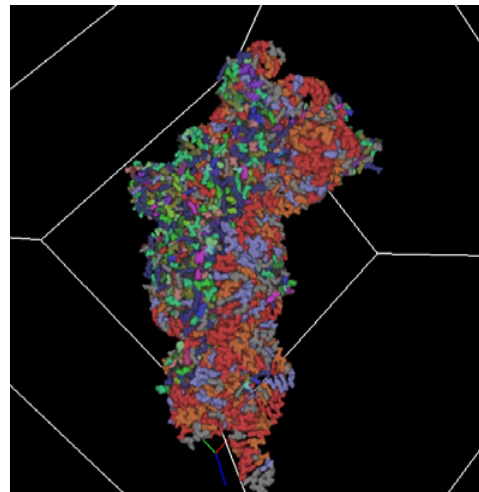
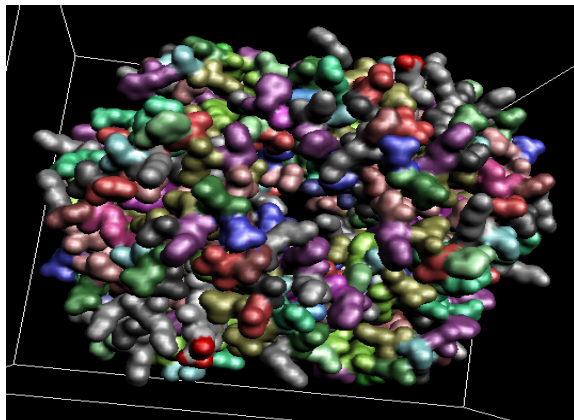
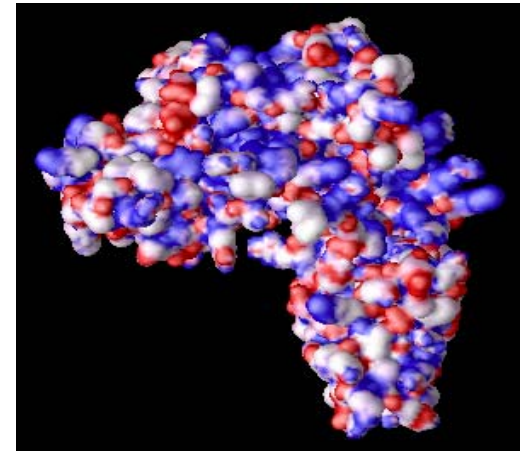
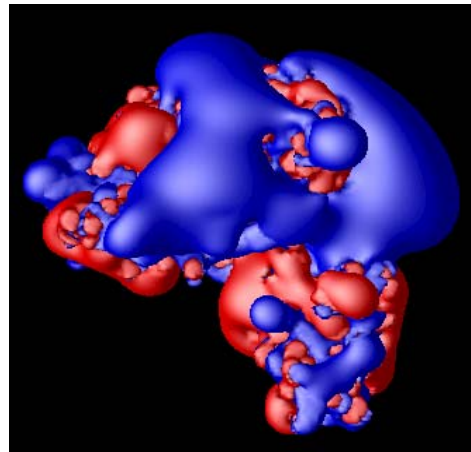
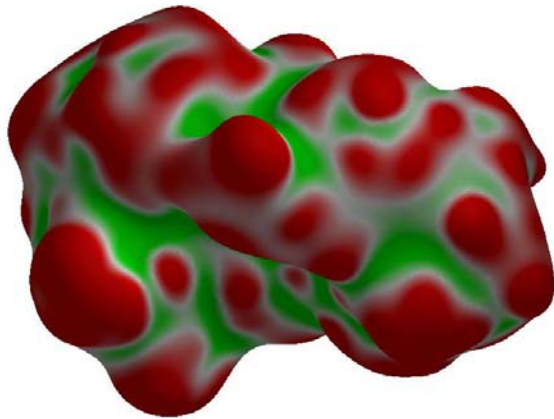
(Collaborators: N. Baker (Wash U), D. Goodsell(Scripps), A. McCammon (UCSD), A. Olson (Scripps), M. Sanner(Scripps))

****Sponsored by NSF-NPACI-**

Interaction Environments (Bio-Alpha)



Compressed Volumetric Representations of Structures & Properties



Volumetric Electron Density (Implicit Solvent Model)

The electron density in the unit volume at point r :

$$\rho(r; X) = N \int dv' \psi^*(x; X) \psi(x; X)$$

where \mathbf{x} denotes the collection of electronic space and spin coordinates and \mathbf{X} the collection of nuclear coordinates.

Common approximation = the summation of individual atomic electron charge distributions:

$$\rho_i(r) = \exp\left(\frac{B_i r^2}{R_i^2} - B_i\right)$$

where $B_i < 0$ is a blobby parameter and R_i is the van der Waals radius of the atom



Volumetric Electrostatic Potential (Baker, McCammon 2002: APBS)

A common model for evaluating the molecules' electrostatic properties is the Poisson-Boltzmann equation.

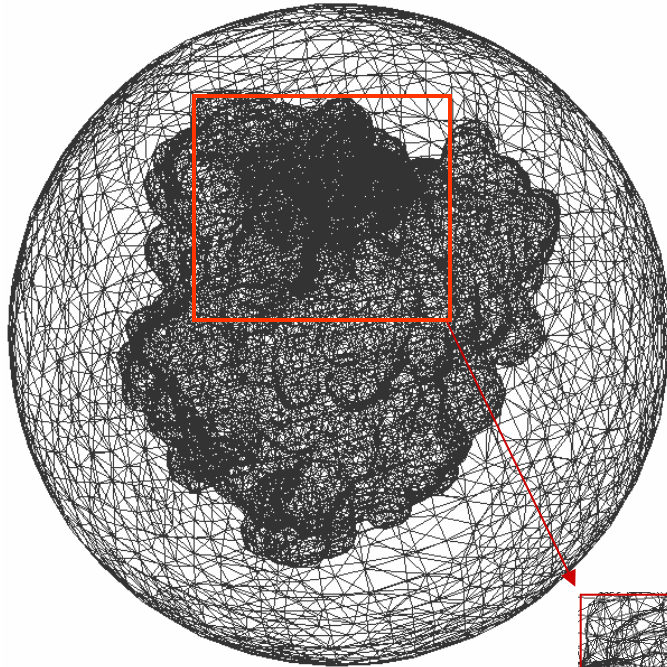
$$-\nabla \cdot [\varepsilon(\mathbf{r}) \nabla V(\mathbf{r})] + k^2(\mathbf{r}) \sinh(V(\mathbf{r})) = \rho(\mathbf{r})$$

where $\varepsilon(\mathbf{r})$ is the dielectric properties of the solute and solvent, k^2 is the ionic strength of the solution and the accessibility of ions to the solute, and $\rho(\mathbf{r})$ is the distribution of solute atomic partial charges.

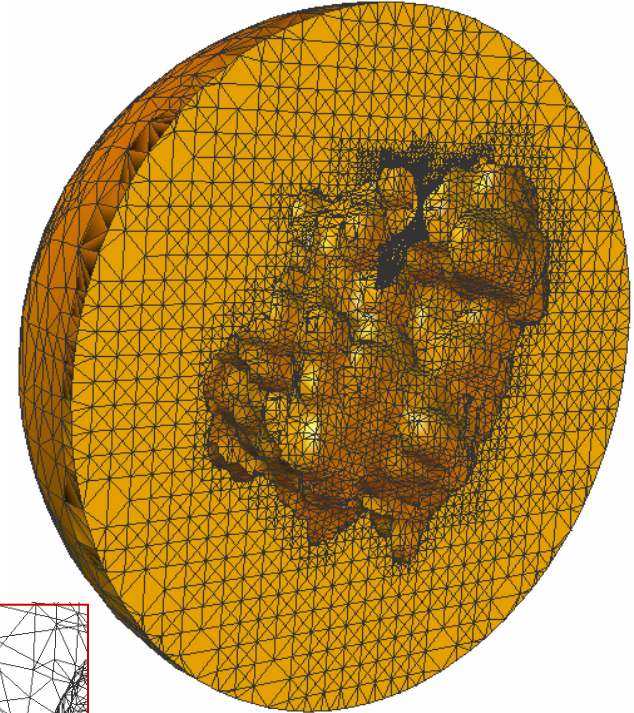
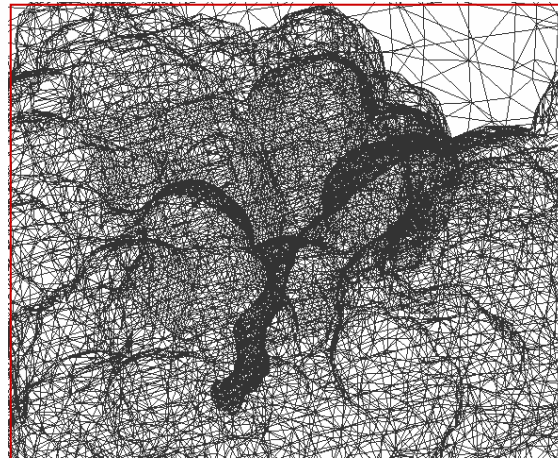


Finite Element Models

– AcetylCholinesterase (257³, 66MB)



The active site groove is inside the red box. Adaptive meshes are generated in order to keep the accuracy of the groove, and reduce the number of elements at the same time.

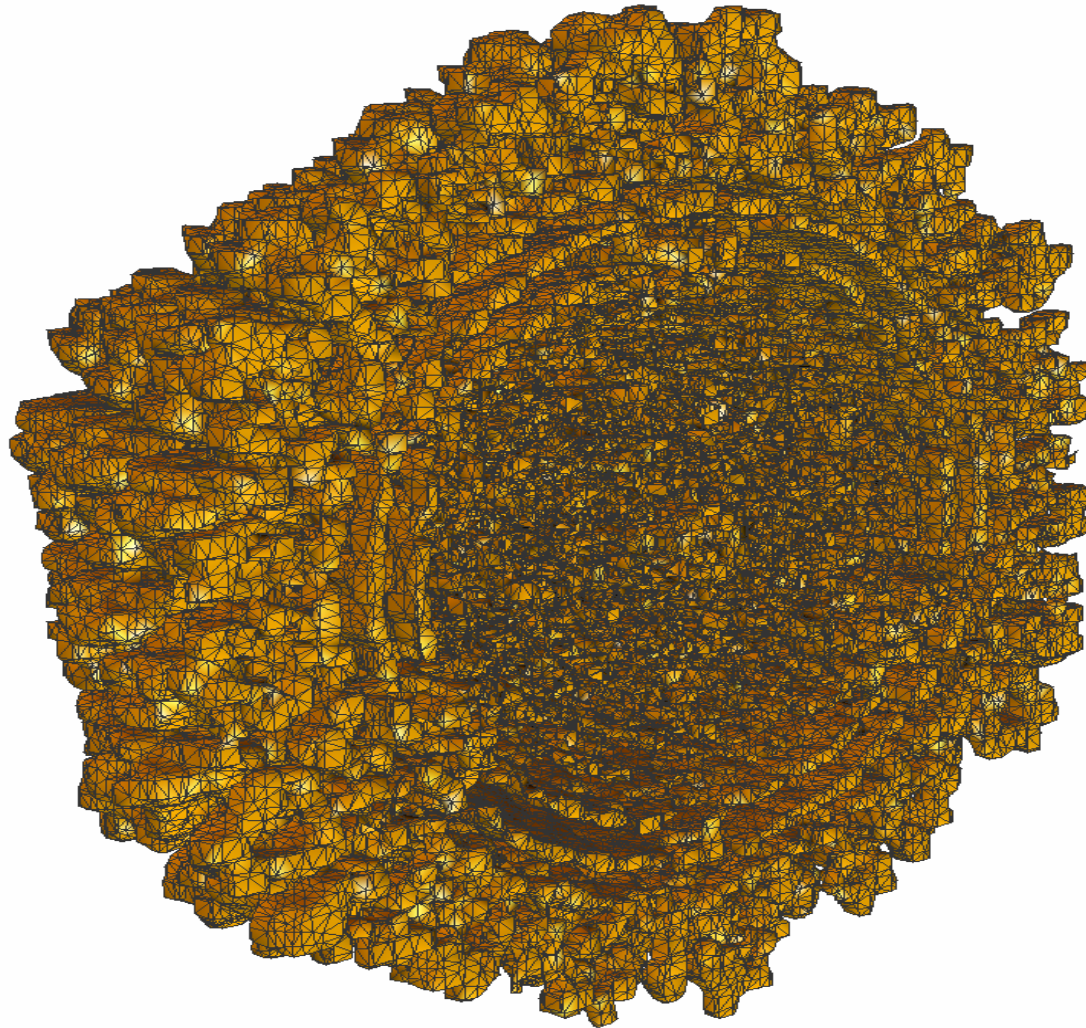


94847 vertices and
497327 tetra

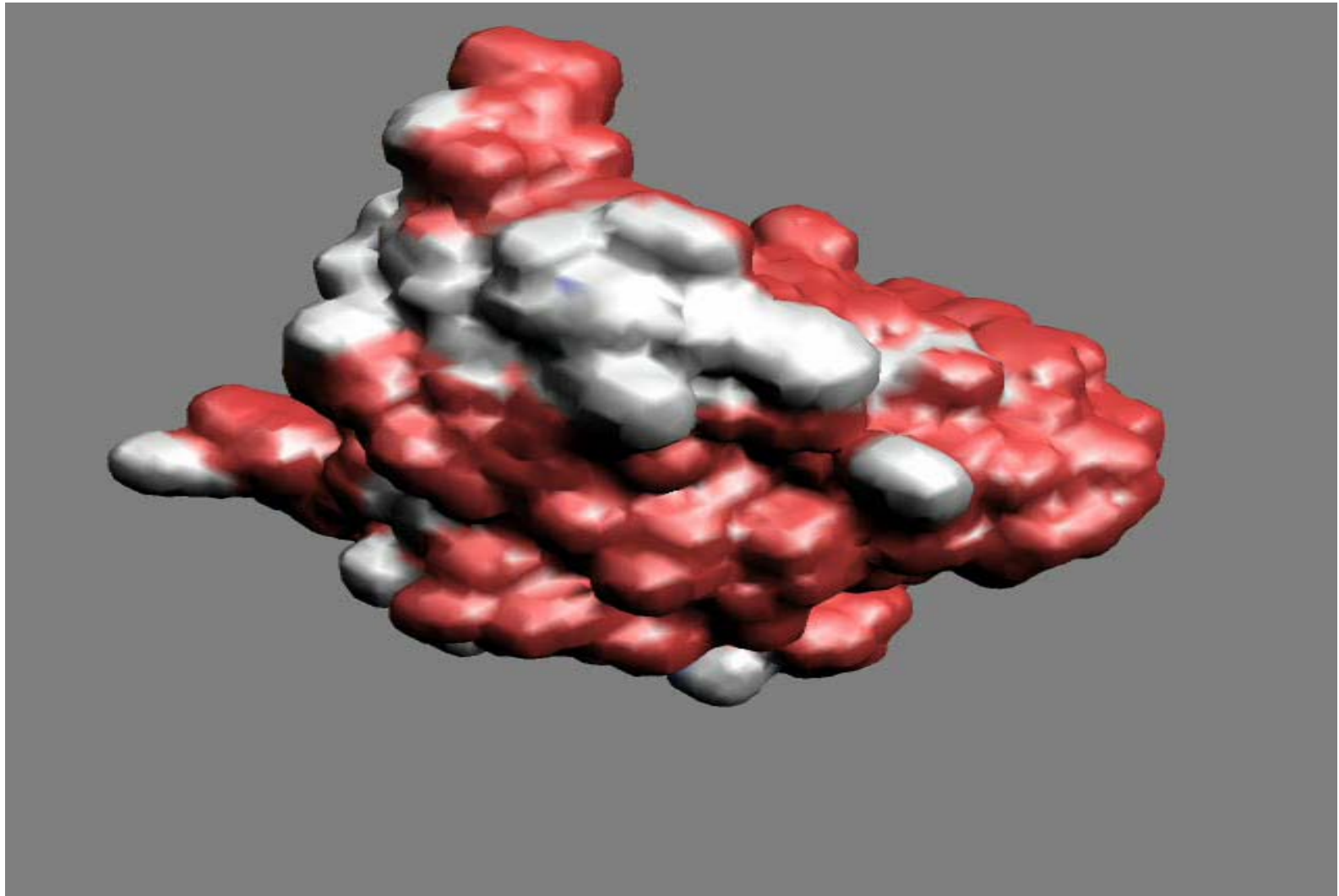
Zhang, Bajaj, Sohn,
ACM Solid
Modeling 2003



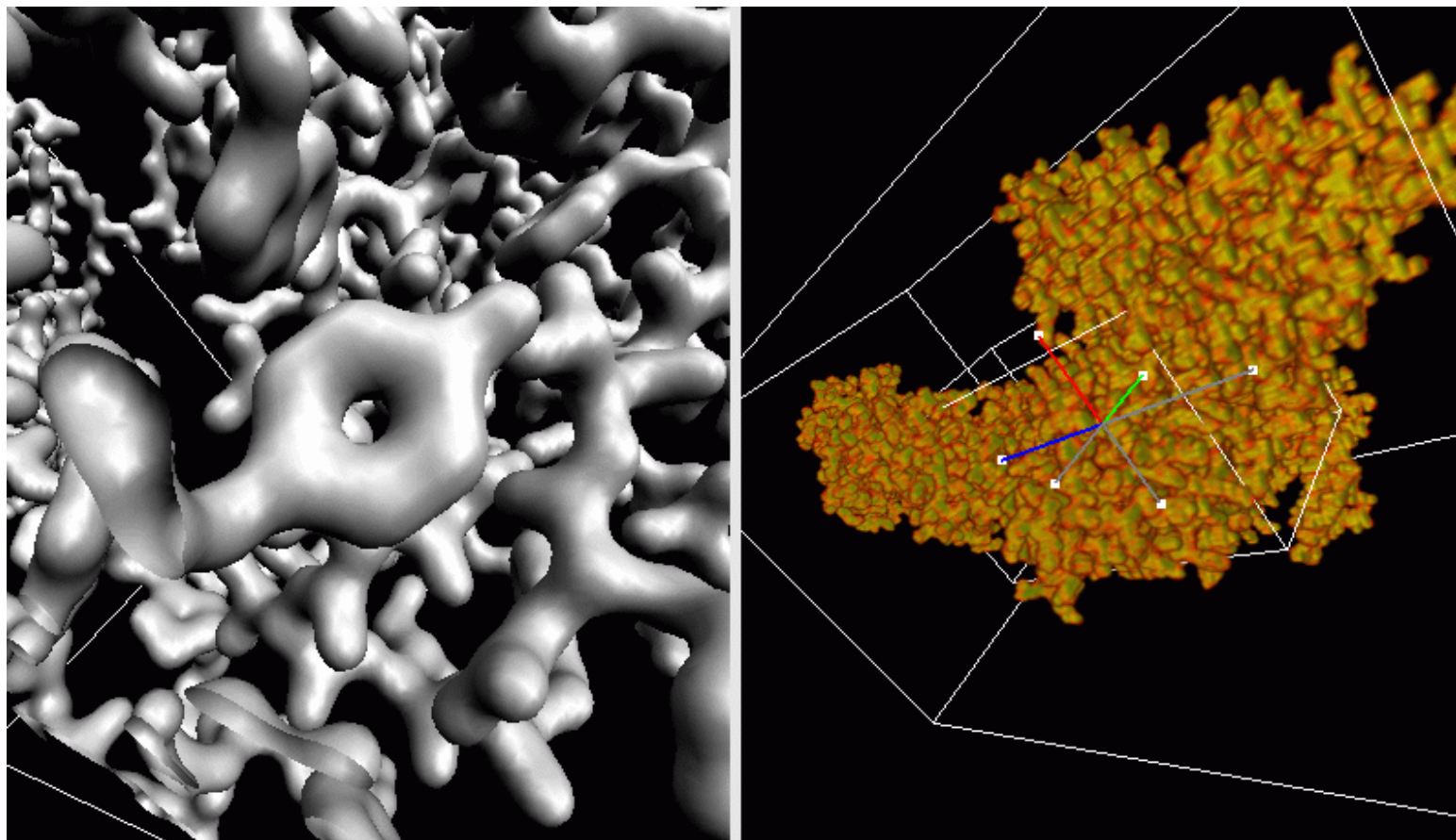
Finite Element Meshing



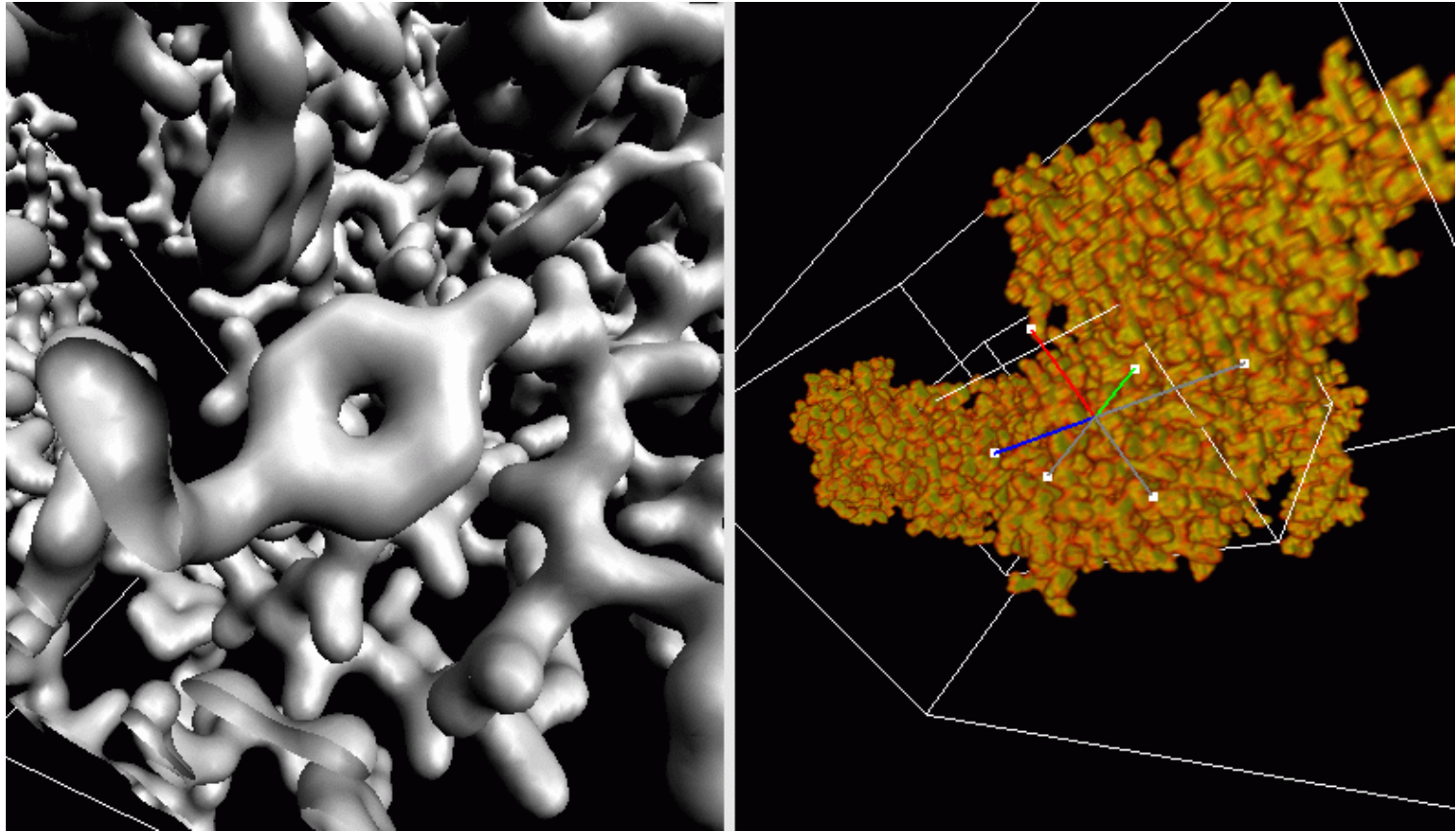
Electrostatic Potential on MACHE



HIV-1 Reverse Transcriptase In Complex With A Polypurine Tract RNA (12,139 atoms)



