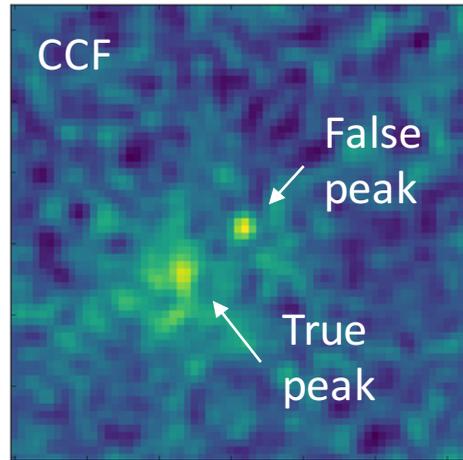
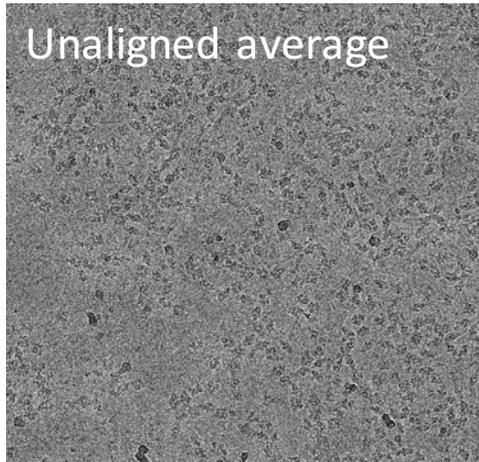
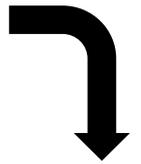
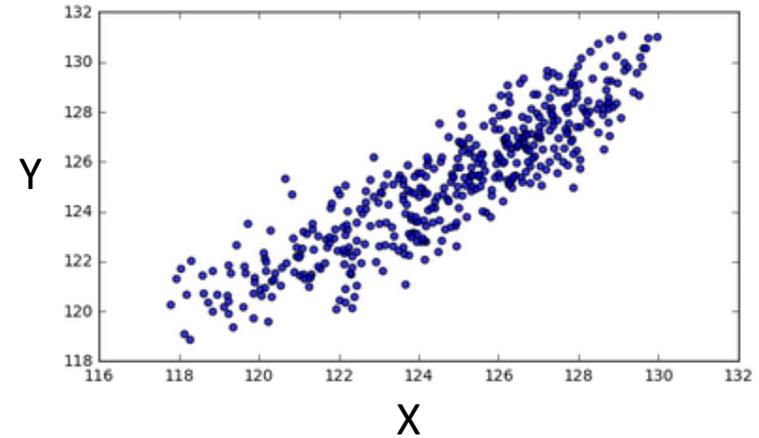


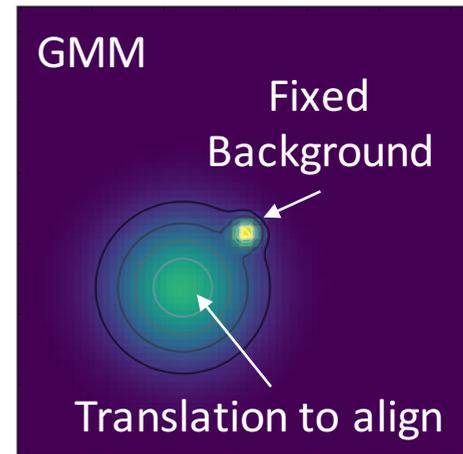
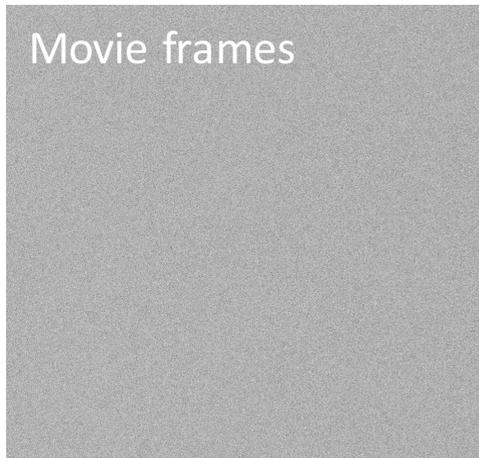
Mixture of Gaussians alignment algorithm



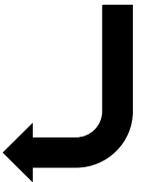
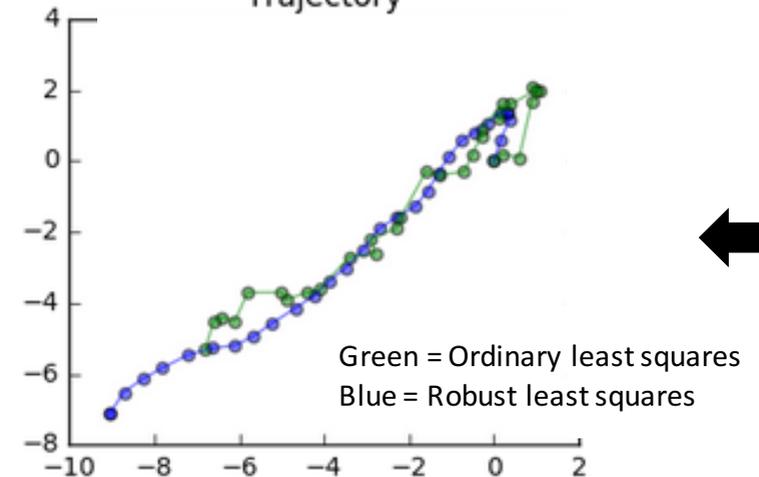
Pairwise CCF model peak coordinates



Least squares



Trajectory



Very little signal per frame