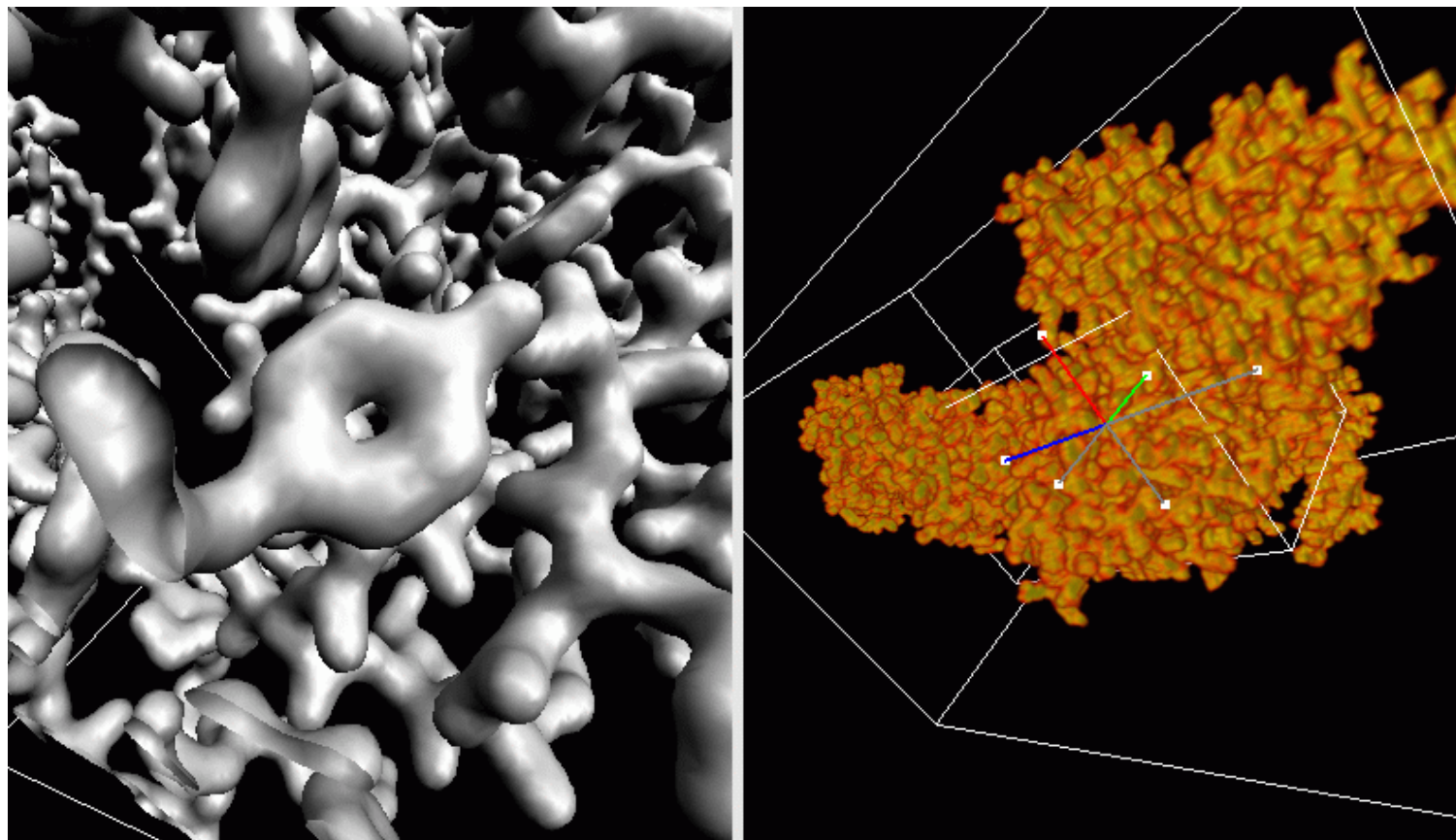
HIV-1 Reverse Transcriptase In Complex With A Polypurine Tract RNA (12,139 atoms)



Compression: 18.5:1 Error: 2.9%



HIV-1 Reverse Transcriptase In Complex With A Polypurine Tract RNA (12,139 atoms)



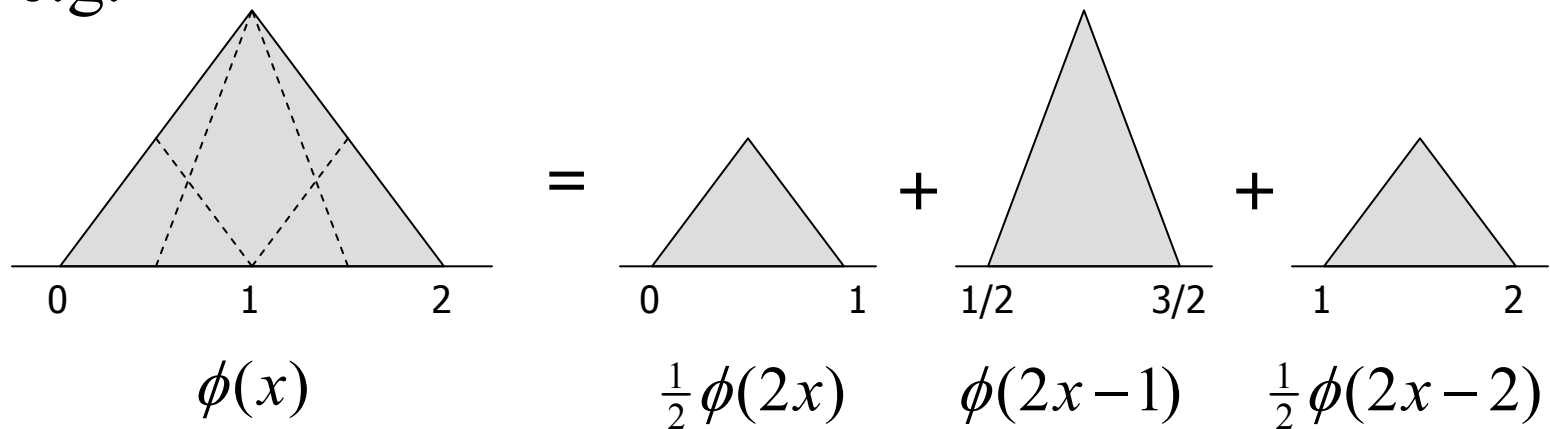
Compression: 49:1 Error: 6.9%



Background (Classical Wavelet Representations)

Key idea: refinement

e.g.



$$\phi(x) = \sum_k h_0[k] \phi(2x - k) \quad \text{with} \quad h_0[k] = \left\{ \frac{1}{2}, 1, \frac{1}{2} \right\}$$

Refinable functions are called scaling functions



Wavelet Representations

Wavelets are also linear combinations of scaling functions

$$\psi(x) = \sum_k h_1[k] \phi(2x - k)$$

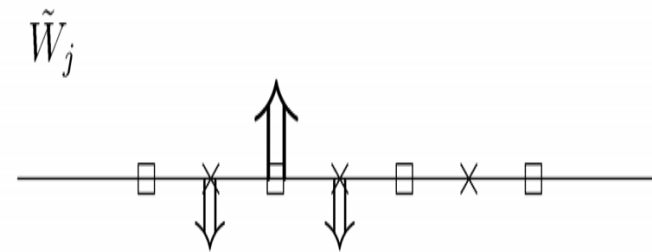
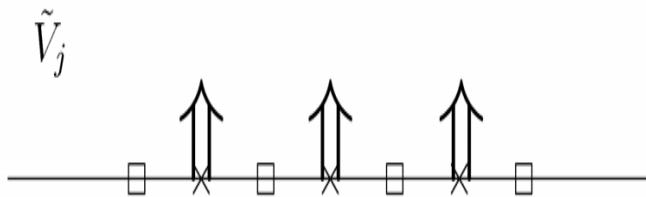
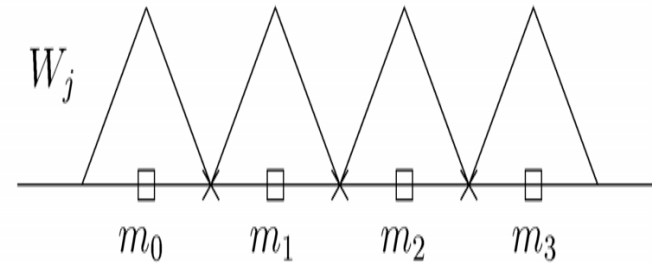
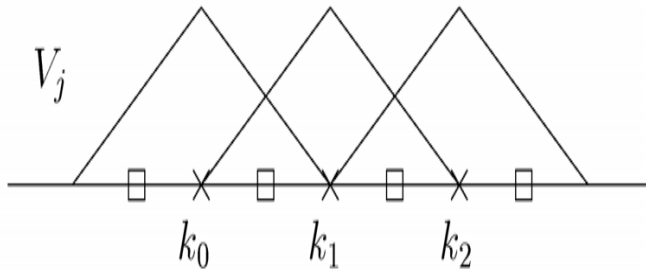
Usual design criteria for $h_0[k]$ and $h_1[k]$

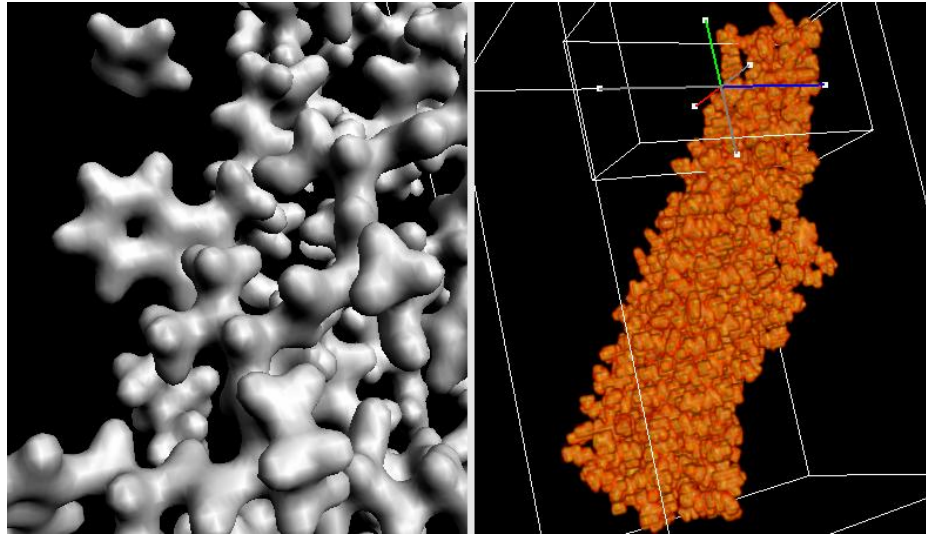
- finite length \Rightarrow makes wavelet and scaling functions compactly supported
- Vanishing moments:

$$\int \psi(x) x^m dx = 0$$

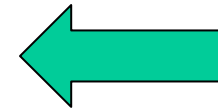


2nd Generation Wavelets Based on Hierarchical Basis and a Lifting Scheme

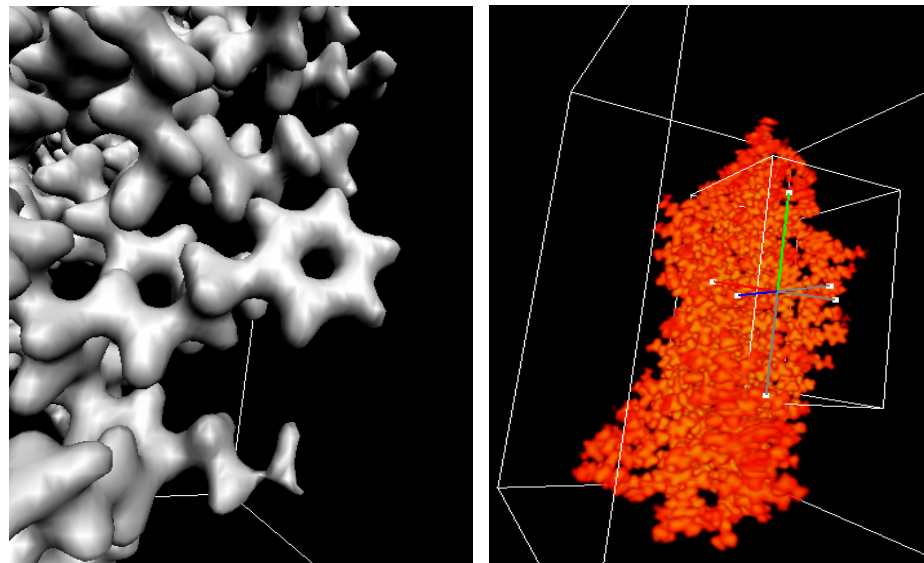


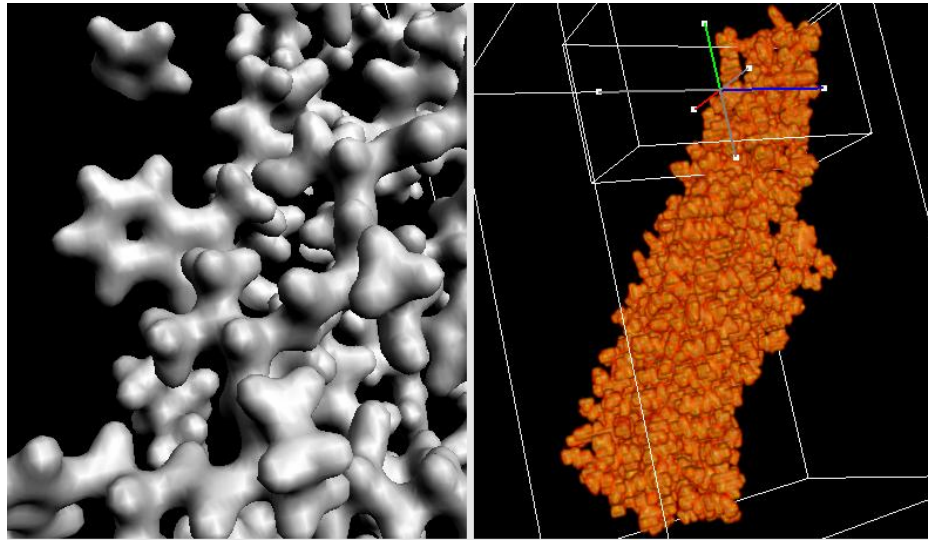


Original data set to be
Compressed by Linear
Hierarchal Basis

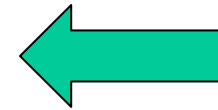


Original data set
To be
Compressed by
Haar Wavelets

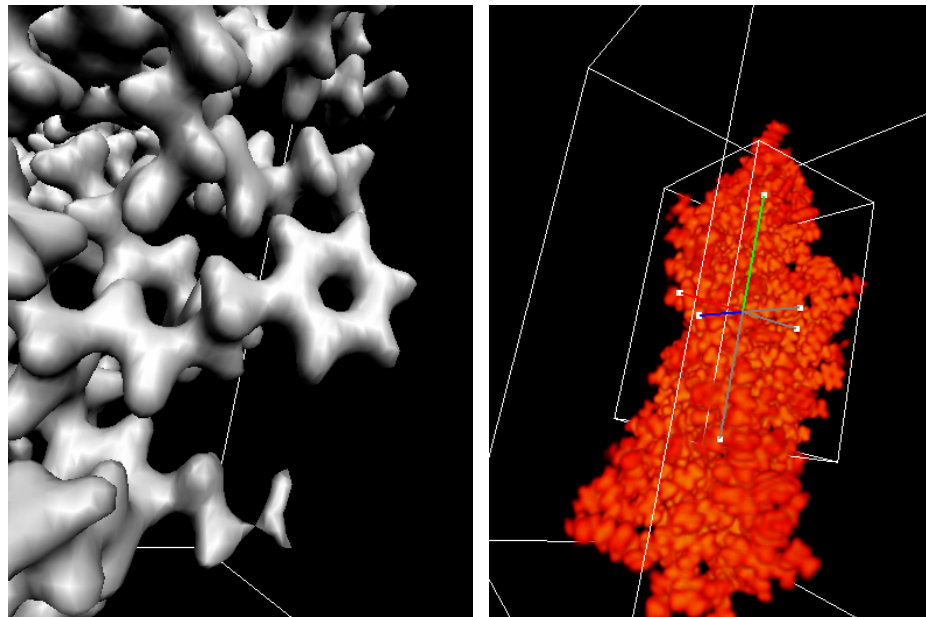


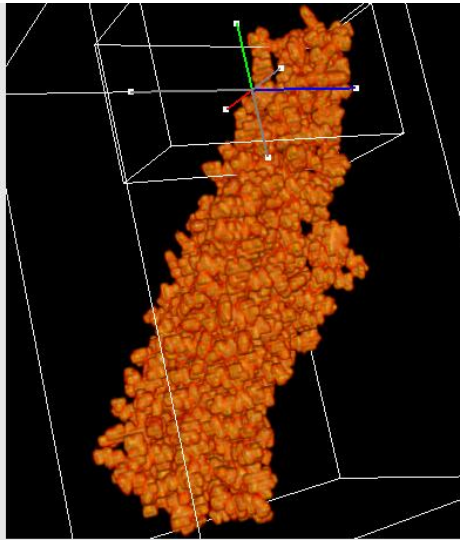
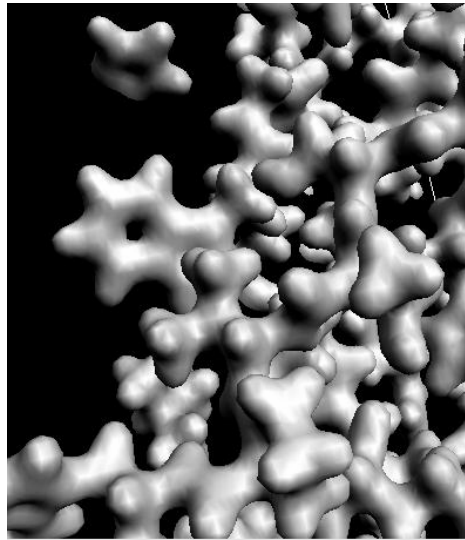


Linear Hierarchical Basis
Total Compression(TC):37

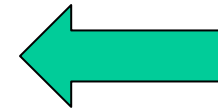


Haar Wavelets
TC:20

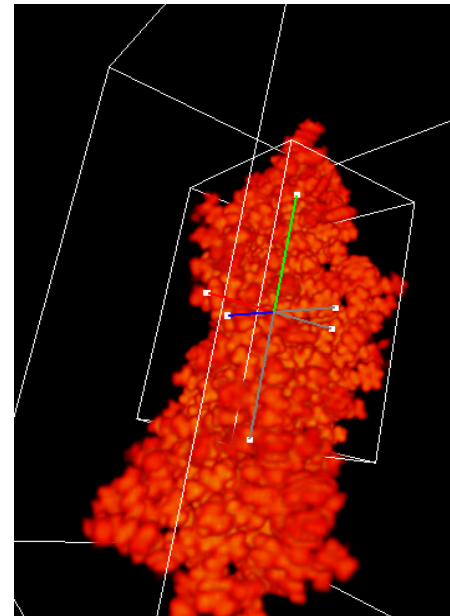
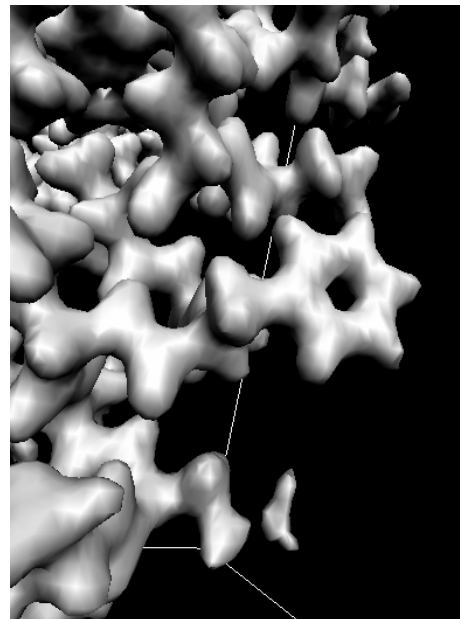


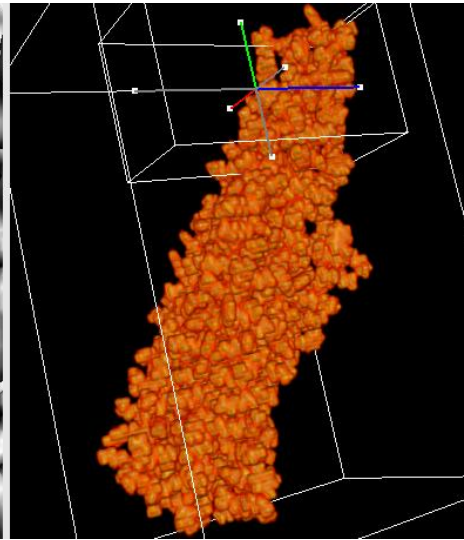
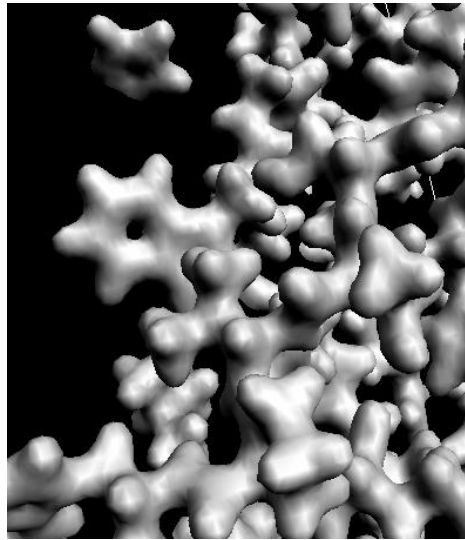


Linear Hierarchical Basis
Total Compression:37

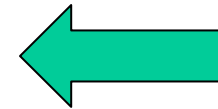


Haar Wavelets
TC:33

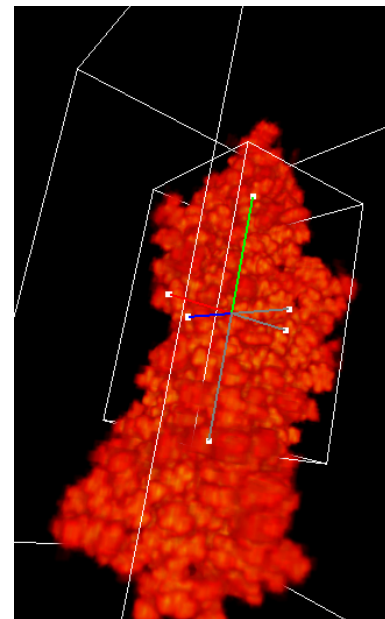
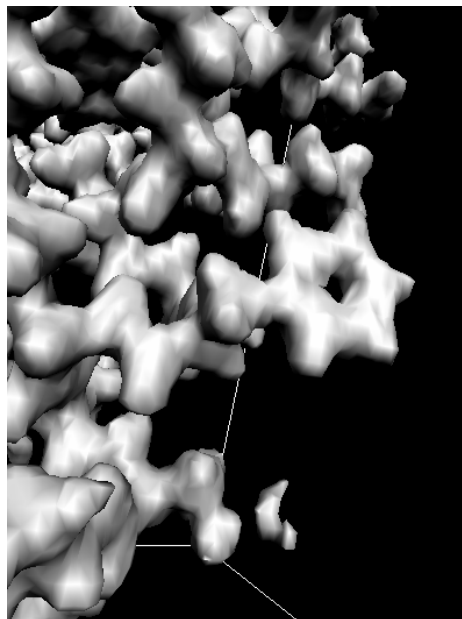
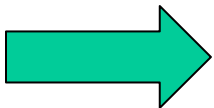


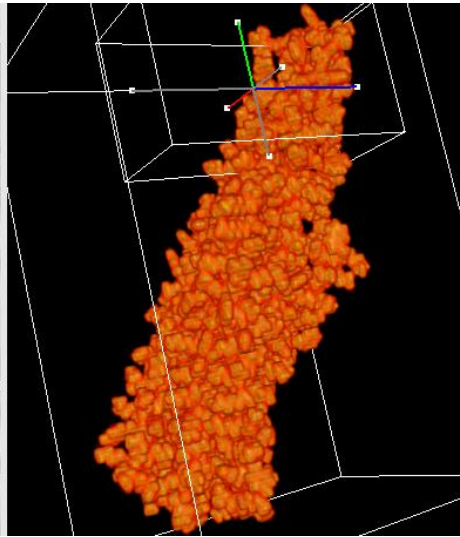
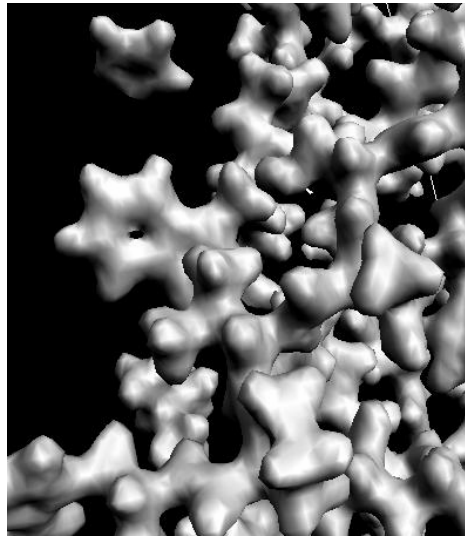


Linear Hierarchical Basis
TC:70.8

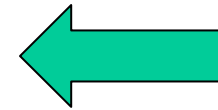


Haar Wavelets
TC:70.8

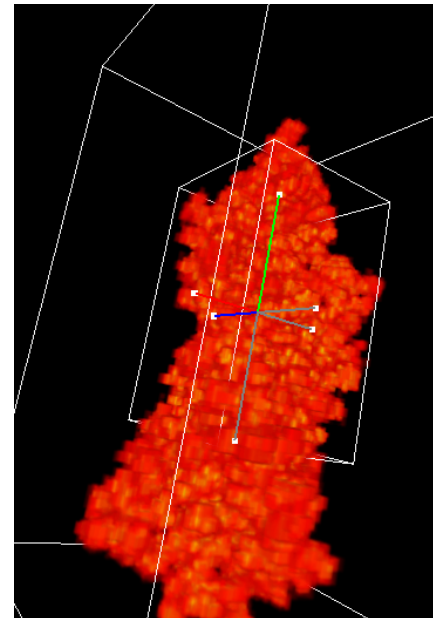
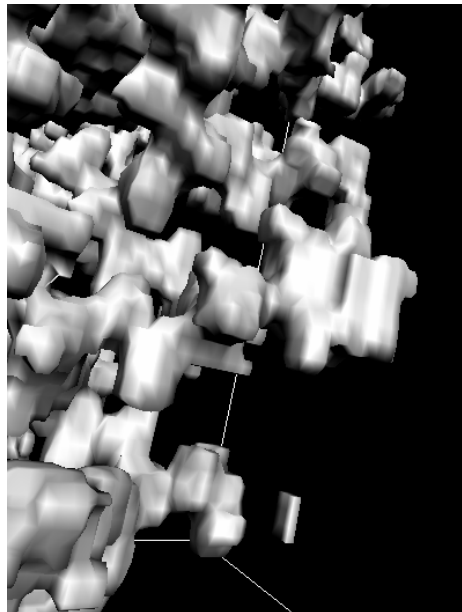


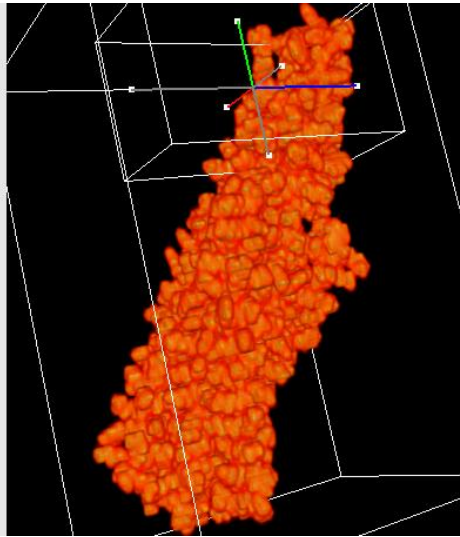
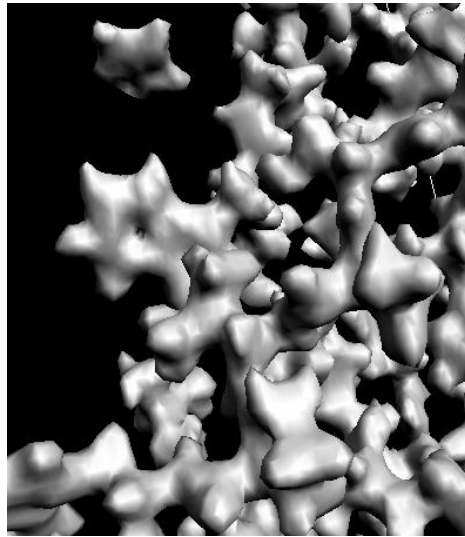


Linear Hierarchical Basis
TC:206.9

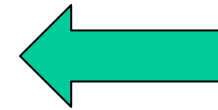


Haar Wavelets
TC:206.9

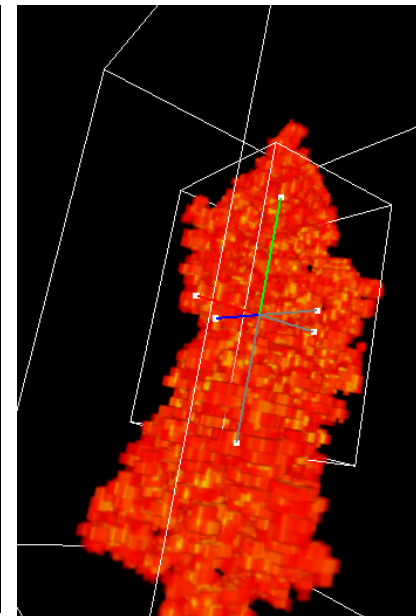
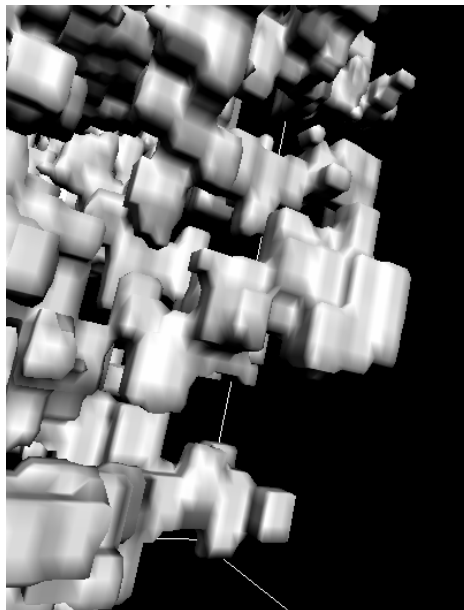




Linear Hierarchical Basis
TC:571

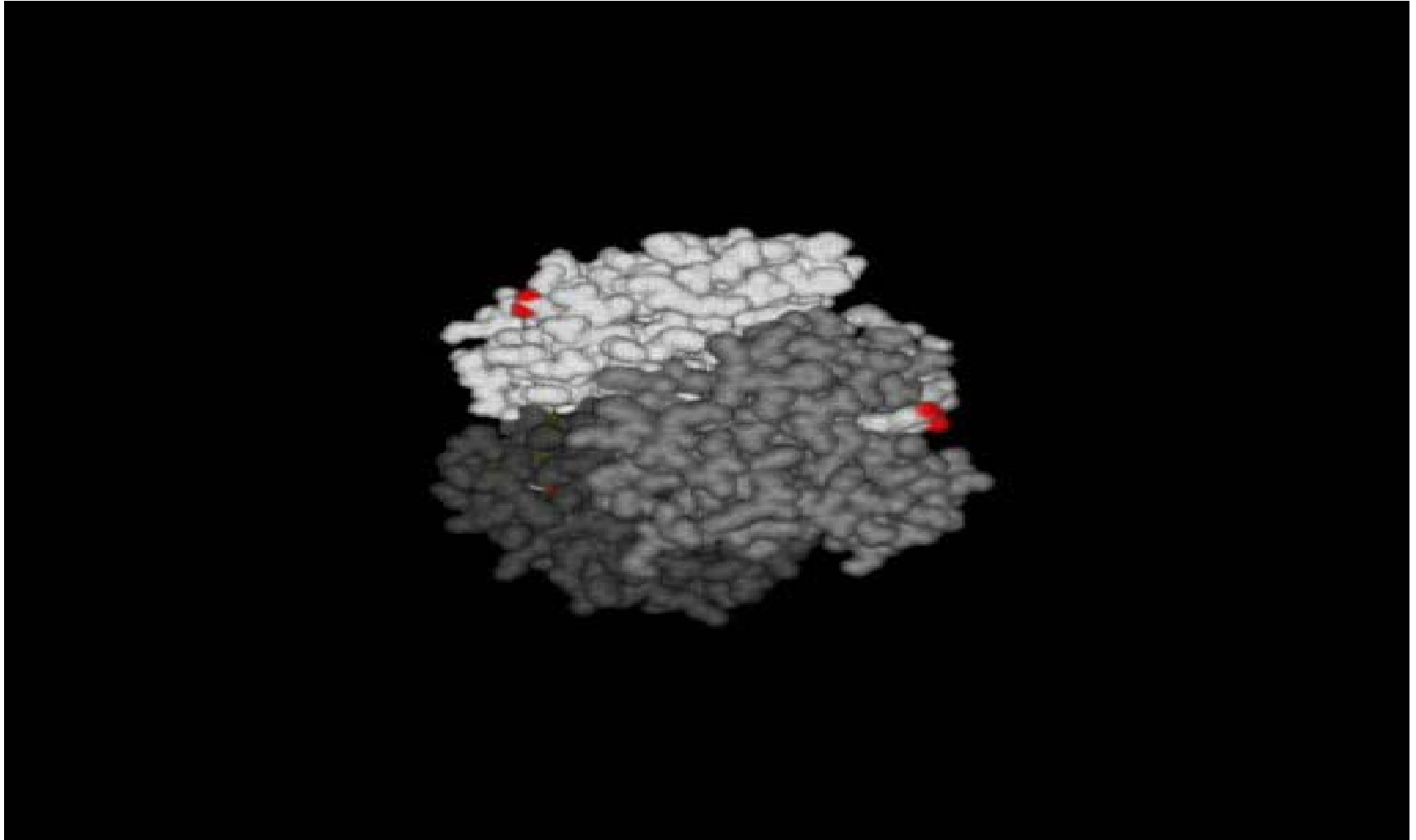


Haar Wavelets
TC:571

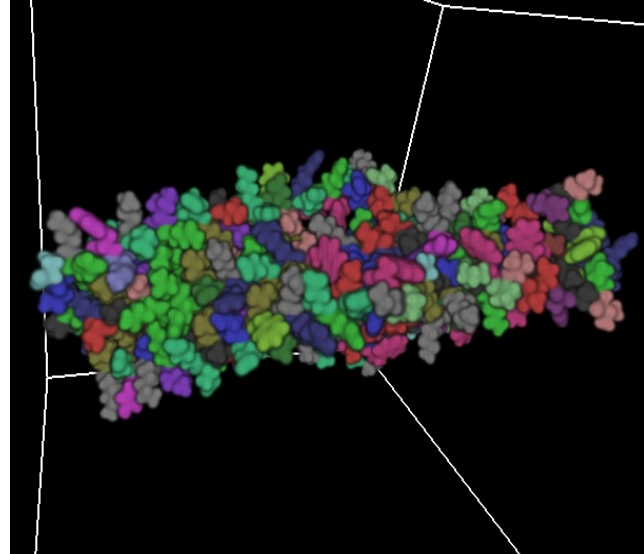
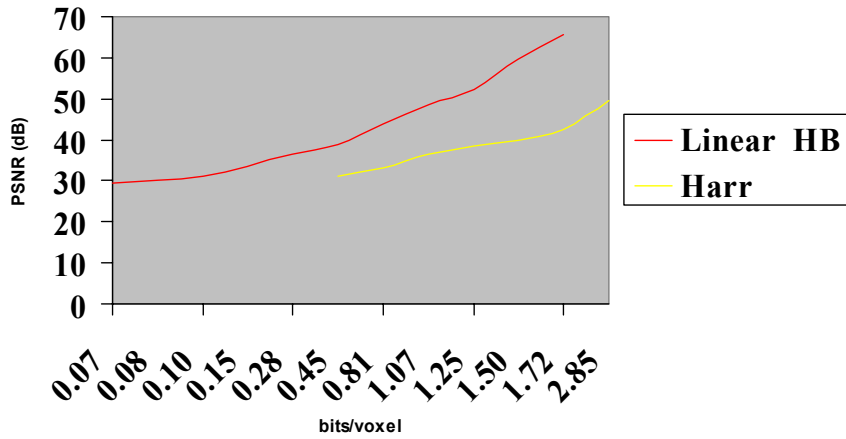


Visualization of Hemoglobin Dynamics

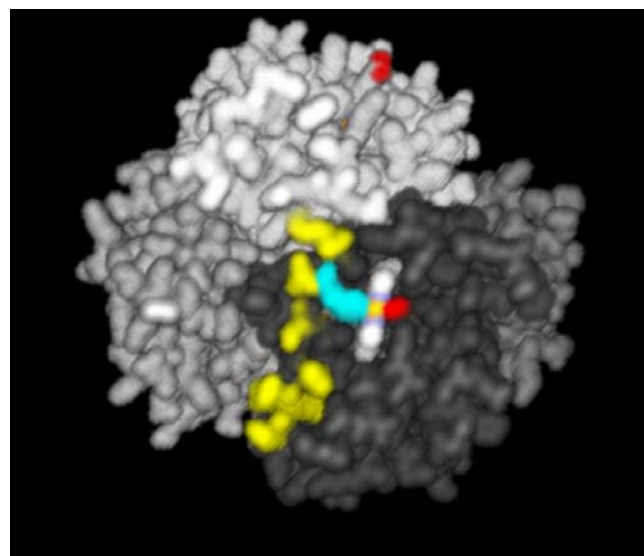
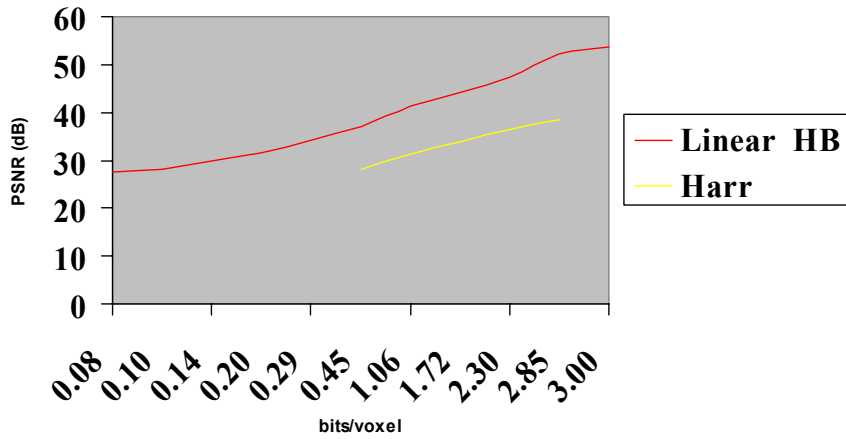
Interrogative Volumetric Video (VolVis2002)



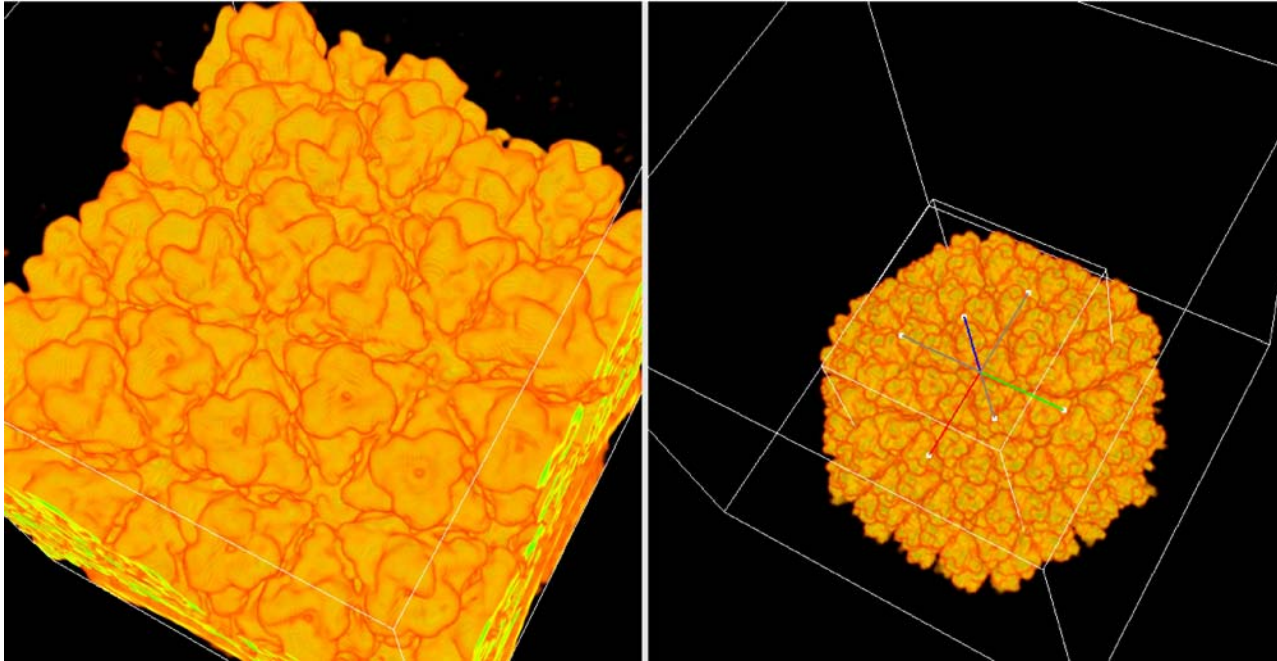
Rate Distortion (2EZP)



Rate Distortion (Hemoglobin)



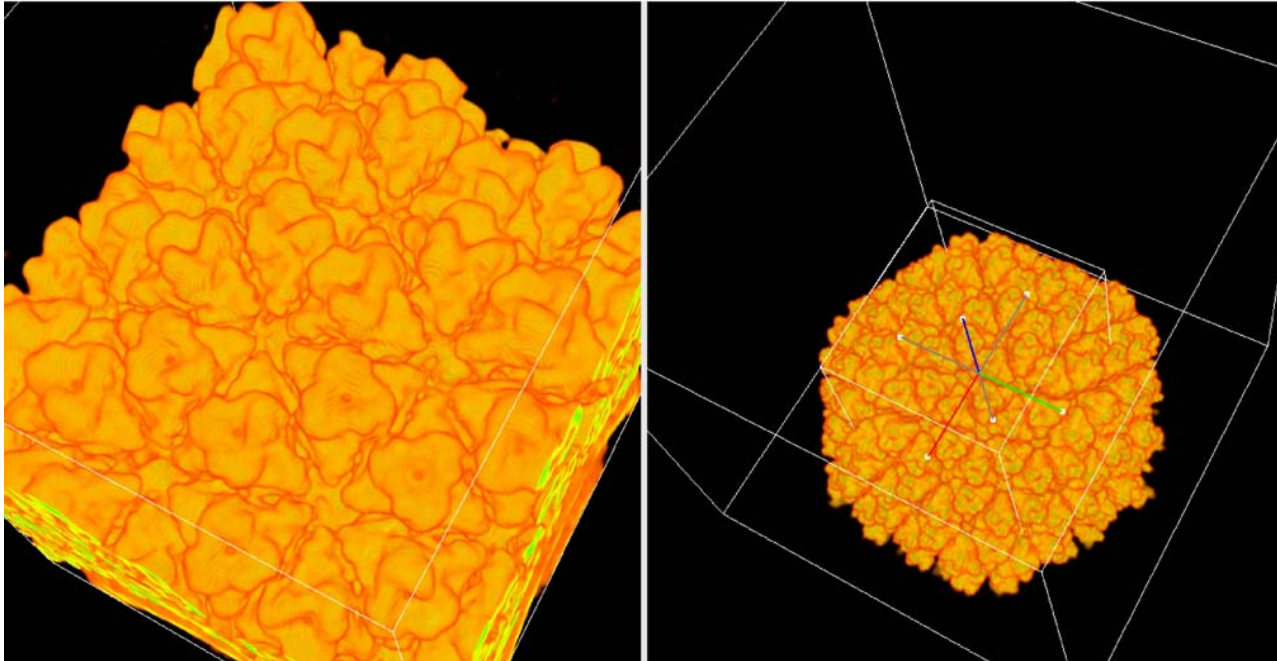
Rice Dwarf Virus(Smoothed)



Original



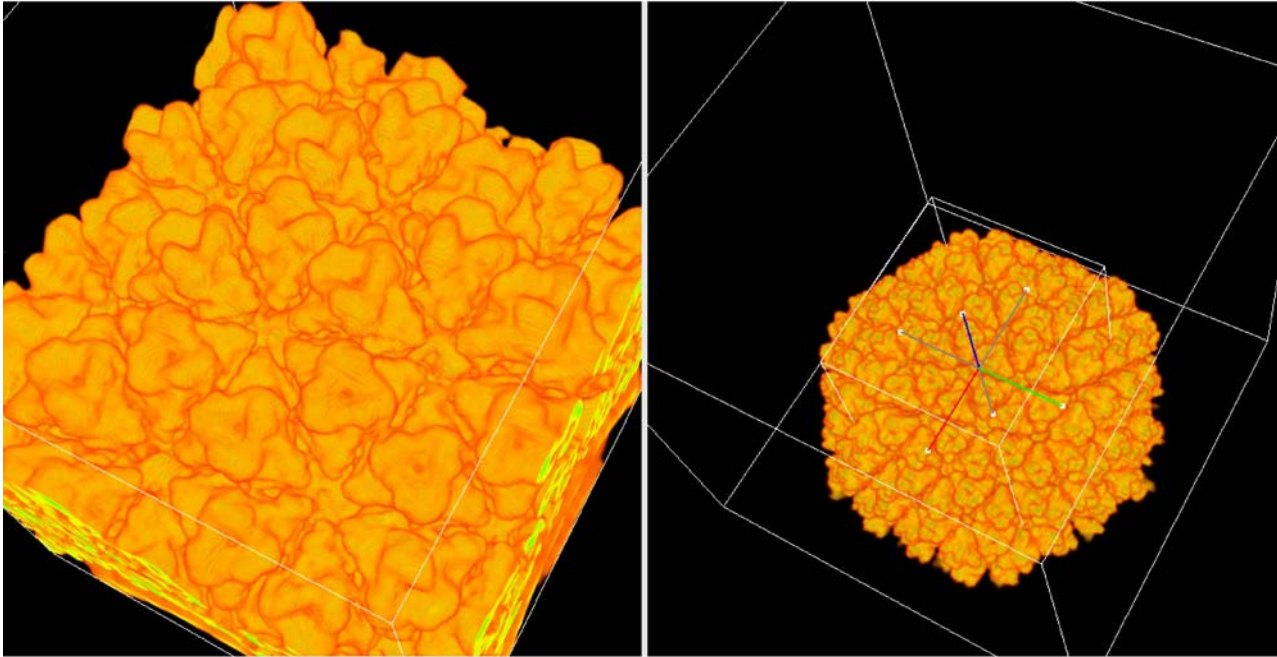
Rice Dwarf Virus(Smoothed)



TC=31.6, PSNR =42.4dB



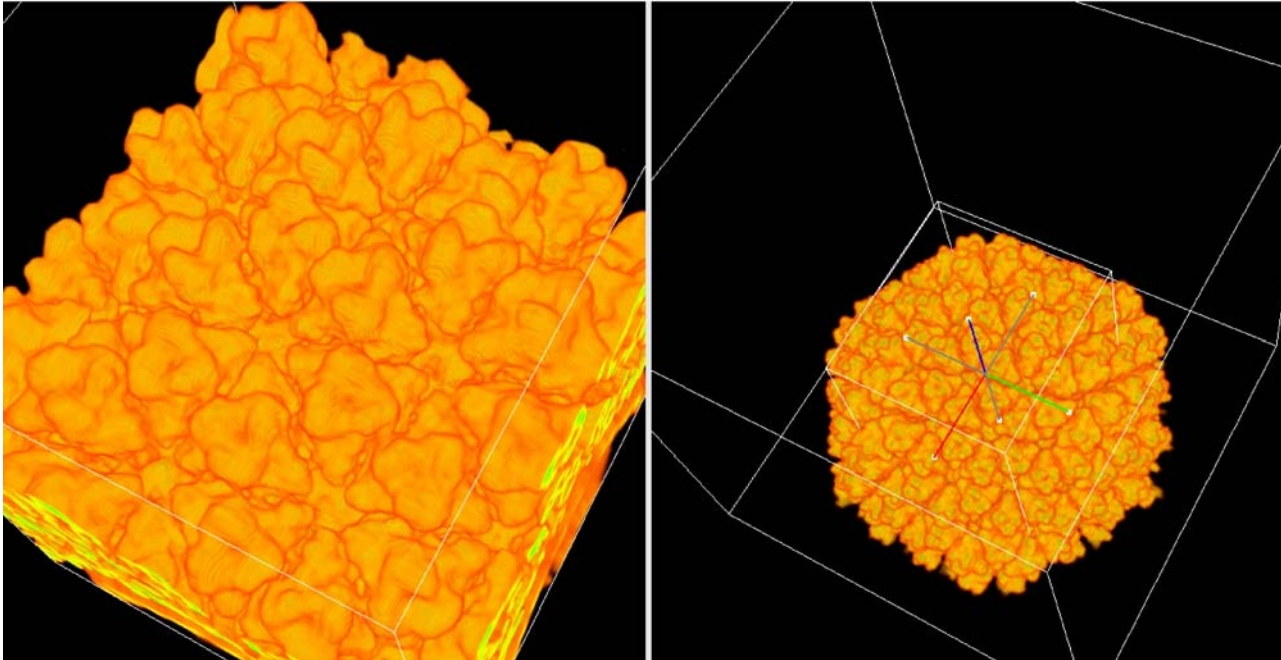
Rice Dwarf Virus(Smoothed)



TC=120.3, PSNR =36.5dB



Rice Dwarf Virus(Smoothed)

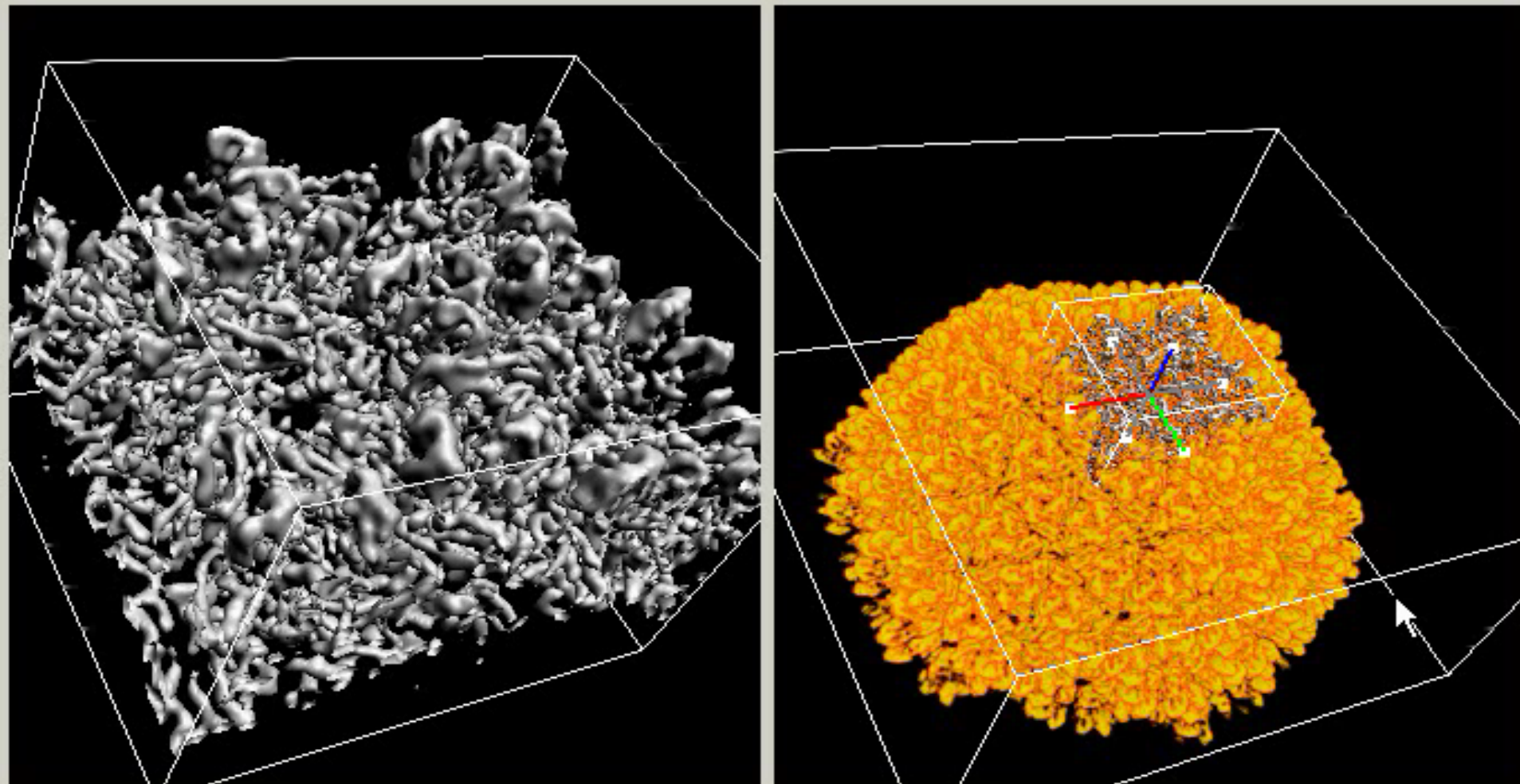


TC=328.3, PSNR =31.6dB



Multi-Resolution Volume Exploration

(<http://www.ices.utexas.edu/CCV/software/>)



Volume Rover (CORBA client)



Center for Computational Visualization
Institute of Computational and Engineering Sciences
Department of Computer Sciences

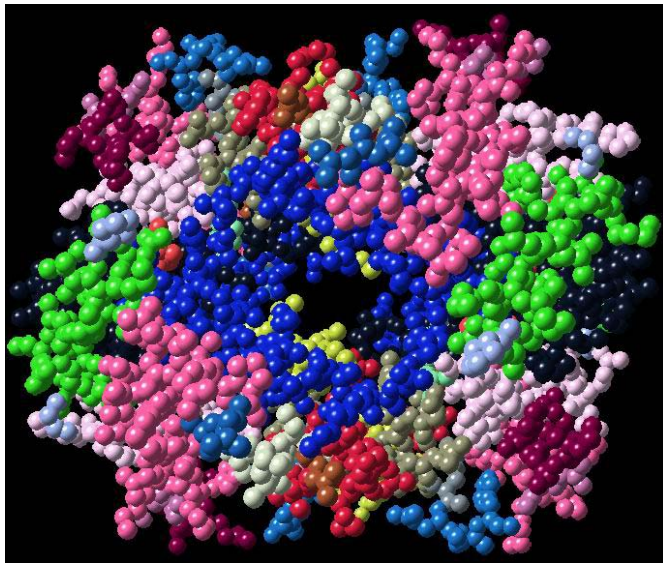
University of Texas at Austin

Oct 2003

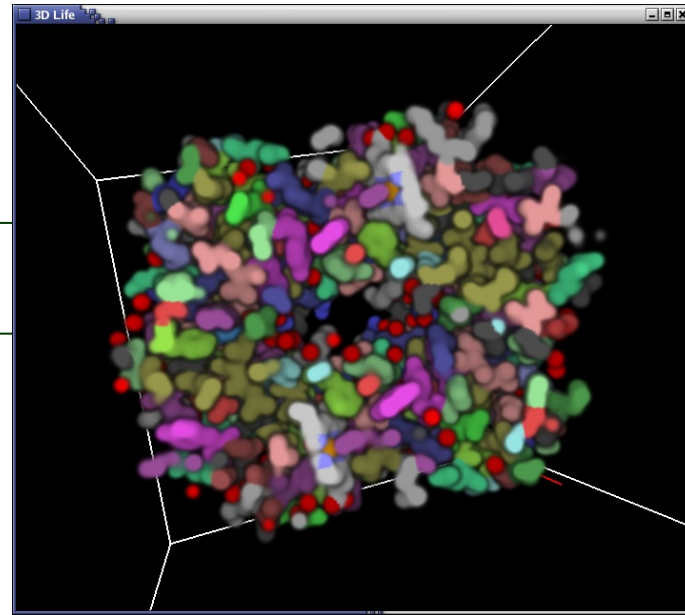
Multi-Level Visualization

Hemoglobin

CPK



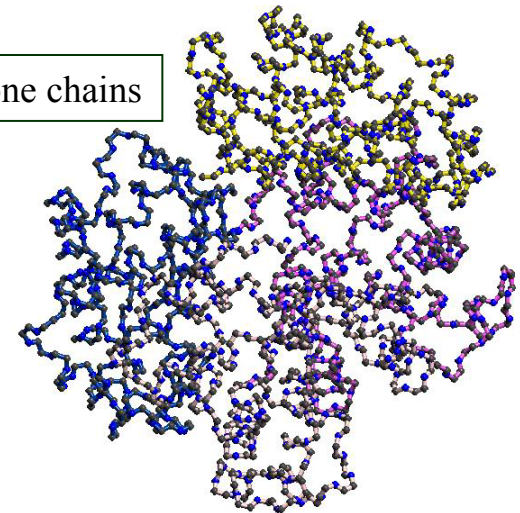
Coloring
Via Residues



Volume
Rendering

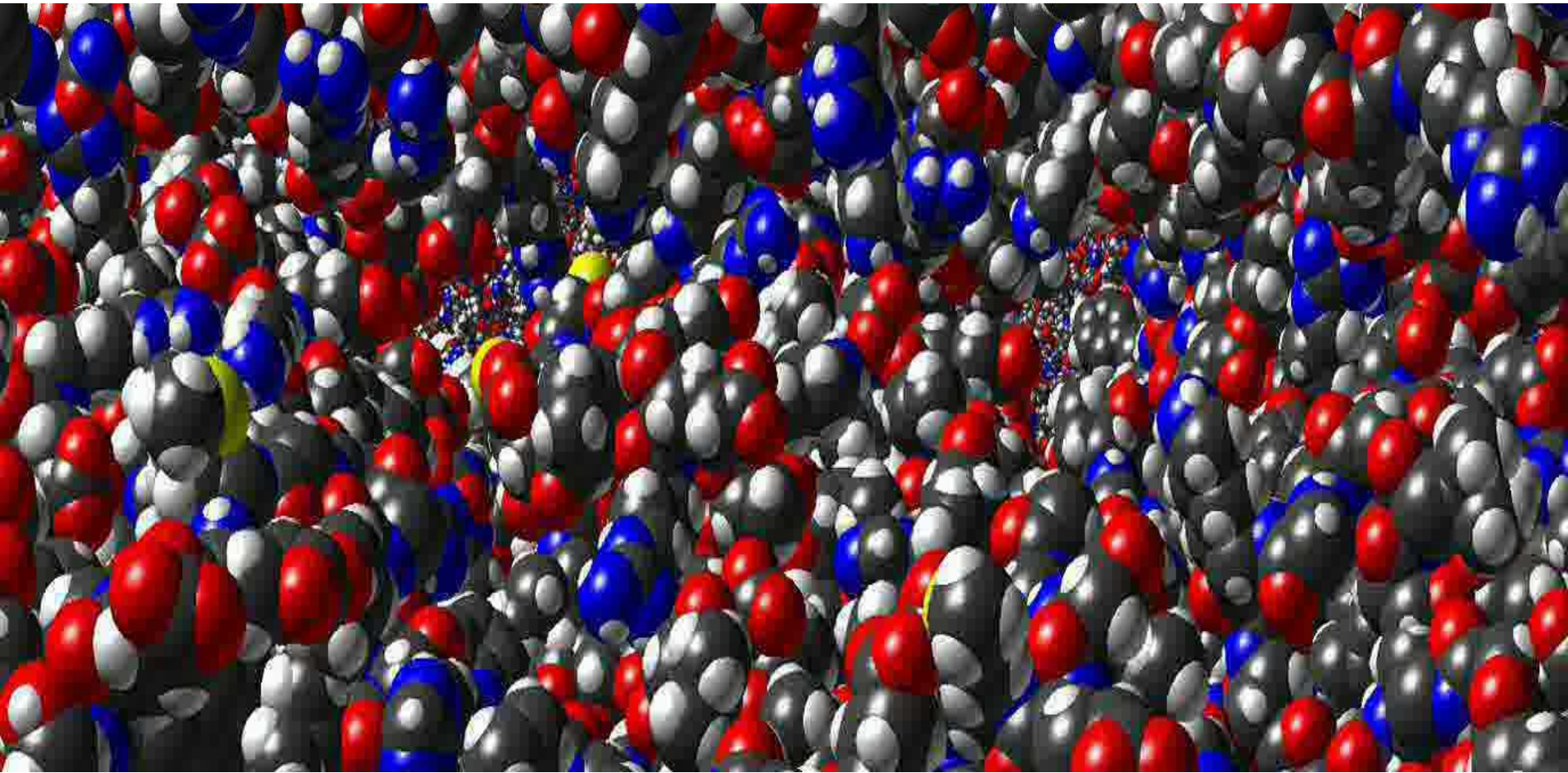
Backbone chains

Coloring via Secondary structures

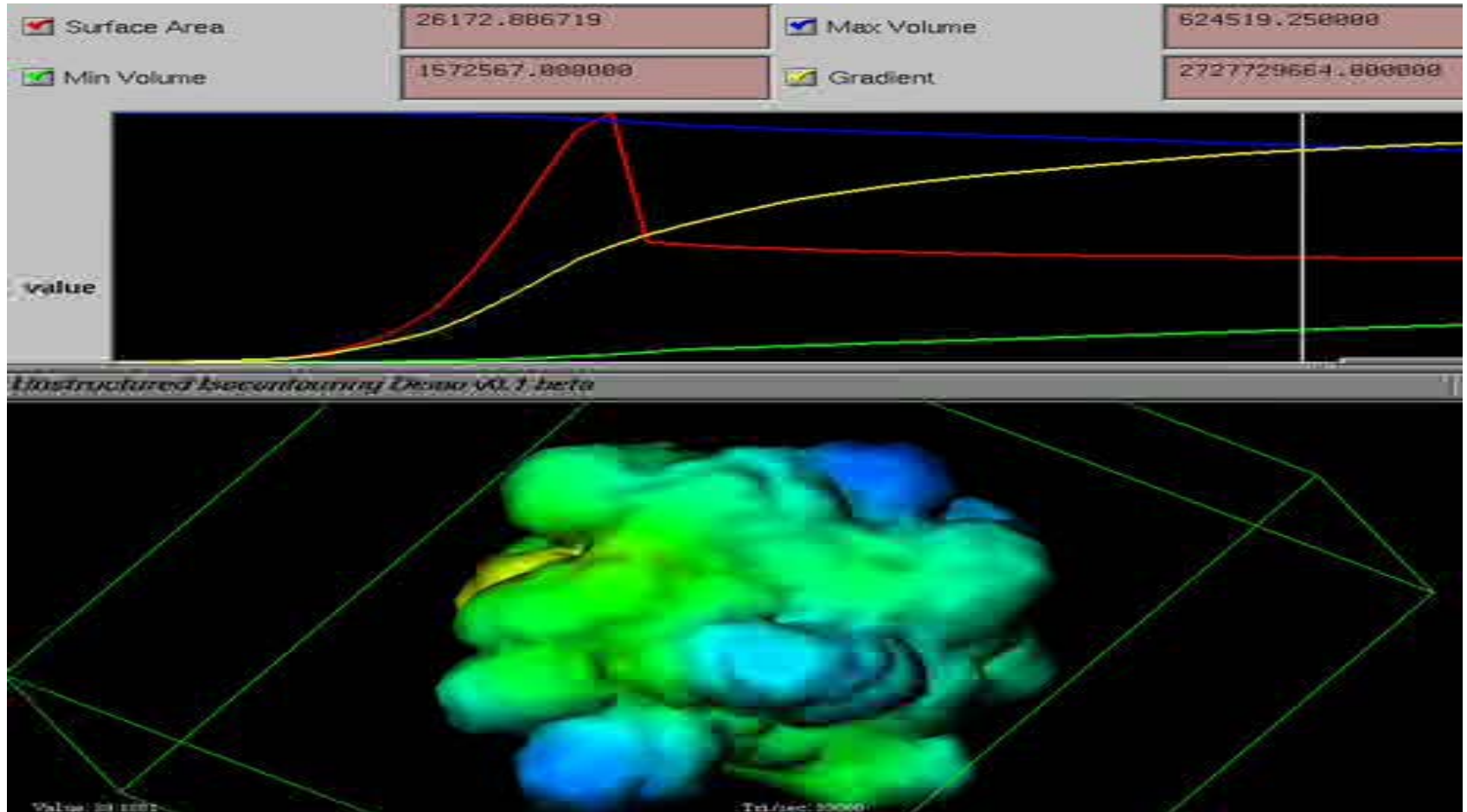


Microtubule

(Graphics Accelerated Texture-Impostors)



(TAQT: Topology Analyses & Quantitative Tools)



The Contour Spectrum (IEEE Vis '97)

Center for Computational Visualization
Institute of Computational and Engineering Sciences
Department of Computer Sciences

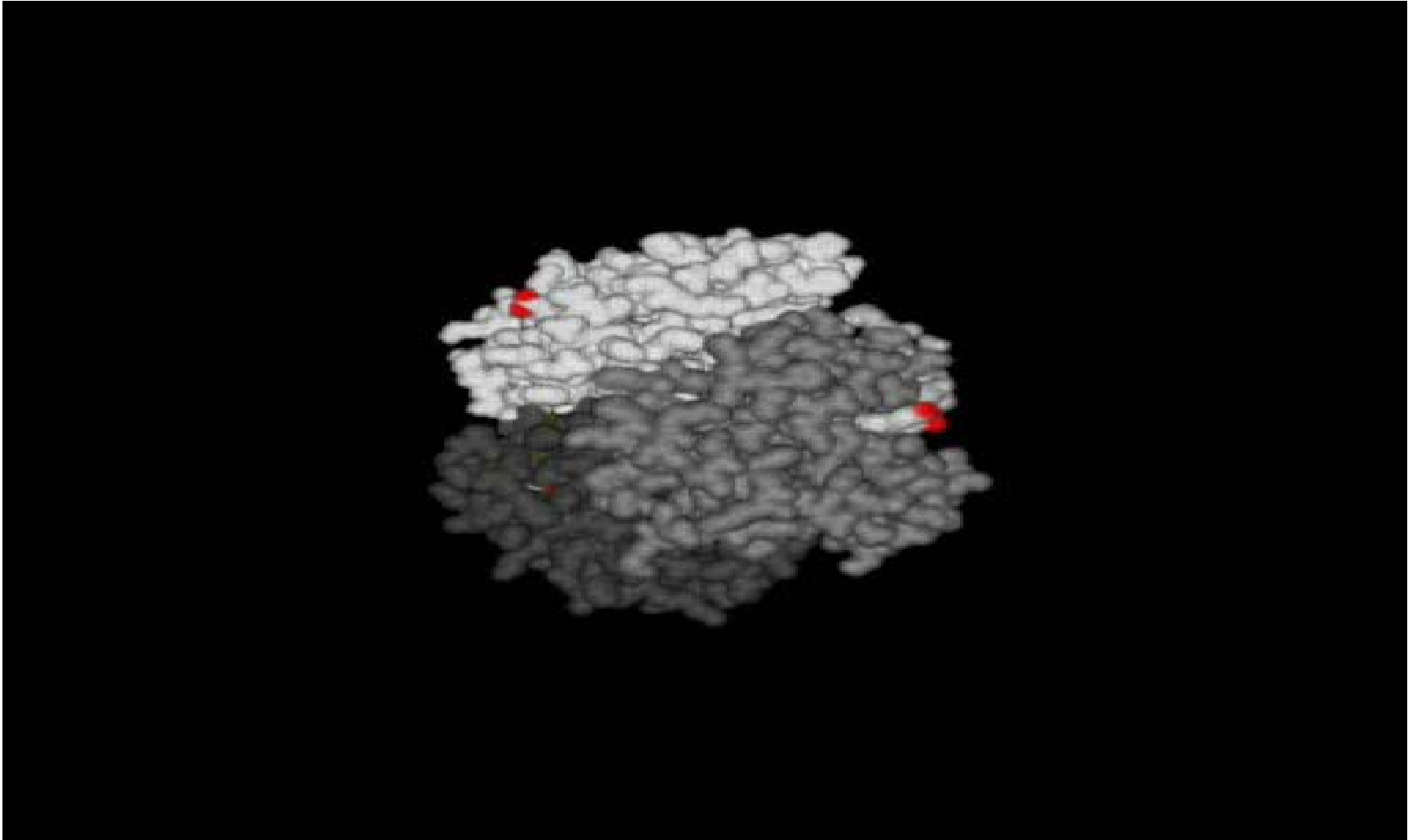
University of Texas at Austin

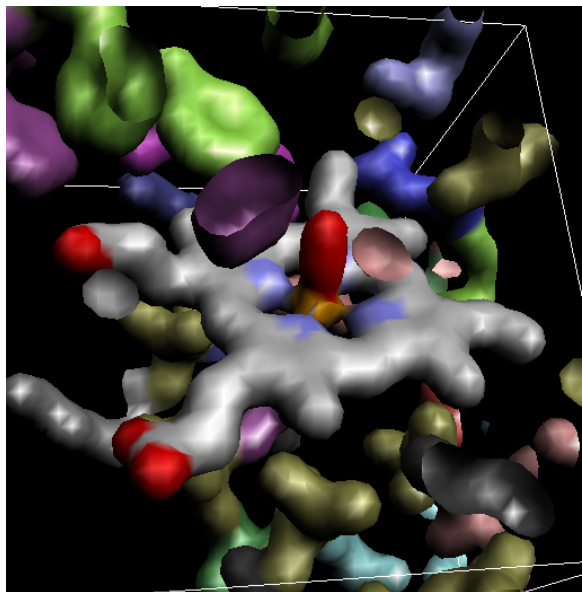
Oct 2003



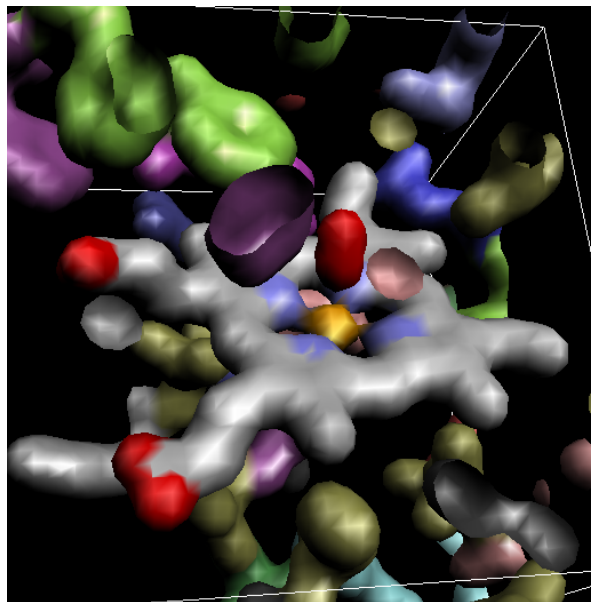
Quantitative Visualization of Hemoglobin Dynamics

Interrogative Volumetric Video (VolVis2002)

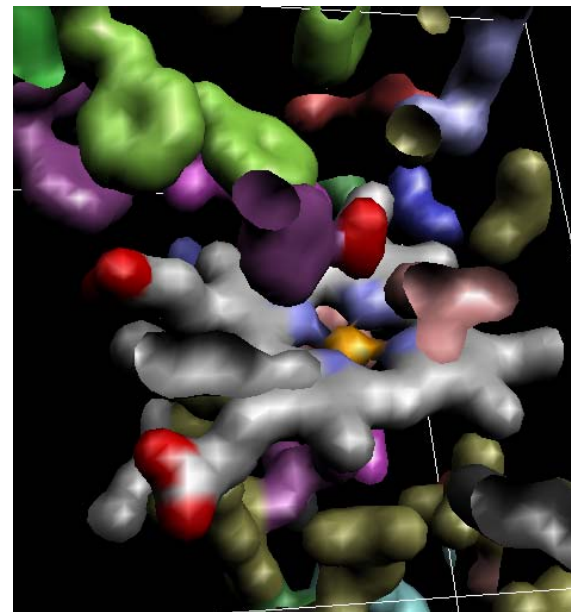




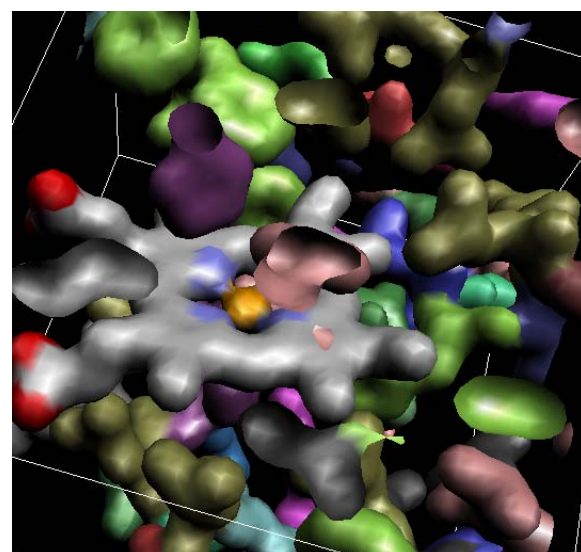
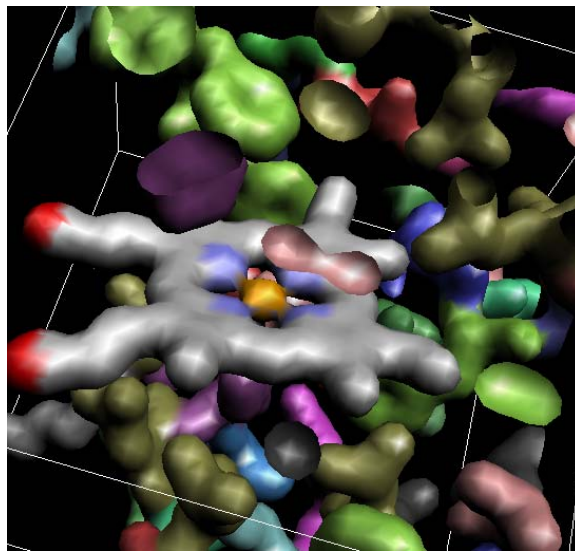
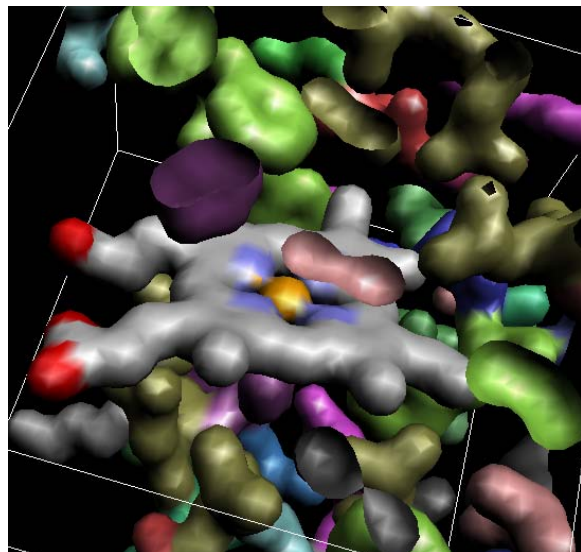
Time 1



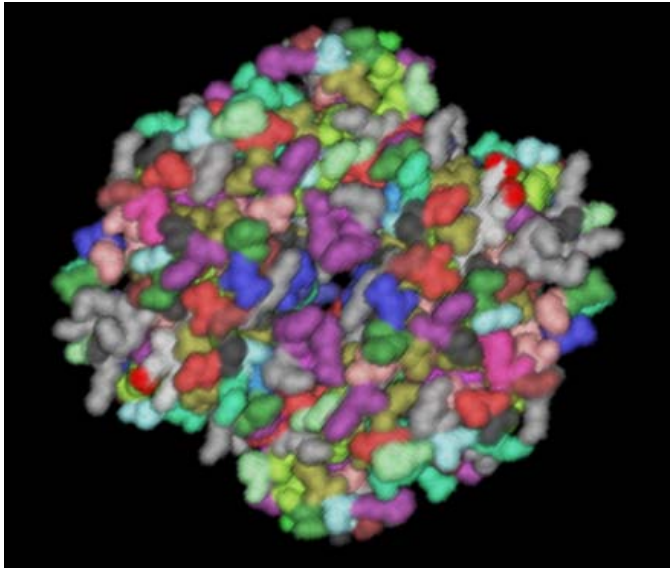
Time 15



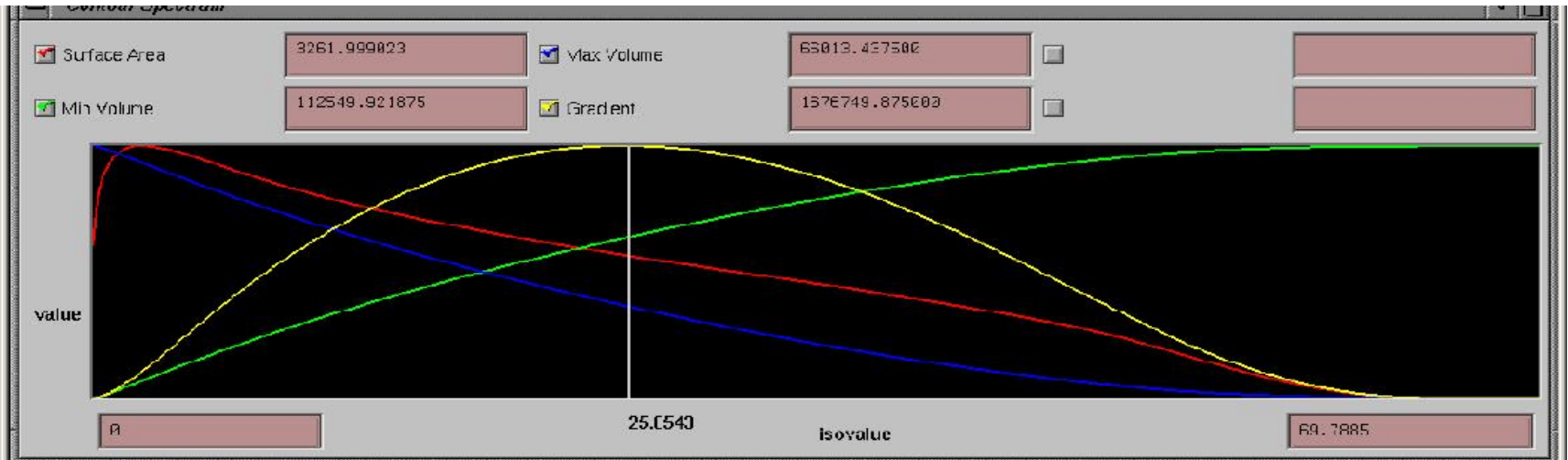
Time 30



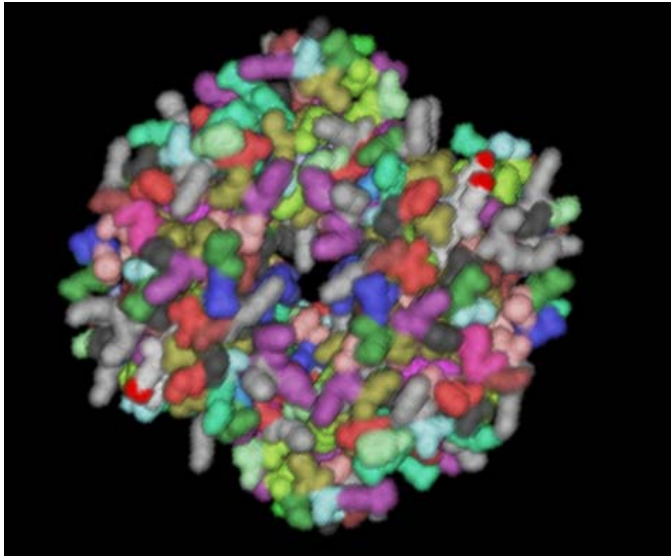
Static Contour Spectrum



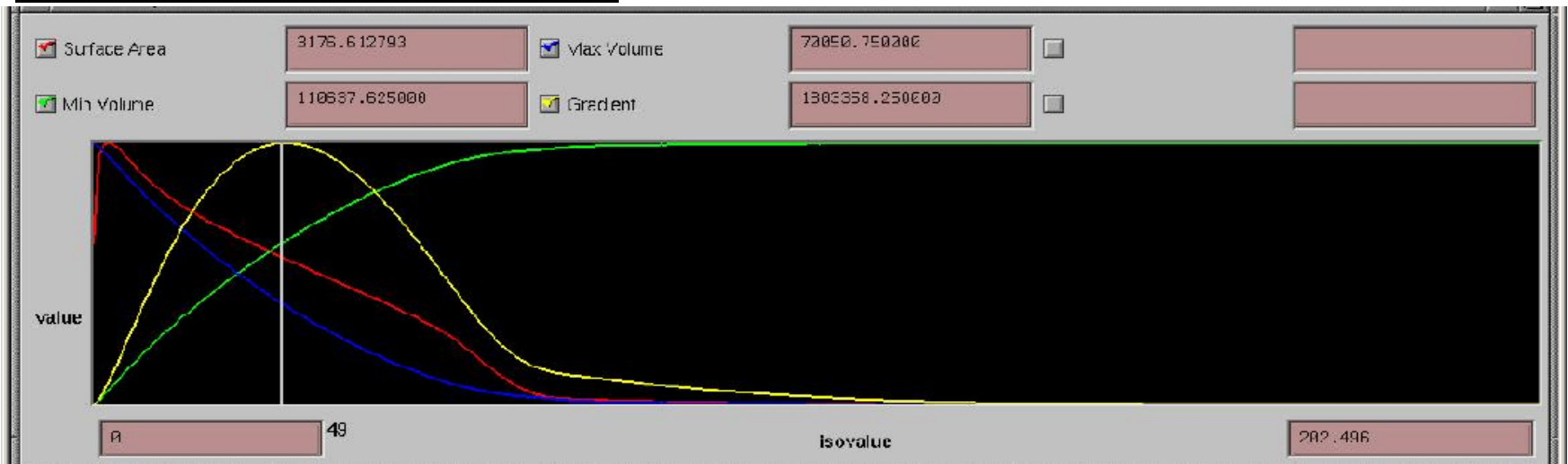
Time = 1



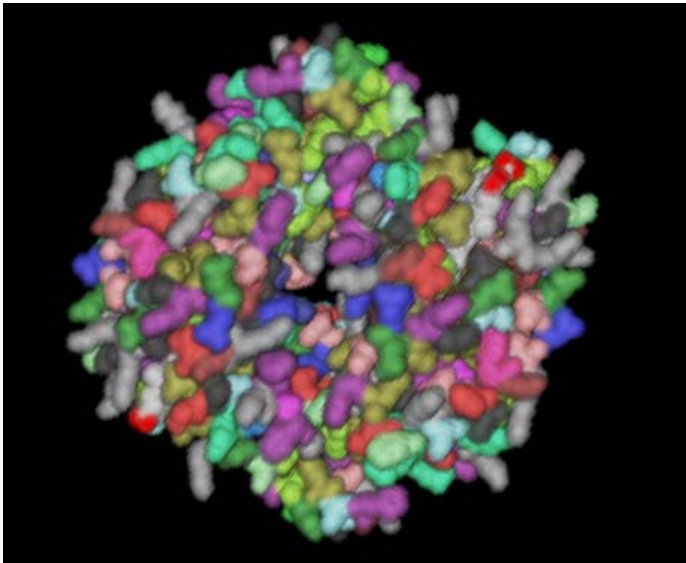
Static Contour Spectrum



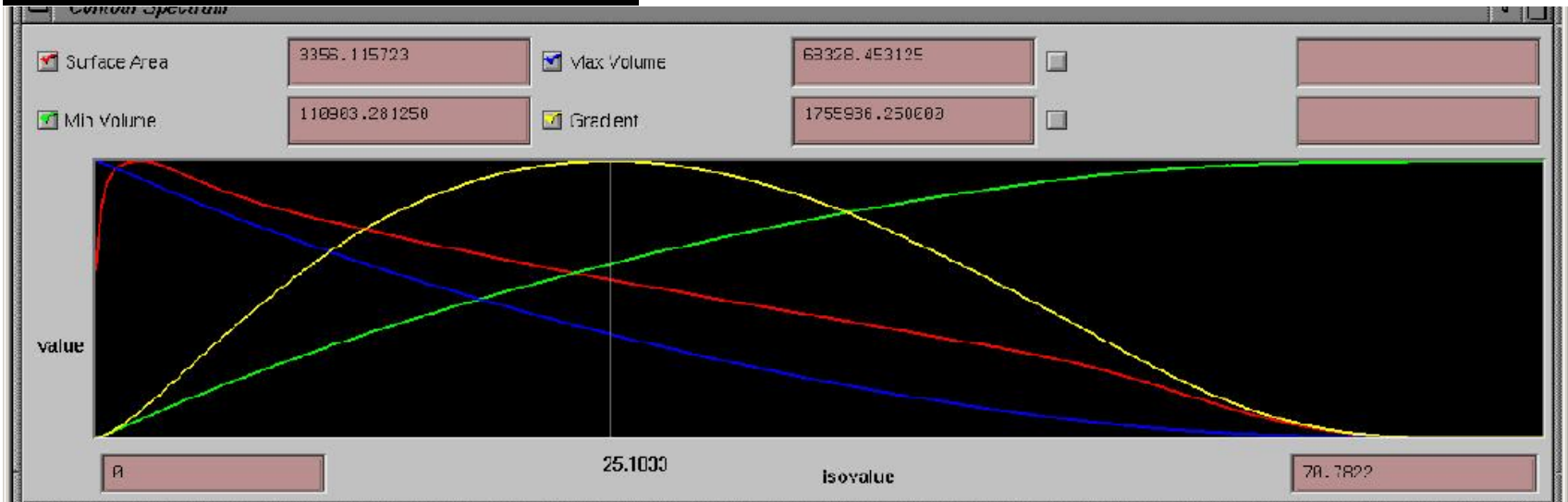
Time = 15



Static Contour Spectrum

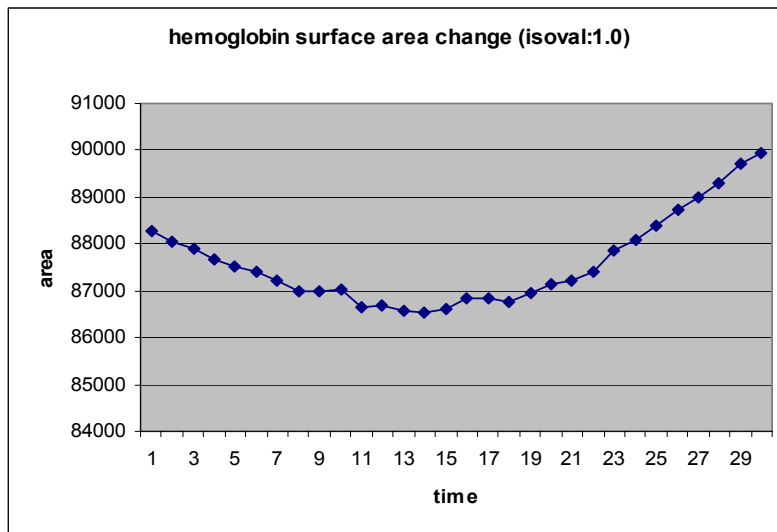


Time = 30

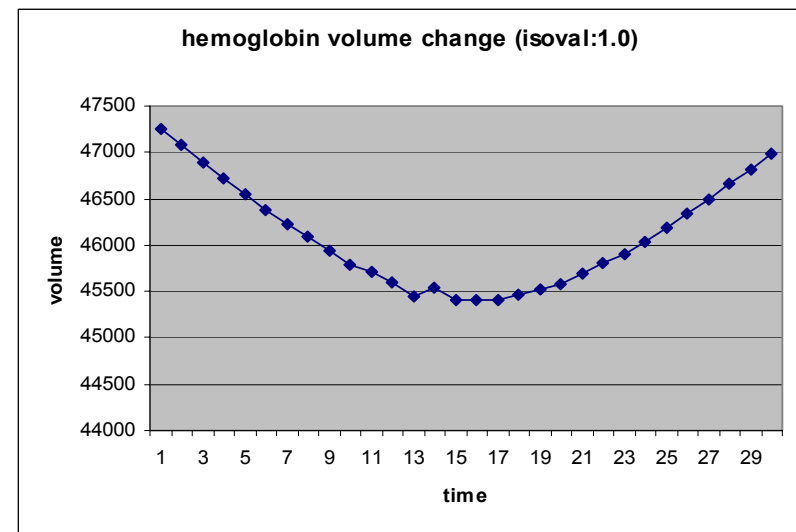


Time-Varying Contour Spectrum

Hemoglobin Surface Area/Volume Change over Time



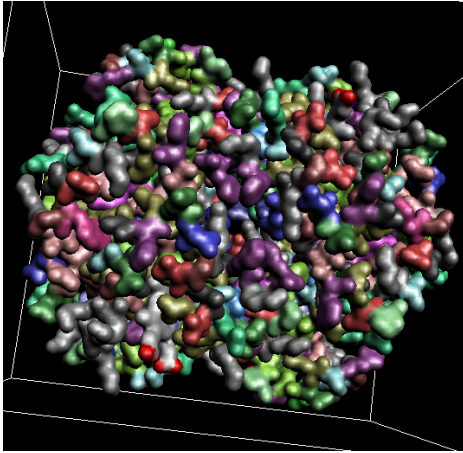
Surface Area



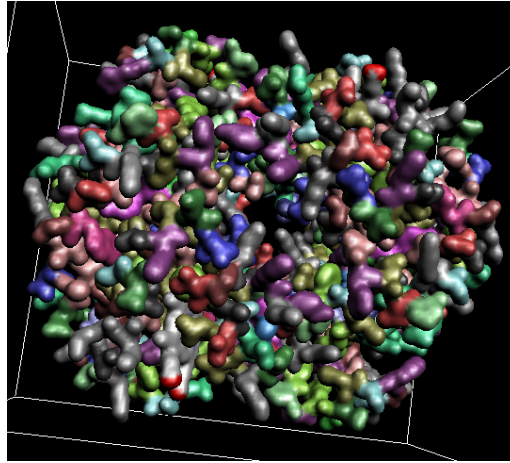
Volume



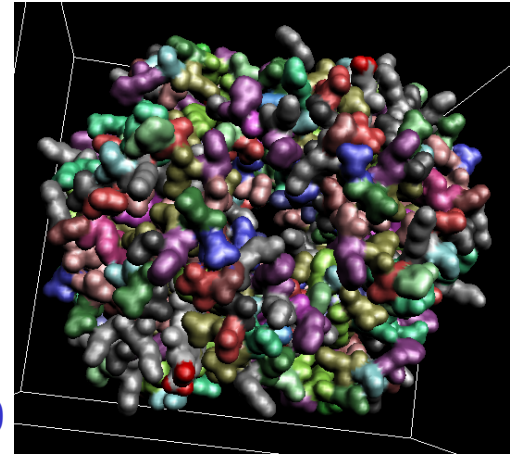
Surface Area



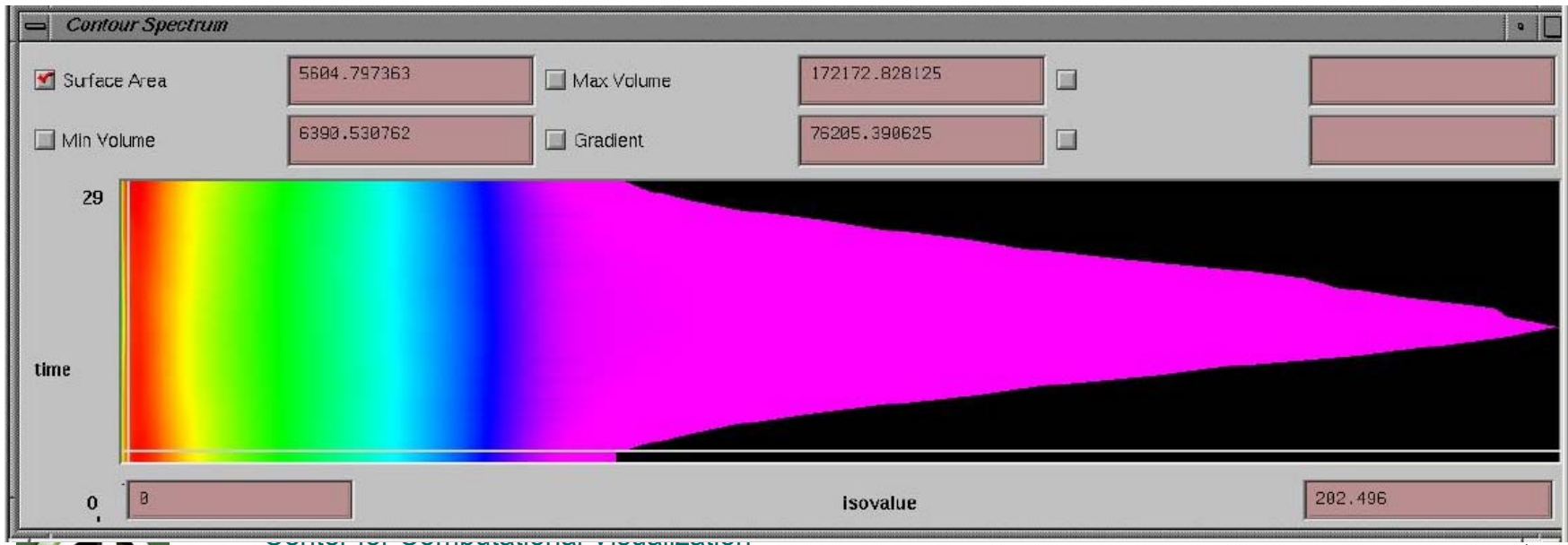
$t=1$
time



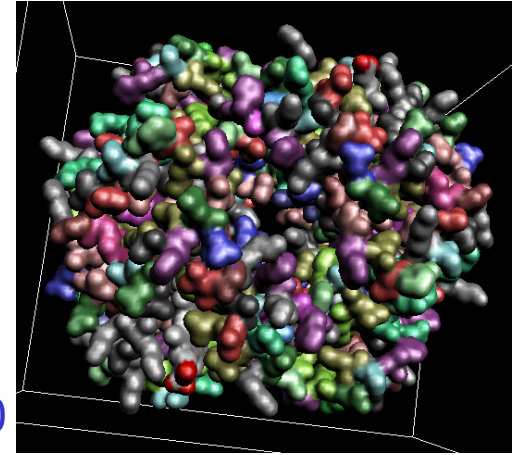
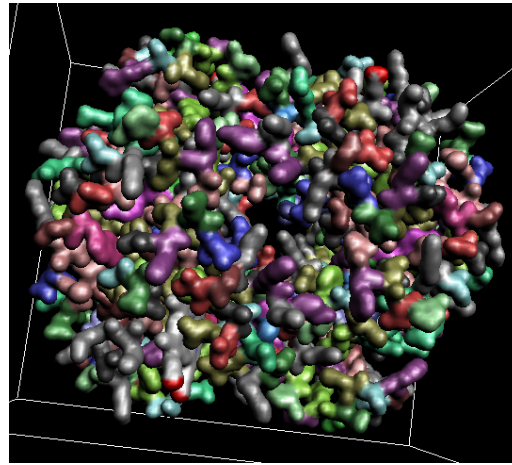
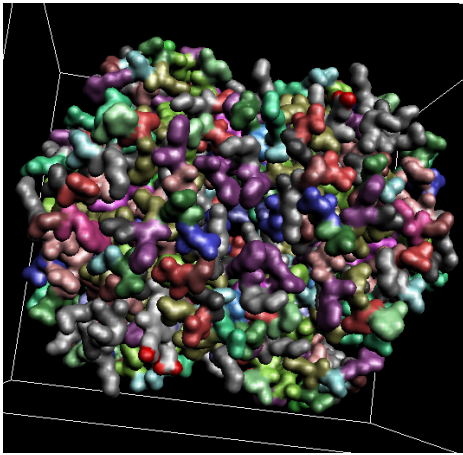
$t=15$



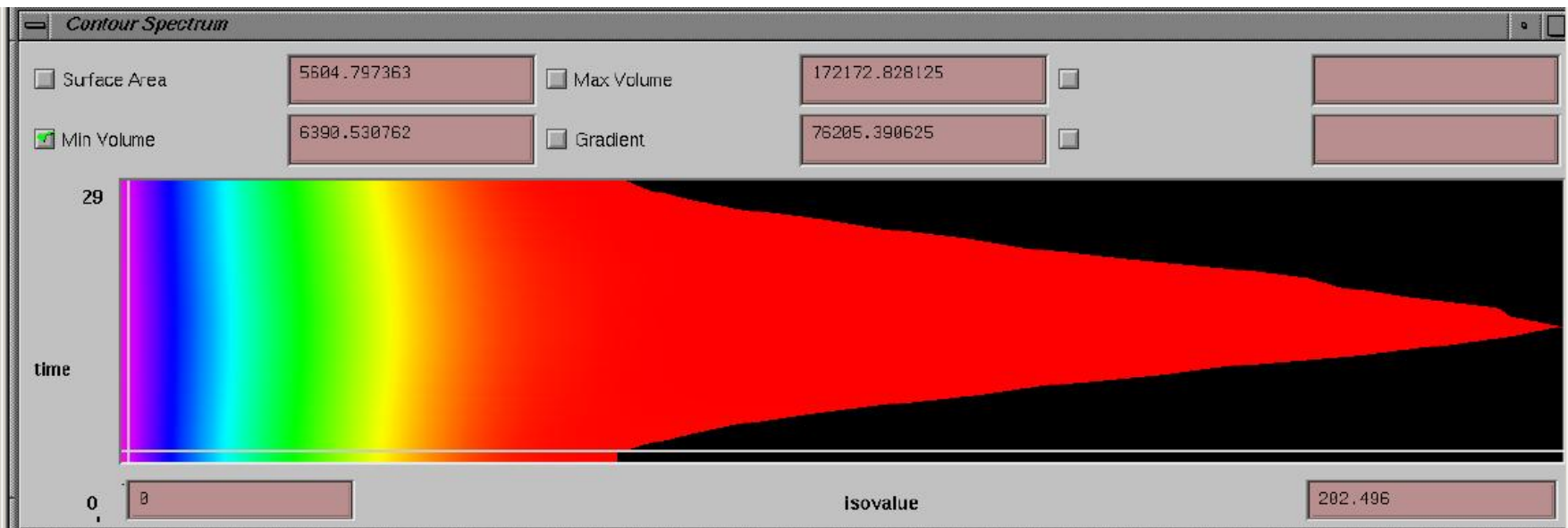
$t=30$



Volume



t=1
time



Center for Computational Visualization

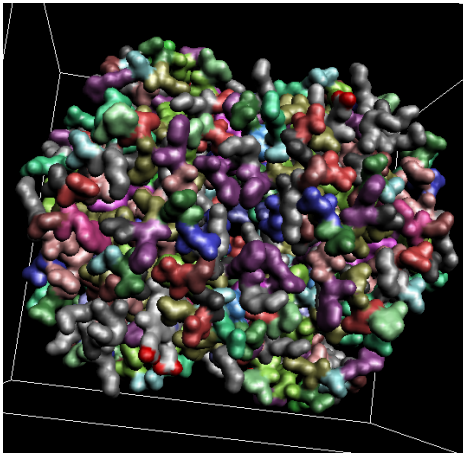
Institute of Computational and Engineering Sciences
Department of Computer Sciences

Isovalue 17.44 is selected for isosurface rendering

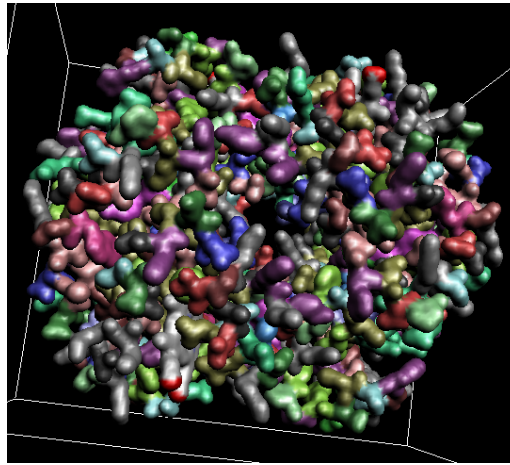
University of Texas at Austin

Oct 2003

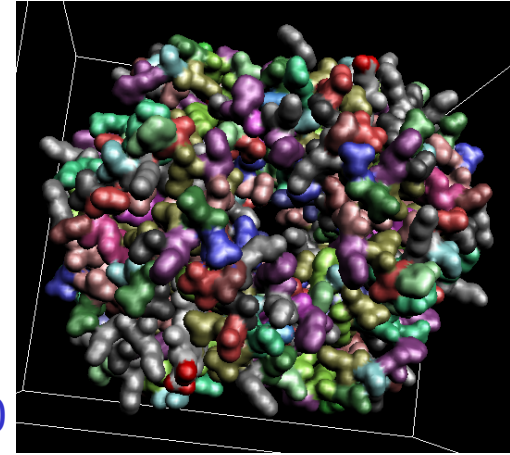
Gradient Magnitude



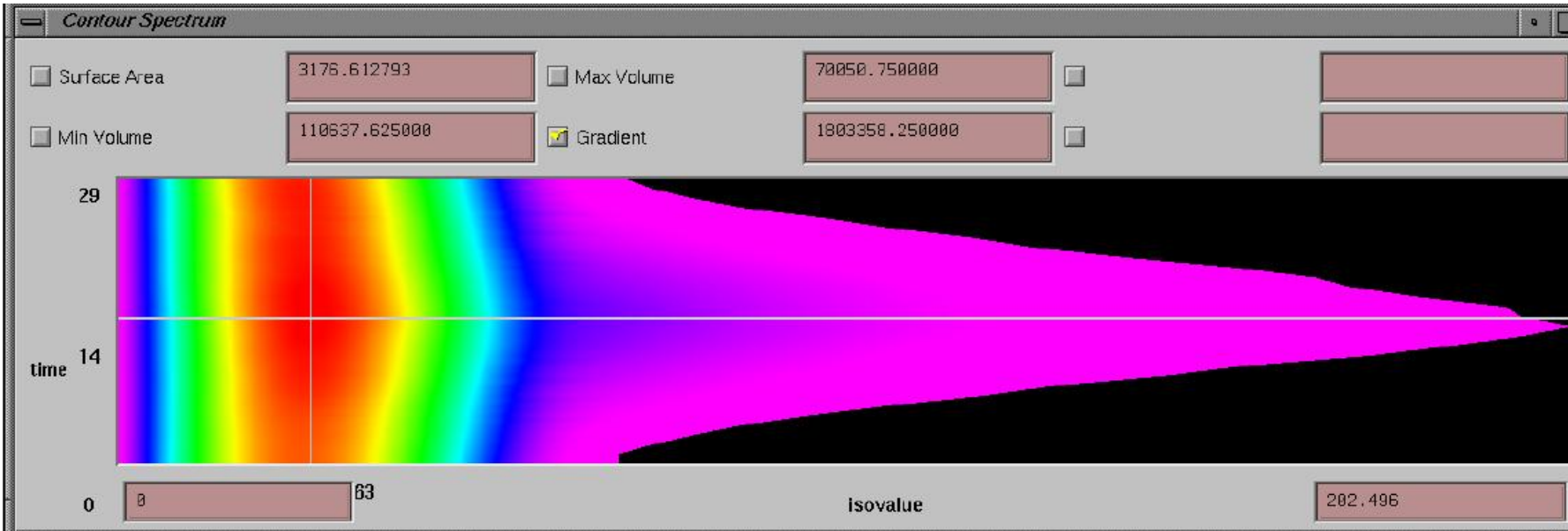
t=1
time



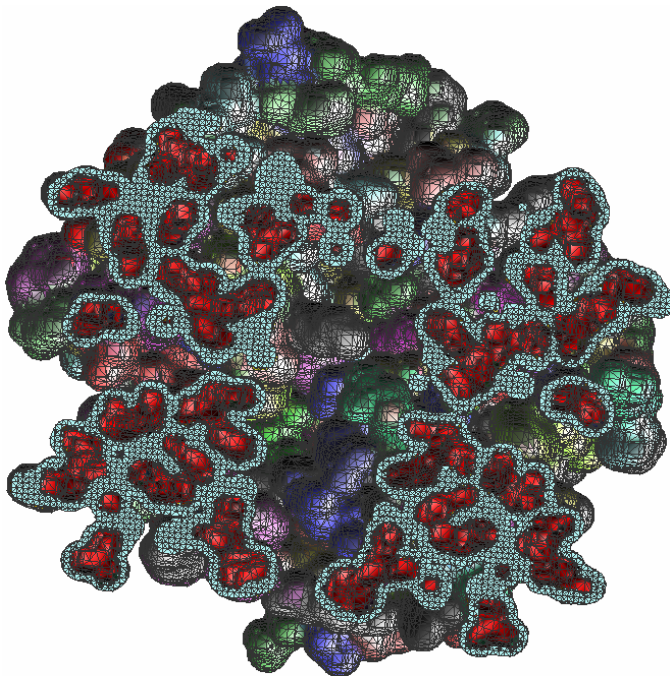
t=15



t=30

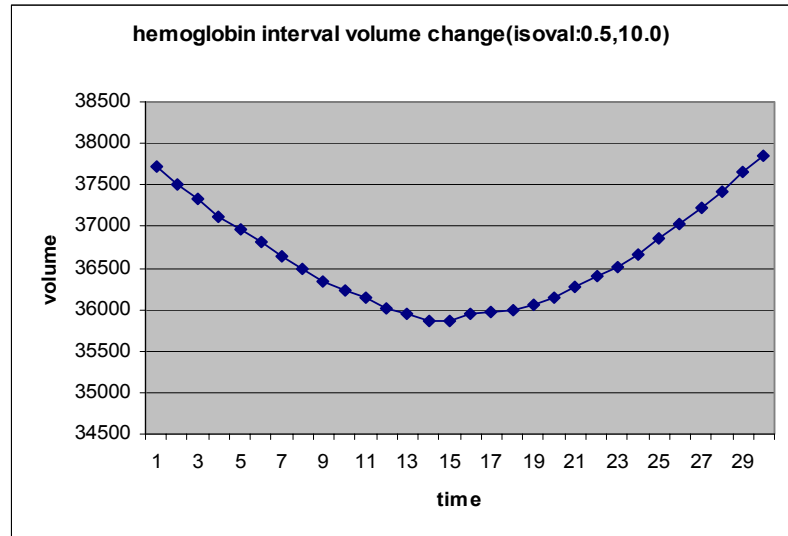


Time-Varying Contour Spectrum



Interval Volume Crosssection

Interval Volume Change over Time

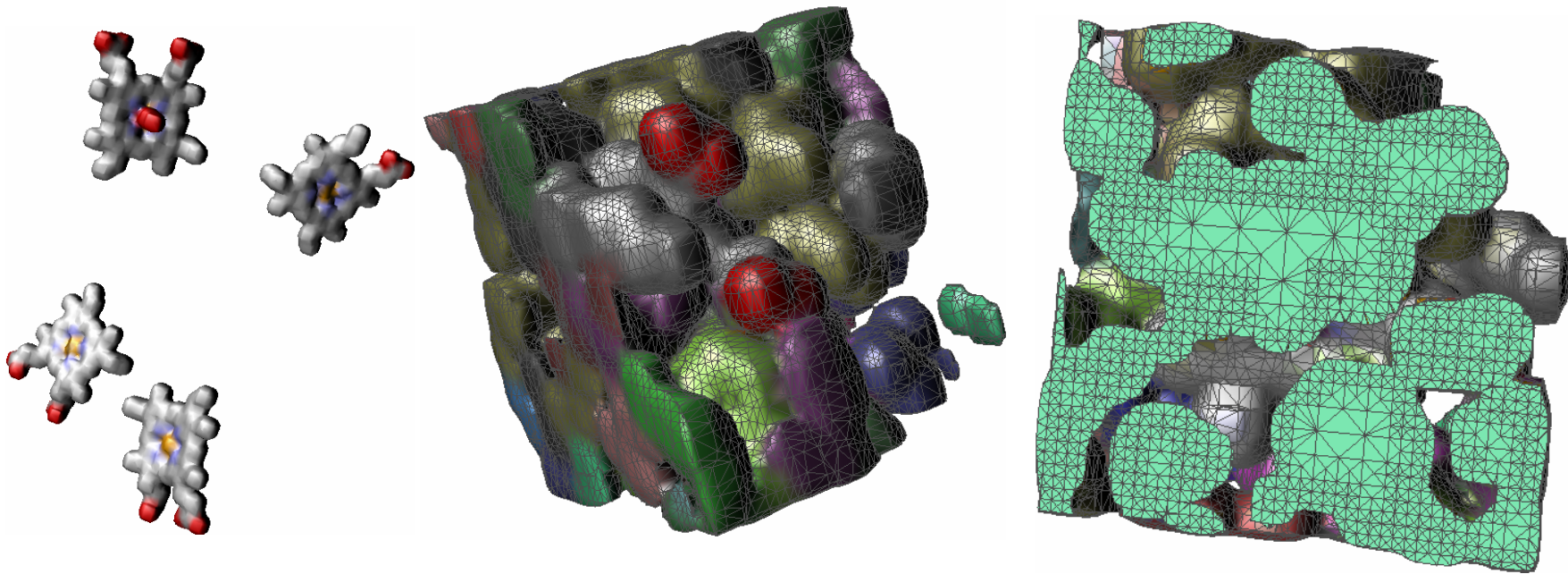


Isovalue 0.5(outer surface) and 10.0(inner surface)



Time-Varying Contour Spectrum

- Quantification around Heme Structure

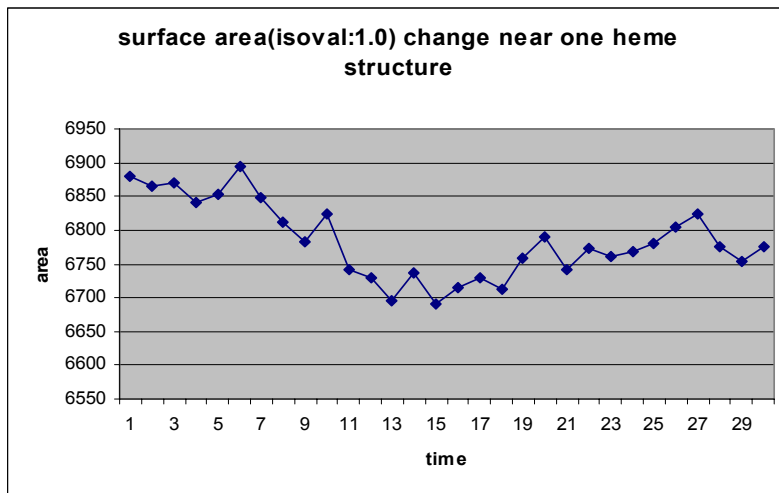


Isovalue 0.5

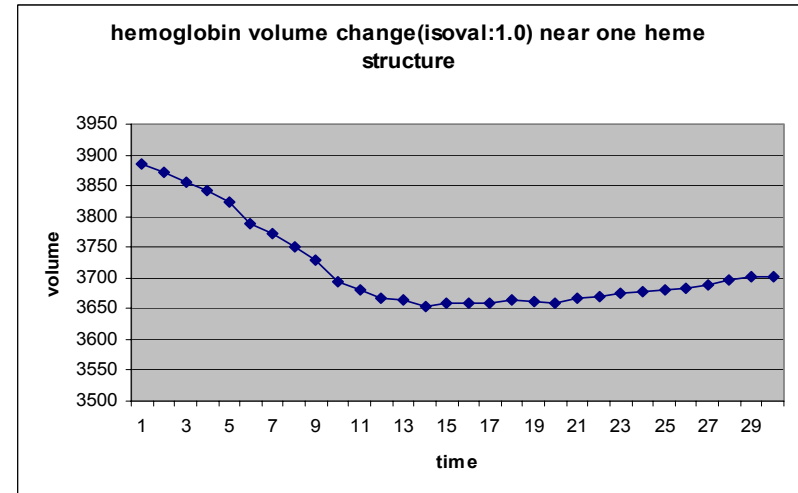


Time-Varying Contour Spectrum

- Quantification around Heme Structure



Surface Area



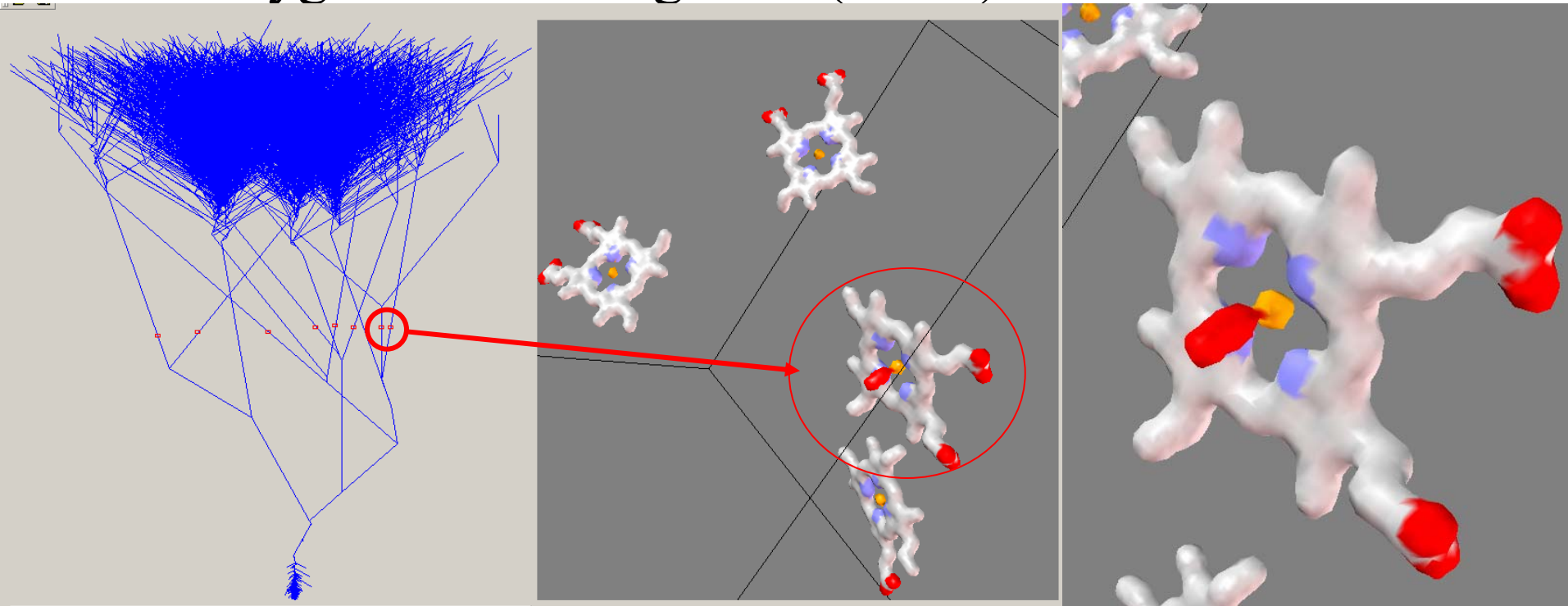
Volume

Isovalue is 1.0



Analysis using the TIME CONTOUR TREE

- Oxygenated Hemoglobin (T=1)

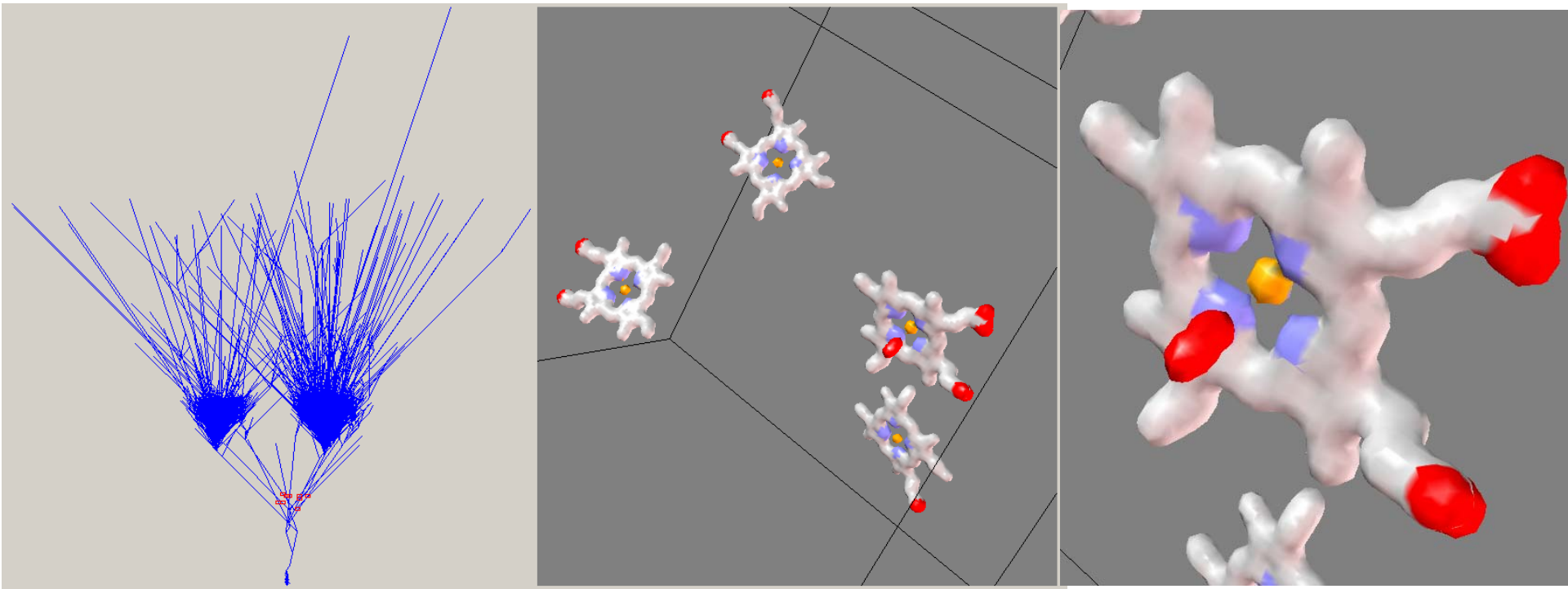


<isovalue = 31>



Analysis using the TIME CONTOUR TREE

- Intermediate step ($T=15$)

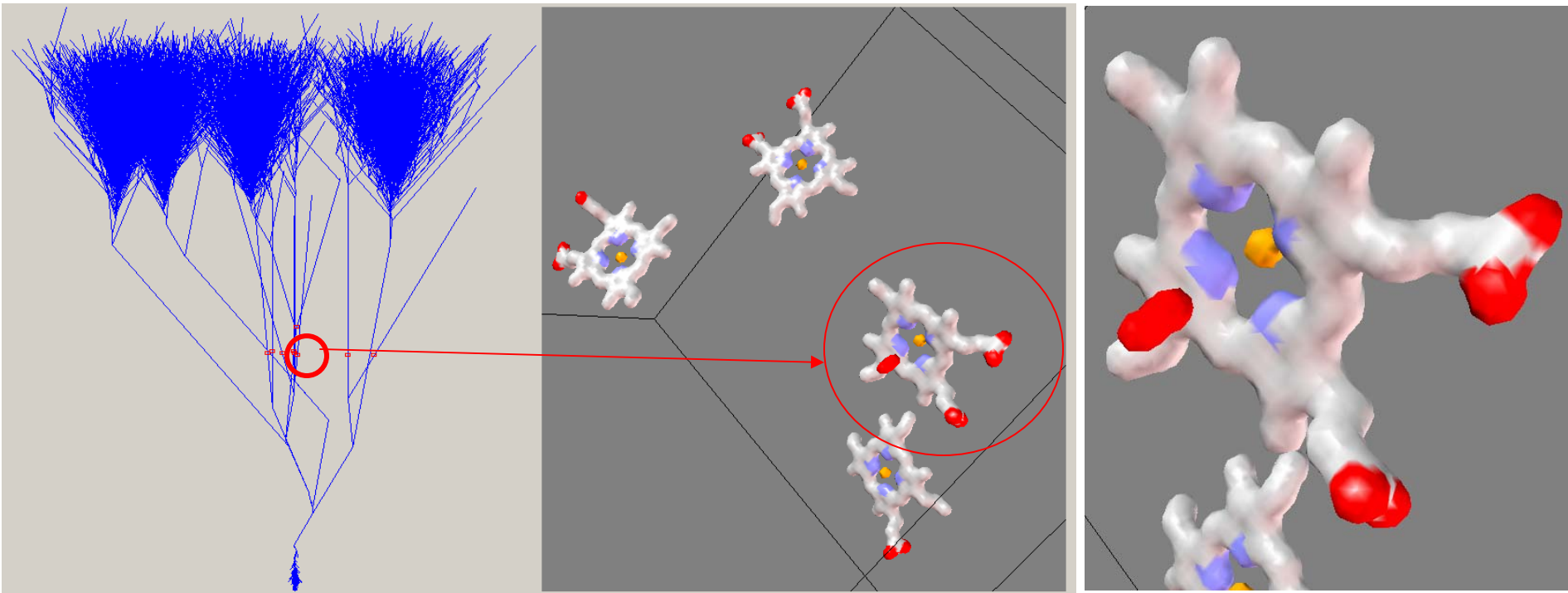


<isovalue = 31>



Analysis using the TIME CONTOUR TREE

- Deoxygenated Hemoglobin (T=30)

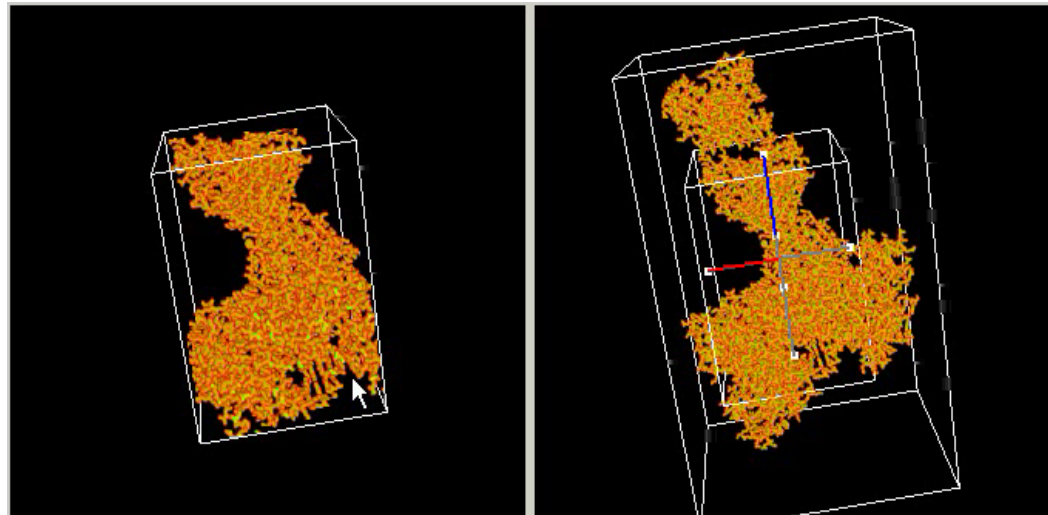
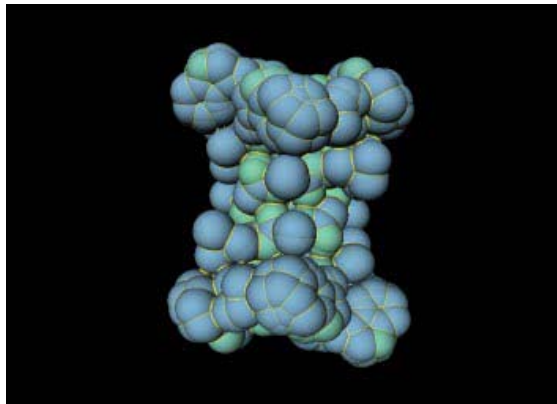
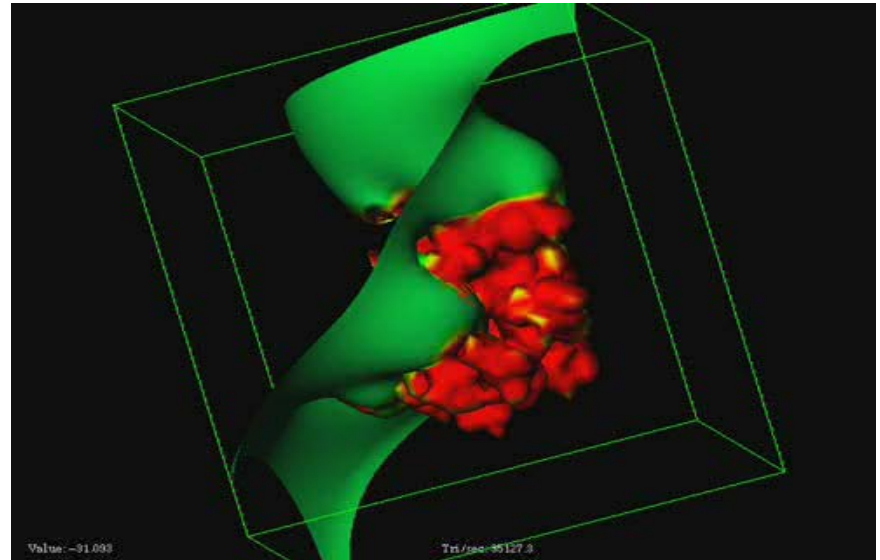


<isovalue = 31>



Modeling, Analysis and Visualization Software (<http://www.ices.utexas.edu/CCV/software/>)

- Desktop and Parallel Tools
 - Isocontouring and volume rendering software on COTS
 - Multi-Display Clients using programmable graphics hardware
 - Integration with the Grid Underway for Remote Visualization Services



whats in the Future ?

- Computational Modeling for Nano-Machines and Nano-Medicine
 - Psuedo-atomic model generation for bio-molecular machines, and their assemblage *properties*
 - Mechanisms for capturing knowledge of macromolecular *flexibility* and inferring *functionality*
 - Understanding *interactions* between molecular assemblies, biological and synthetic through biochemistry/biophysics simulations



Acknowledgements

- **CCV**

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- **Greg Johnson**
- **Zaiqing Xu**
- **KL Chandrasekhar**
- **Qiu Wu**
- **Jasun Sun**
- **Anthony Thane**
- **Shashank Khandelwal**

- **Computational resources**

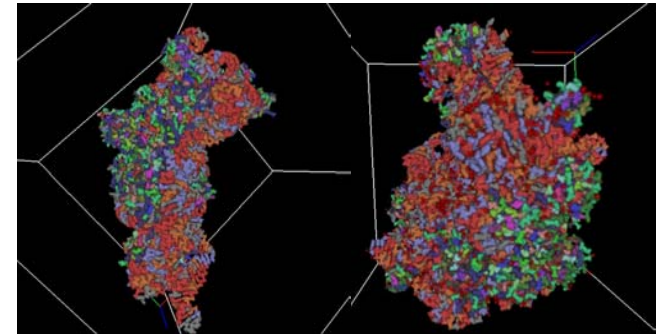
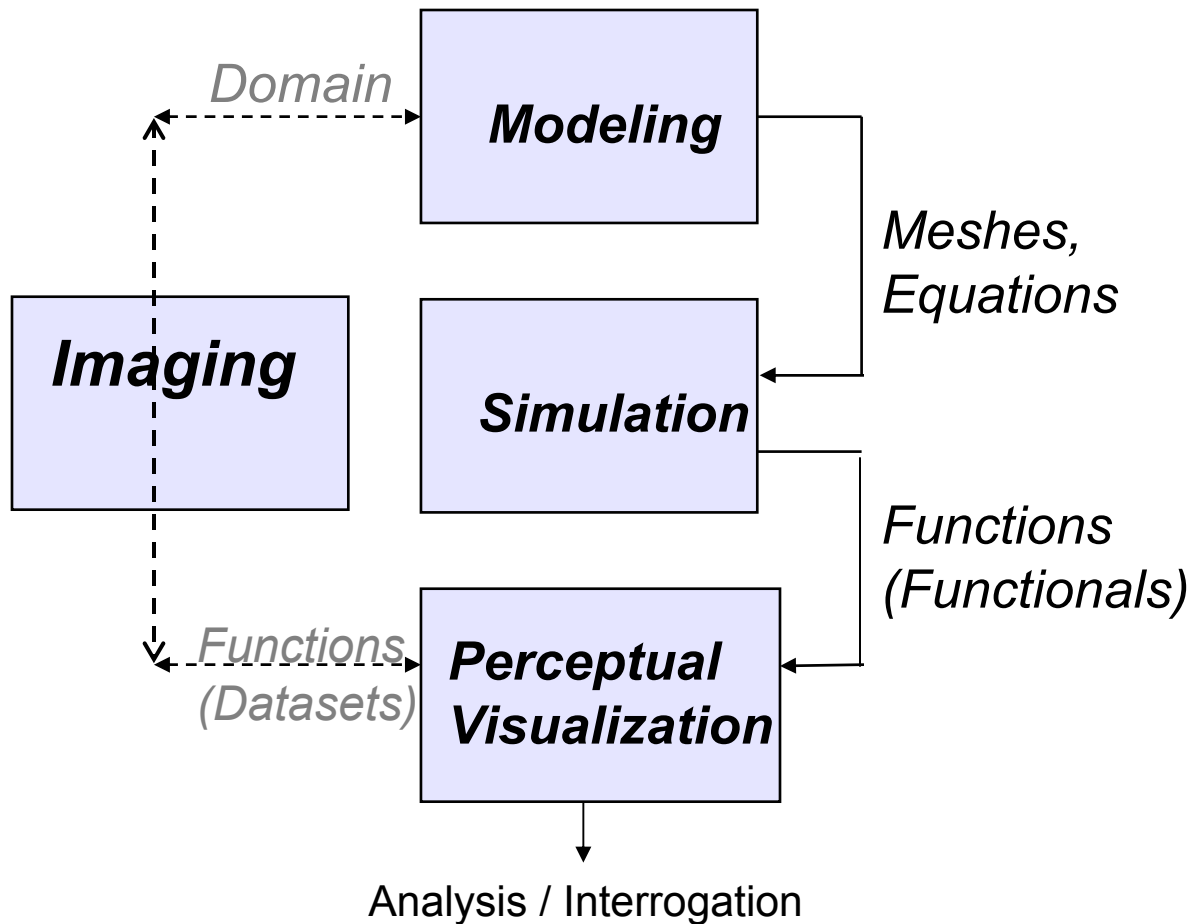
- **CCV/ICES/UT**
- **NPACI/SDSC**

- **Sponsors**

- **NSF**
- **UT/MDACC/Whitaker**
- **NPACI/NSF**
- **DOE-LLNL/Sandia**



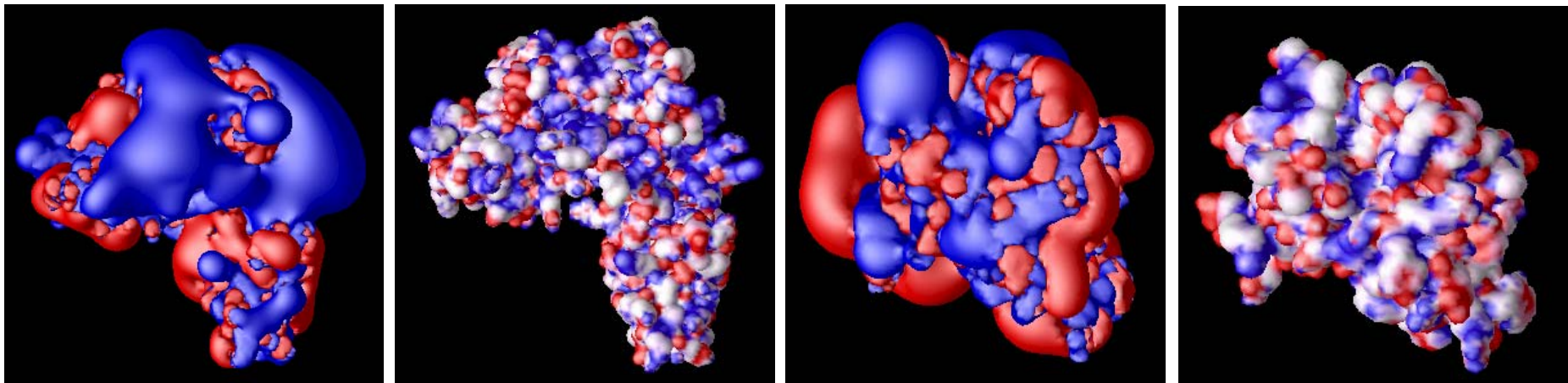
Computational visualization



- To identify and perceive *information* for model calibration or scientific discovery
- Model *Analysis, Visualization* and *interrogation* with maximum *fidelity*



Molecular Electrostatics visualization



Blue *positive*

White *neutral*

Red *negative*

Isosurfaces of Electrostatics potential, and rendered as a Function on an Isosurface of Electron Density



Surface curvatures

The two main surface curvatures in differential geometry are the *Mean Curvature* H and the *Gaussian curvature* K .

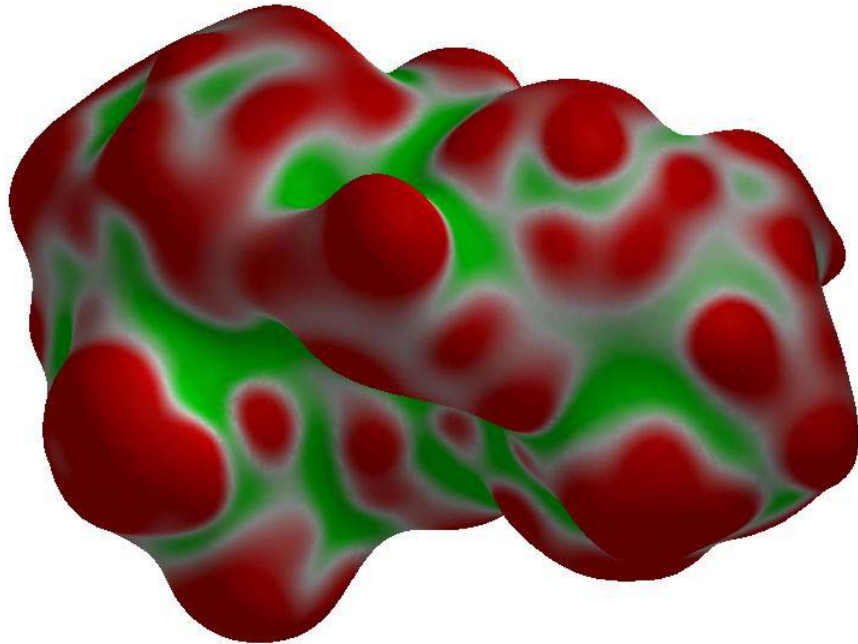
Let k_{\min} and k_{\max} be the minimum and maximum curvatures at a point. Then,

$$H = \frac{1}{2}(k_{\min} + k_{\max}) \quad \text{and}$$

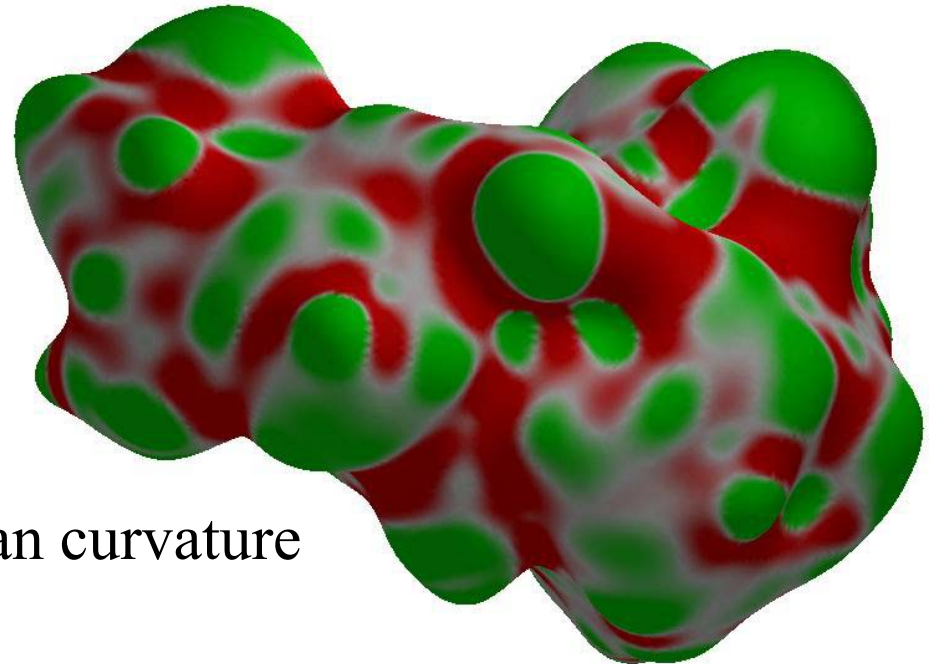
$$K = k_{\min} k_{\max}$$



Protein Kinase from Rat (1a06)



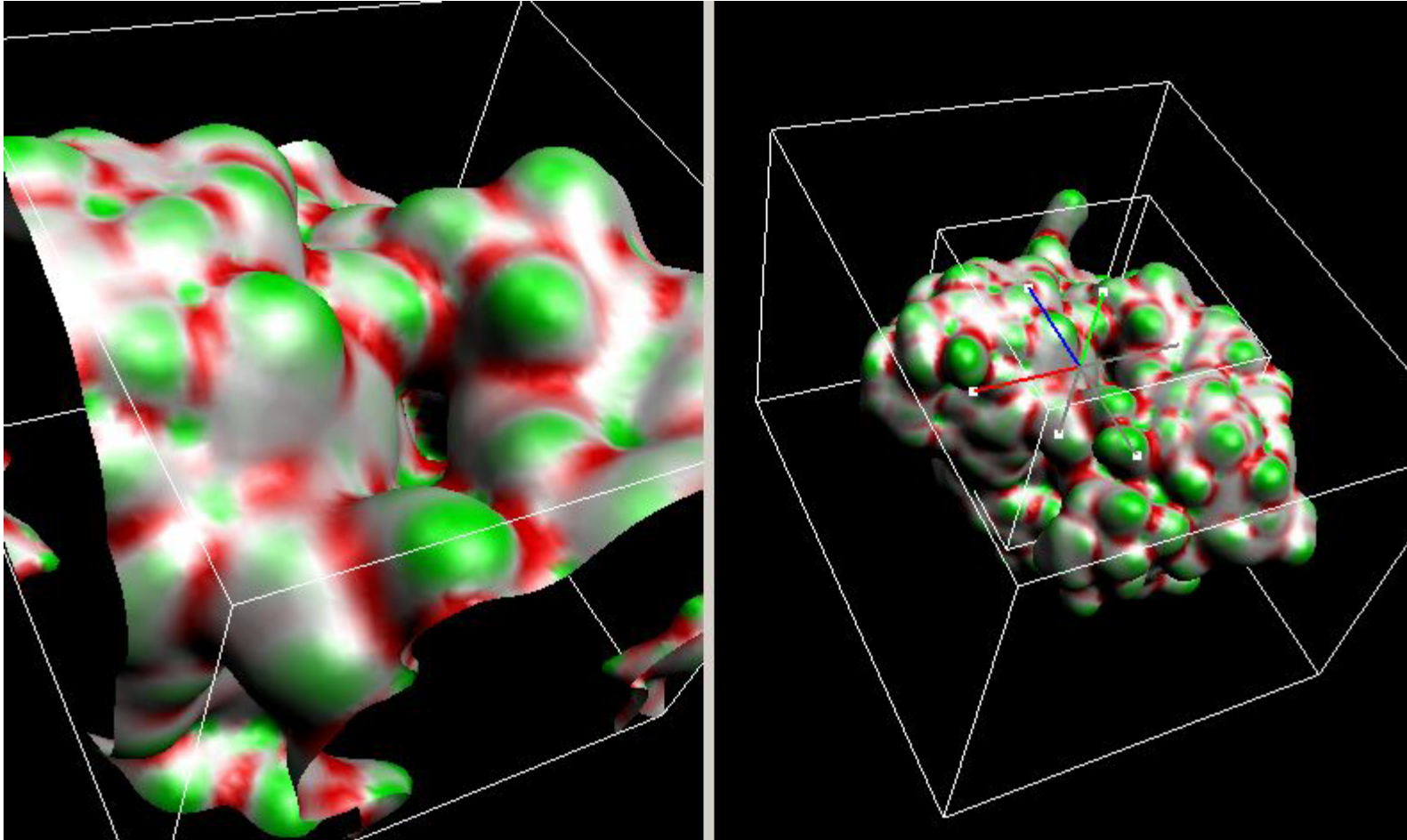
Mean curvature



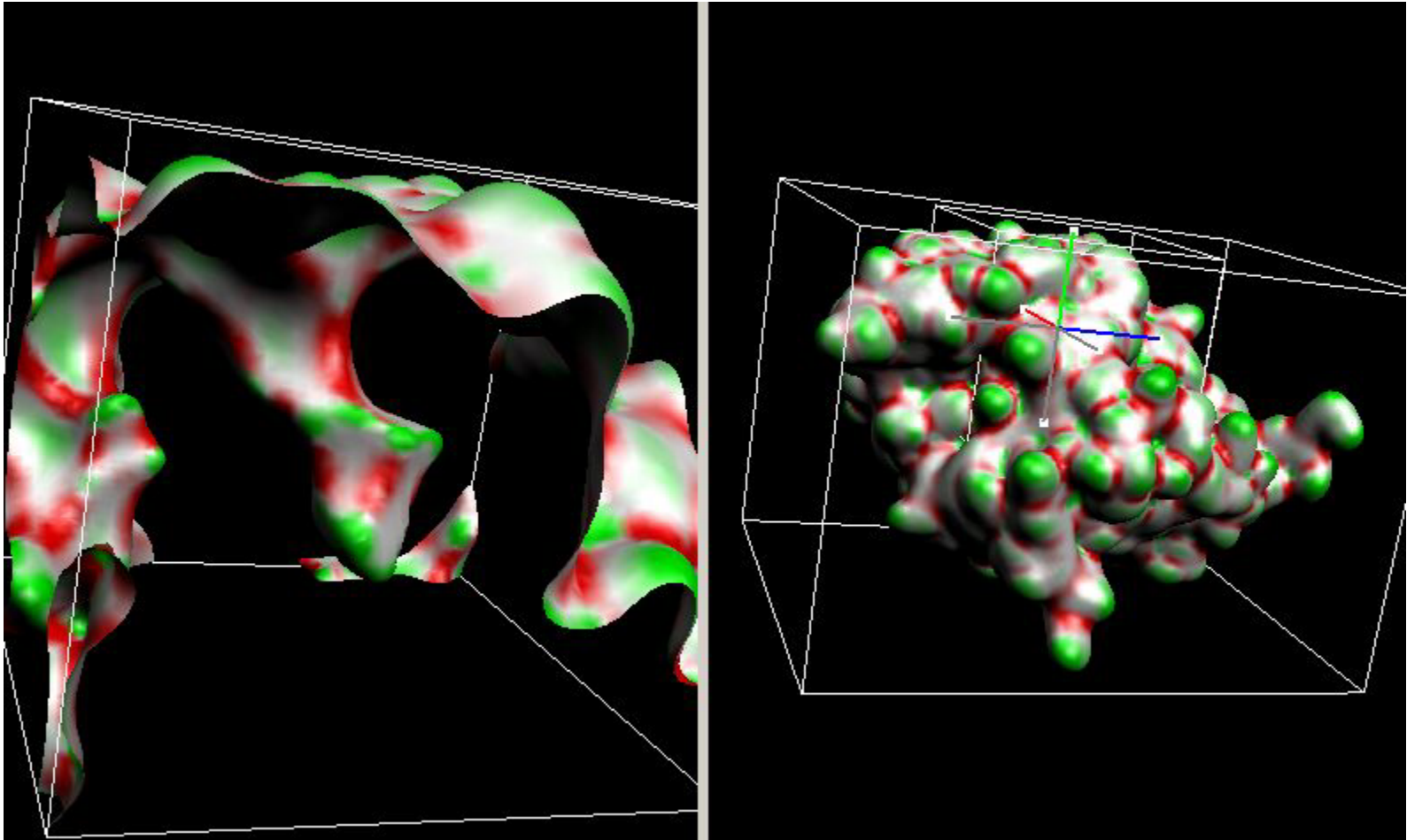
Gaussian curvature



Gaussian curvatures on Mouse AcetylCholinesterase



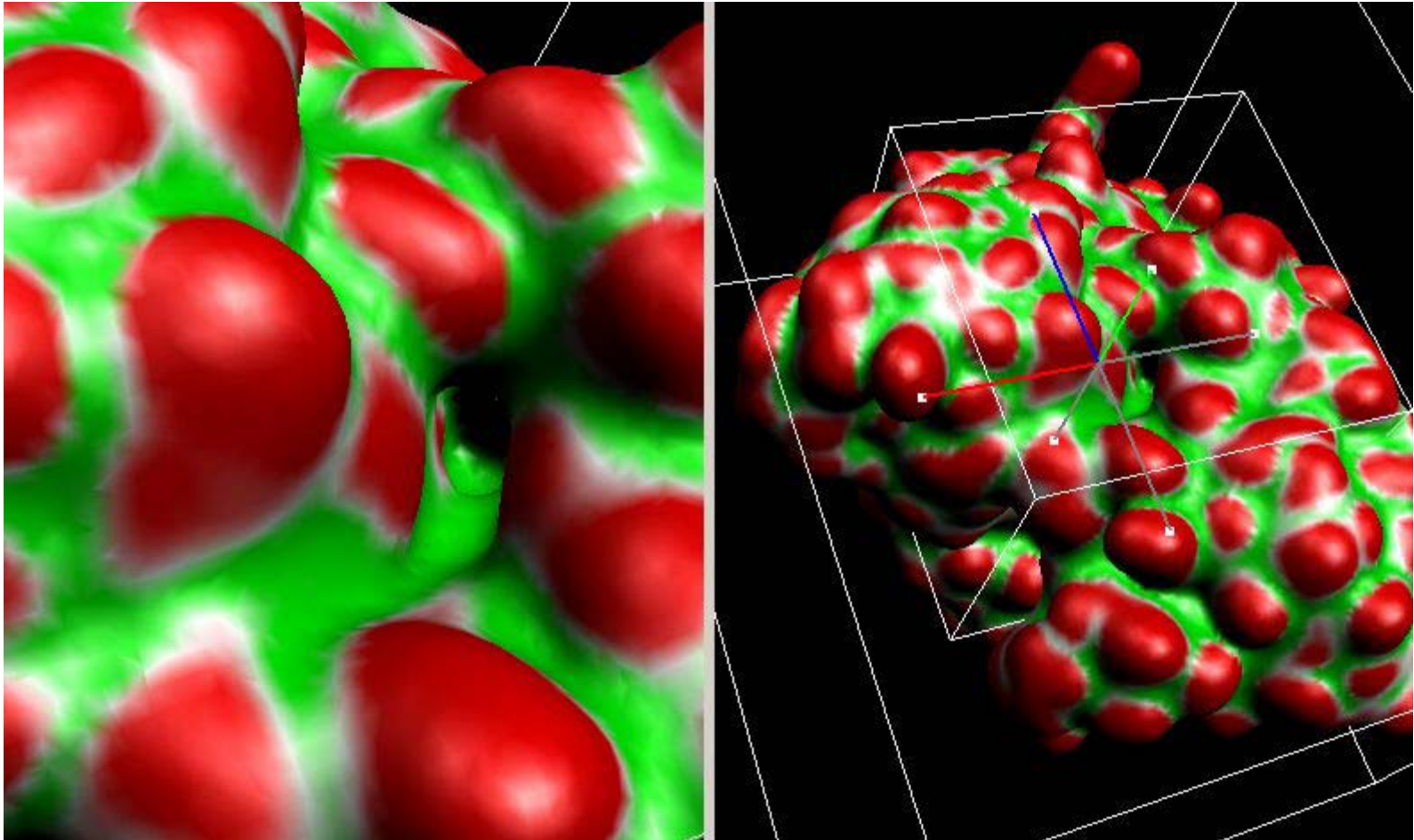
Mouse AcetylCholinesterase



Gaussian curvatures



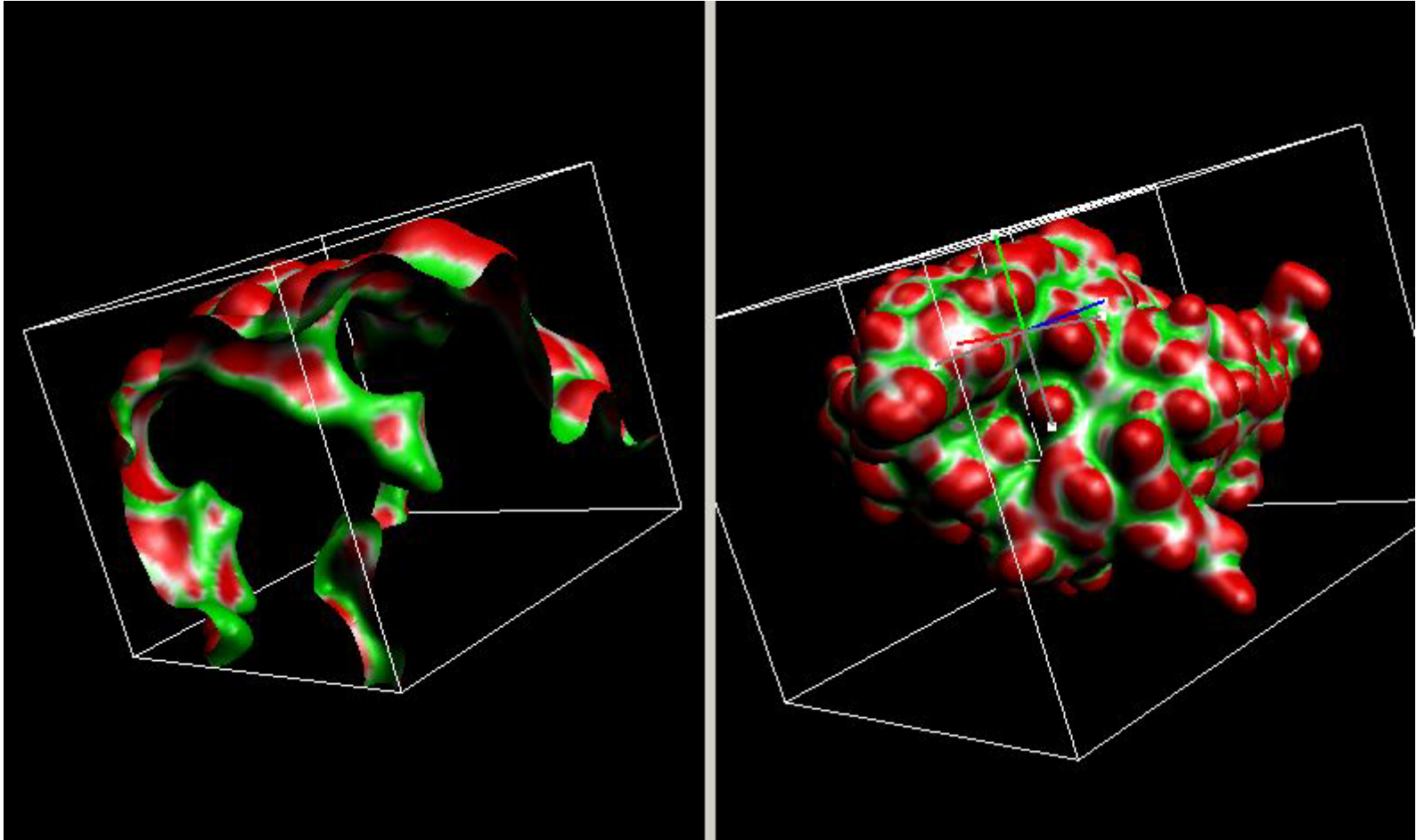
Mouse AcetylCholinesterase



Mean curvatures



Mouse AcetylCholinesterase



Mean curvatures

